

# Sampling 2D signals

# Impulse Train

$$\text{comb}_{M,N}[m,n] \triangleq \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta[m - kM, n - lN]$$

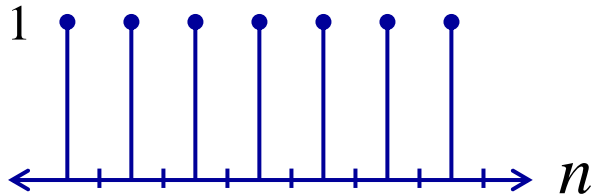
$$\text{comb}_{M,N}(x,y) \triangleq \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta(x - kM, y - lN)$$

- Fourier Transform of an impulse train is also an impulse train:

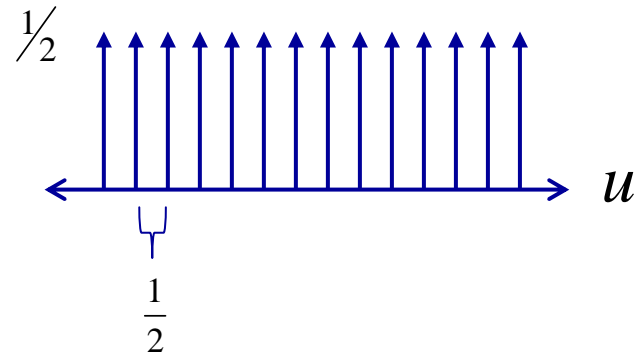
$$\underbrace{\sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta[m - kM, n - lN]}_{\text{comb}_{M,N}[m,n]} \Leftrightarrow \frac{1}{MN} \underbrace{\sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(u - \frac{k}{M}, v - \frac{l}{N}\right)}_{\text{comb}_{\frac{1}{M}, \frac{1}{N}}(u,v)}$$

# Impulse Train

$$\text{comb}_2[n]$$



$$\frac{1}{2} \text{comb}_{\frac{1}{2}}(u)$$



# Impulse Train

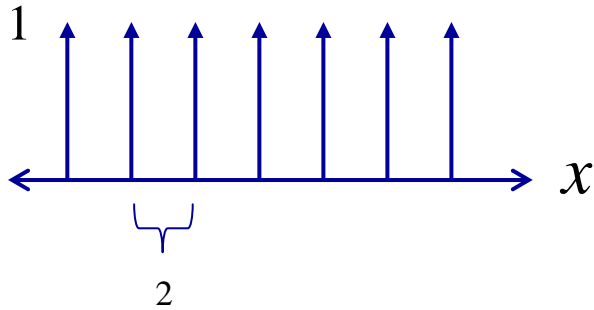
$$\text{comb}_{M,N}(x, y) \triangleq \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta(x - kM, y - lN)$$

- In the case of continuous signals:

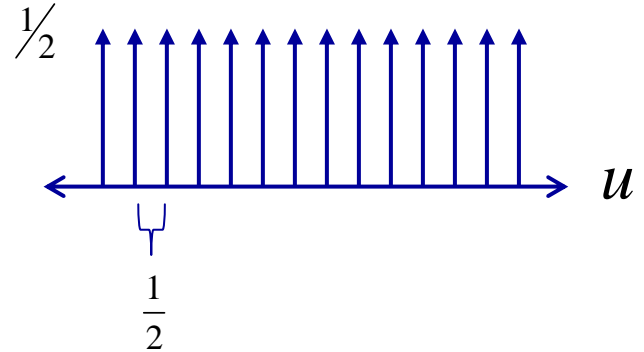
$$\underbrace{\sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta(x - kM, y - lN)}_{\text{comb}_{M,N}(x, y)} \Leftrightarrow \frac{1}{MN} \underbrace{\sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(u - \frac{k}{M}, v - \frac{l}{N}\right)}_{\text{comb}_{\frac{1}{M}, \frac{1}{N}}(u, v)}$$

# Impulse Train

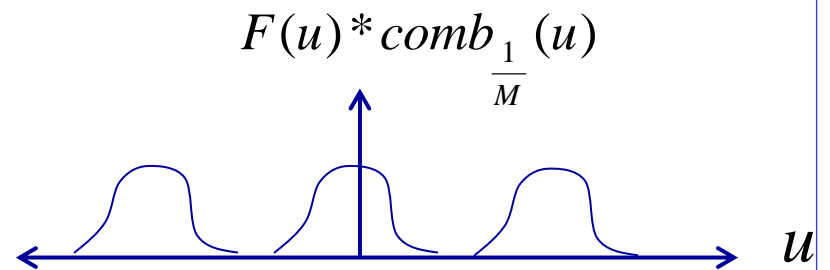
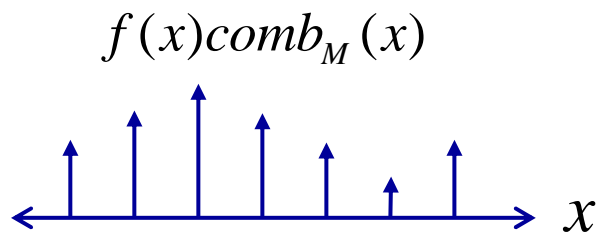
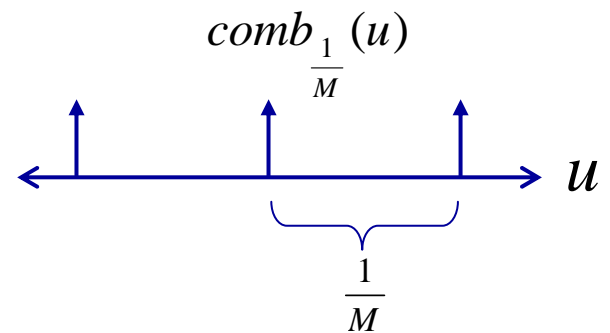
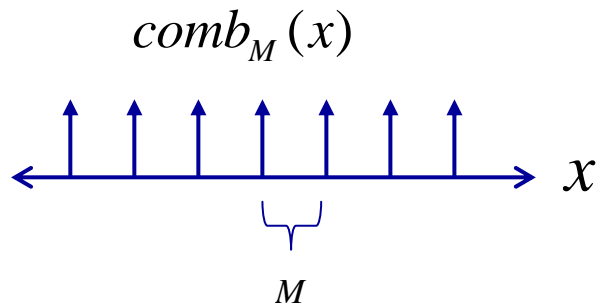
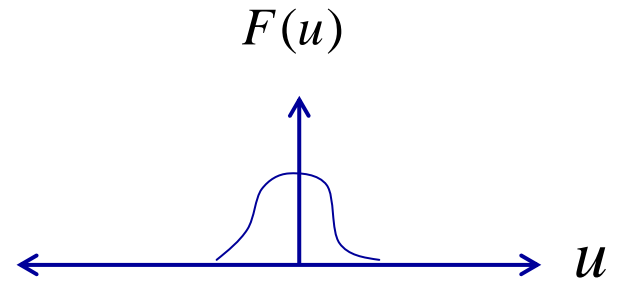
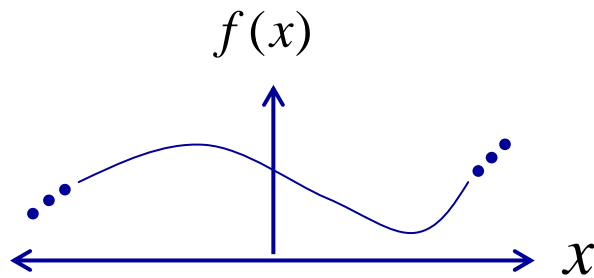
$$\text{comb}_2(x)$$



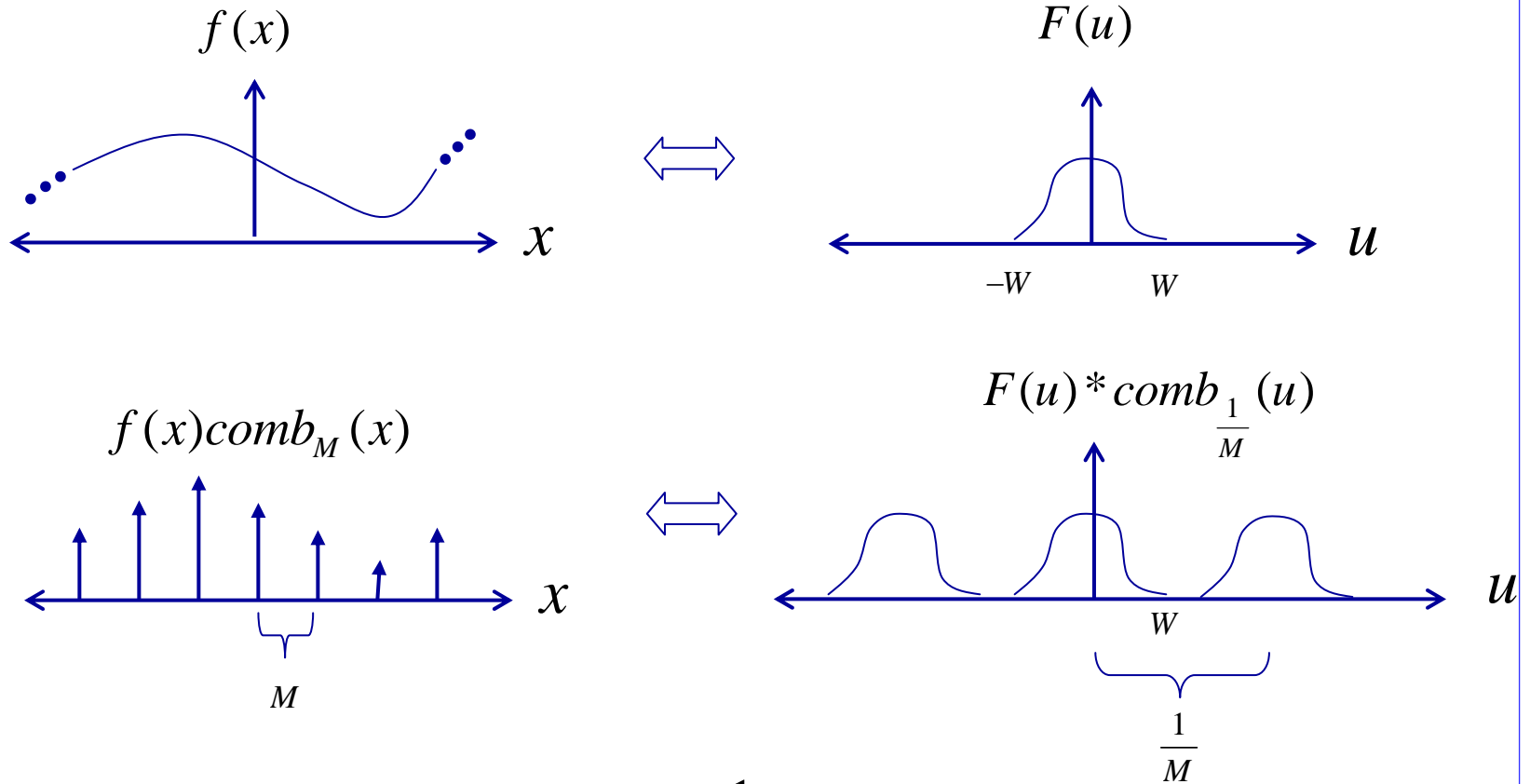
$$\frac{1}{2} \text{comb}_{\frac{1}{2}}(u)$$



# Sampling revisitation

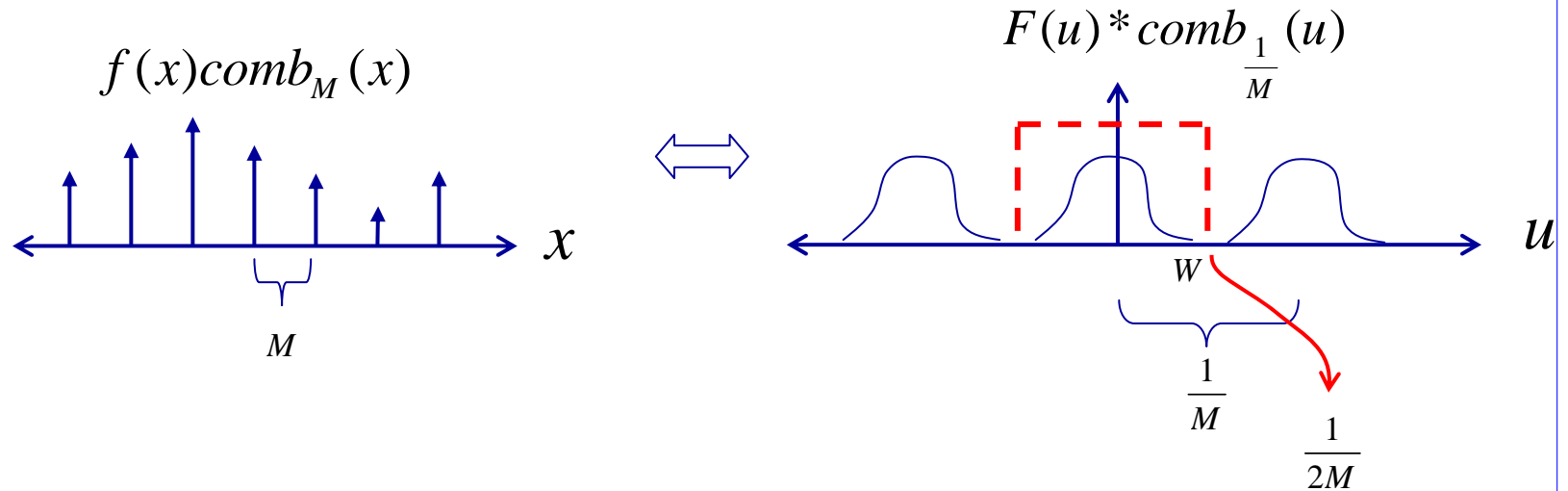


# Sampling revisitation



No aliasing if  $\frac{1}{M} > 2W$

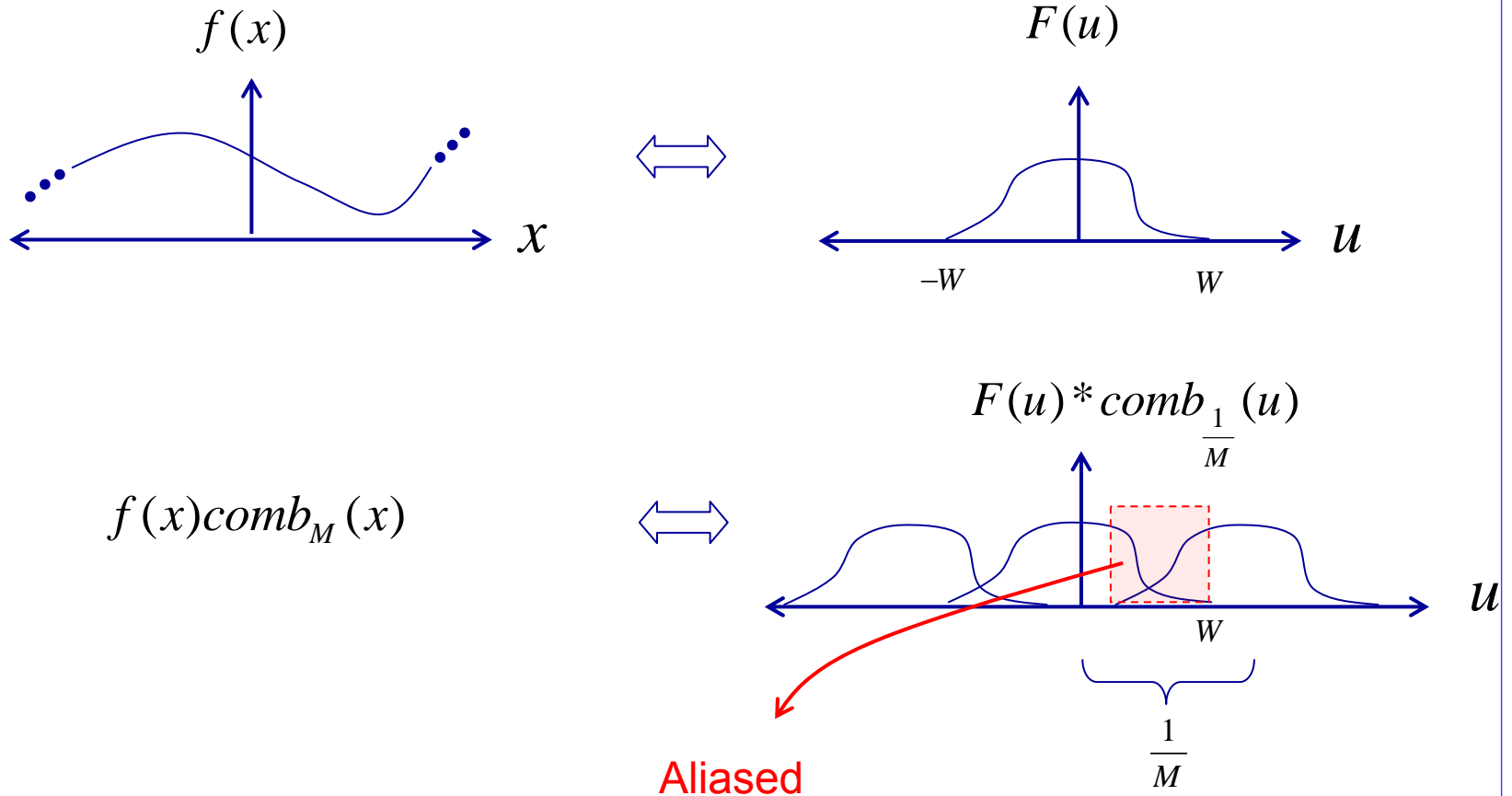
# Sampling and aliasing



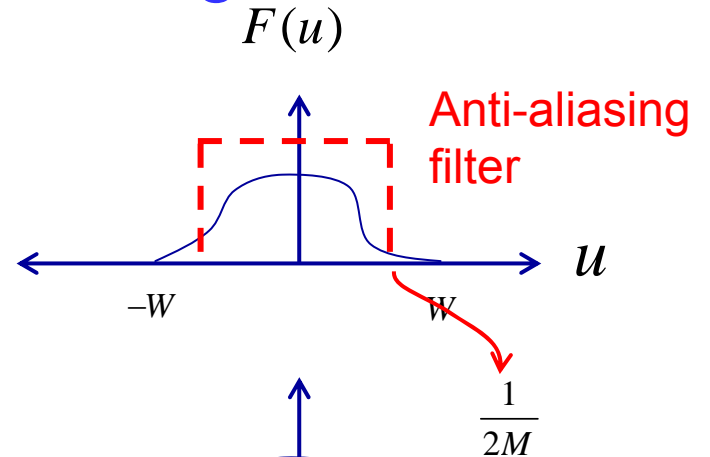
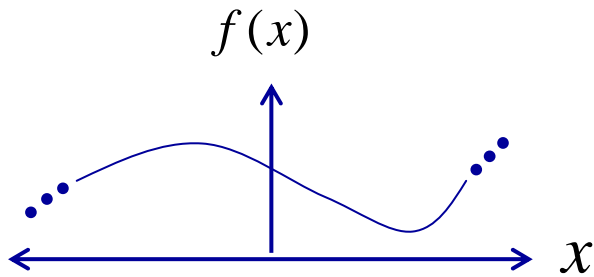
*If there is no aliasing, the original signal can be recovered from its samples by low-pass filtering.*



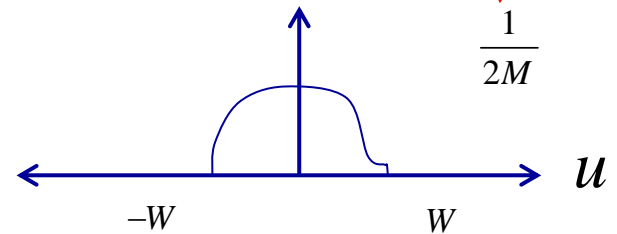
# Sampling and aliasing



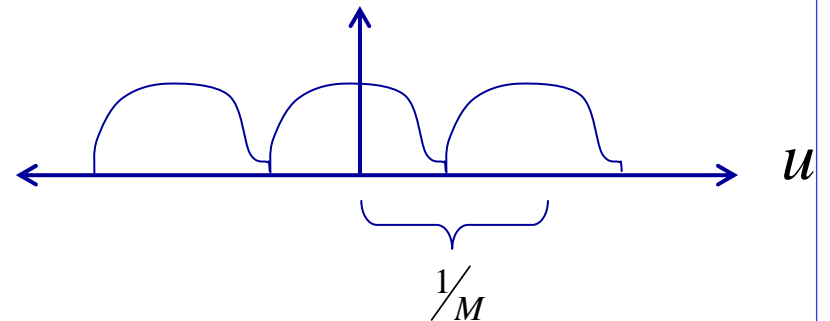
# Sampling and aliasing



$$f(x) * h(x)$$



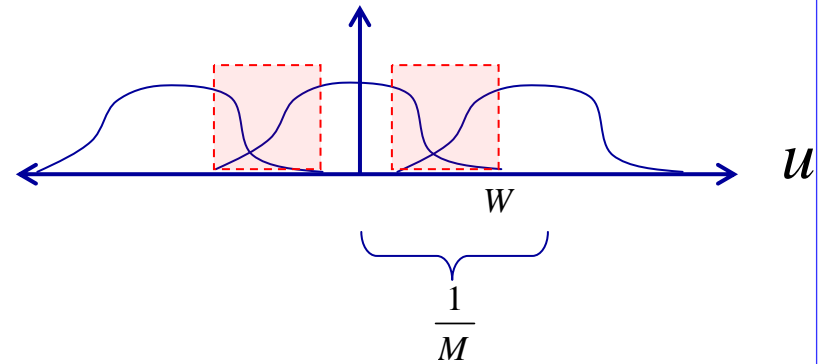
$$[f(x) * h(x)] \text{comb}_M(x)$$



# Sampling and aliasing

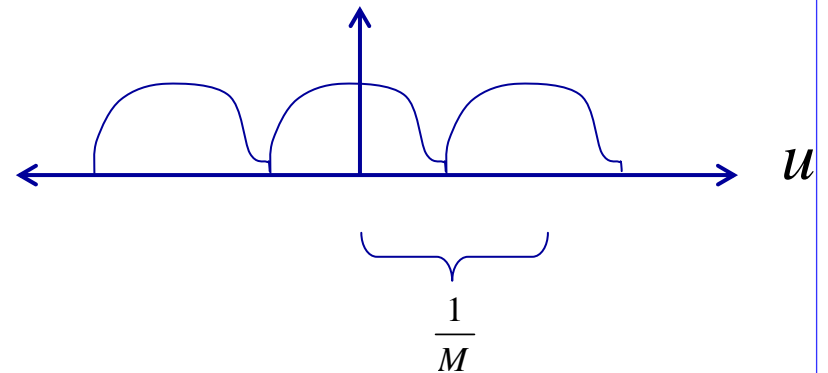
- Without anti-aliasing filter:

$$f(x)comb_M(x)$$



- With anti-aliasing filter:

$$[f(x) * h(x)]comb_M(x)$$



## More formally qui

- Let  $g[m, n] = f(x, y) \text{comb}_{M, N}(x, y)$

we start in the continuous  
in signal domain

$m, n$ : discrete indexes

$x, y$ : continuous (real) coordinates

Using the multiplication property:

$$G(u, v) = F(u, v) * \frac{1}{MN} \text{comb}_{\frac{1}{M}, \frac{1}{N}}(u, v)$$

in frequency domain

$$\text{comb}_{M, N}(u, v) \triangleq \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta(u - kM, v - lN)$$

$$\text{comb}_{\frac{1}{M}, \frac{1}{N}}(u, v) \triangleq \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(u - \frac{k}{M}, v - \frac{l}{N}\right)$$

$$\text{comb}_{\frac{1}{M}, \frac{1}{N}}(\eta, \nu) \triangleq \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(\eta - \frac{k}{M}, \nu - \frac{l}{N}\right)$$

$\eta, \nu$ : generic variables,  
used to calculate the  
integral in the convolution

# Sampling

Convolution integral:

$$F * H(u, v) = \int_{-\frac{1}{2}}^{\frac{1}{2}} \int_{-\frac{1}{2}}^{\frac{1}{2}} F(\eta, \nu) H\left(u - \eta, v - \nu\right) d\eta d\nu$$

$$H(u, v) = \frac{1}{MN} \text{comb}_{\frac{1}{M}, \frac{1}{N}}(u, v) = \frac{1}{MN} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(u - \frac{k}{M}, v - \frac{l}{N}\right)$$

$$H(\eta, \nu) = \frac{1}{MN} \text{comb}_{\frac{1}{M}, \frac{1}{N}}(\eta, \nu) = \frac{1}{MN} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(\eta - \frac{k}{M}, \nu - \frac{l}{N}\right)$$

$$F * H(u, v) = \frac{1}{MN} \int_{-\frac{1}{2}}^{\frac{1}{2}} \int_{-\frac{1}{2}}^{\frac{1}{2}} F(\eta, \nu) \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(u - \left(\eta - \frac{k}{M}\right), v - \left(\nu - \frac{l}{N}\right)\right) d\eta d\nu =$$

$$= \frac{1}{MN} \int_{-\frac{1}{2}}^{\frac{1}{2}} \int_{-\frac{1}{2}}^{\frac{1}{2}} F(\eta, \nu) \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(u - \eta + \frac{k}{M}, v - \nu + \frac{l}{N}\right) d\eta d\nu$$

# Sampling

- Since  $k, l$  goes from  $-\infty$  to  $+\infty$ , we can change their sign in the formula

$$G(u, v) = F * H(u, v) = \frac{1}{MN} \int_{-\frac{1}{2}}^{\frac{1}{2}} \int_{-\frac{1}{2}}^{\frac{1}{2}} F(\eta, \nu) \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \delta\left(u - \eta - \frac{k}{M}, v - \nu - \frac{l}{N}\right) d\eta d\nu$$

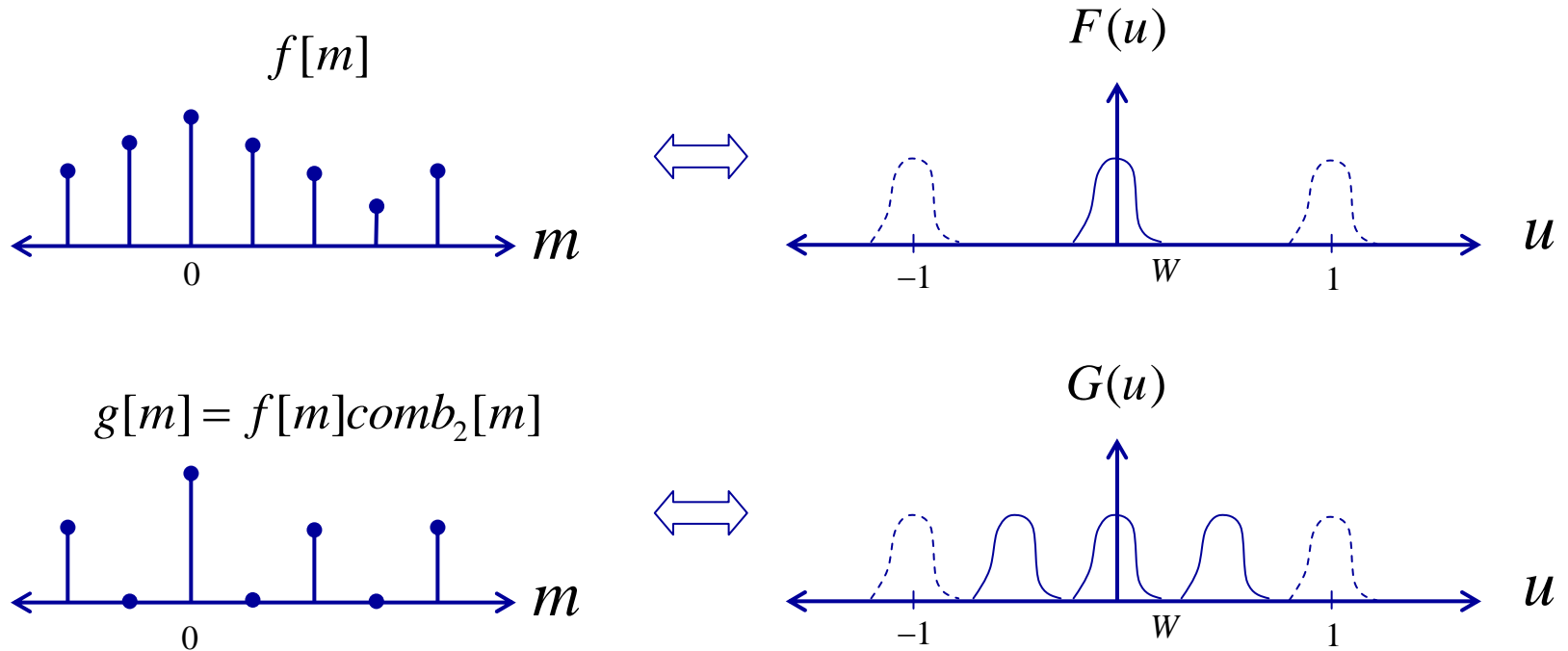
# Sampling

$$G(u, v) = \frac{1}{MN} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} \int_{-\frac{1}{2}}^{\frac{1}{2}} \int_{-\frac{1}{2}}^{\frac{1}{2}} F(\eta, \nu) \delta\left(u - \eta - \frac{k}{M}, v - \nu - \frac{l}{N}\right) d\eta d\nu$$

sampling property of the delta function:

$$G(u, v) = \frac{1}{MN} \sum_{k=-\infty}^{+\infty} \sum_{l=-\infty}^{+\infty} F\left(u - \frac{k}{M}, v - \frac{l}{N}\right)$$

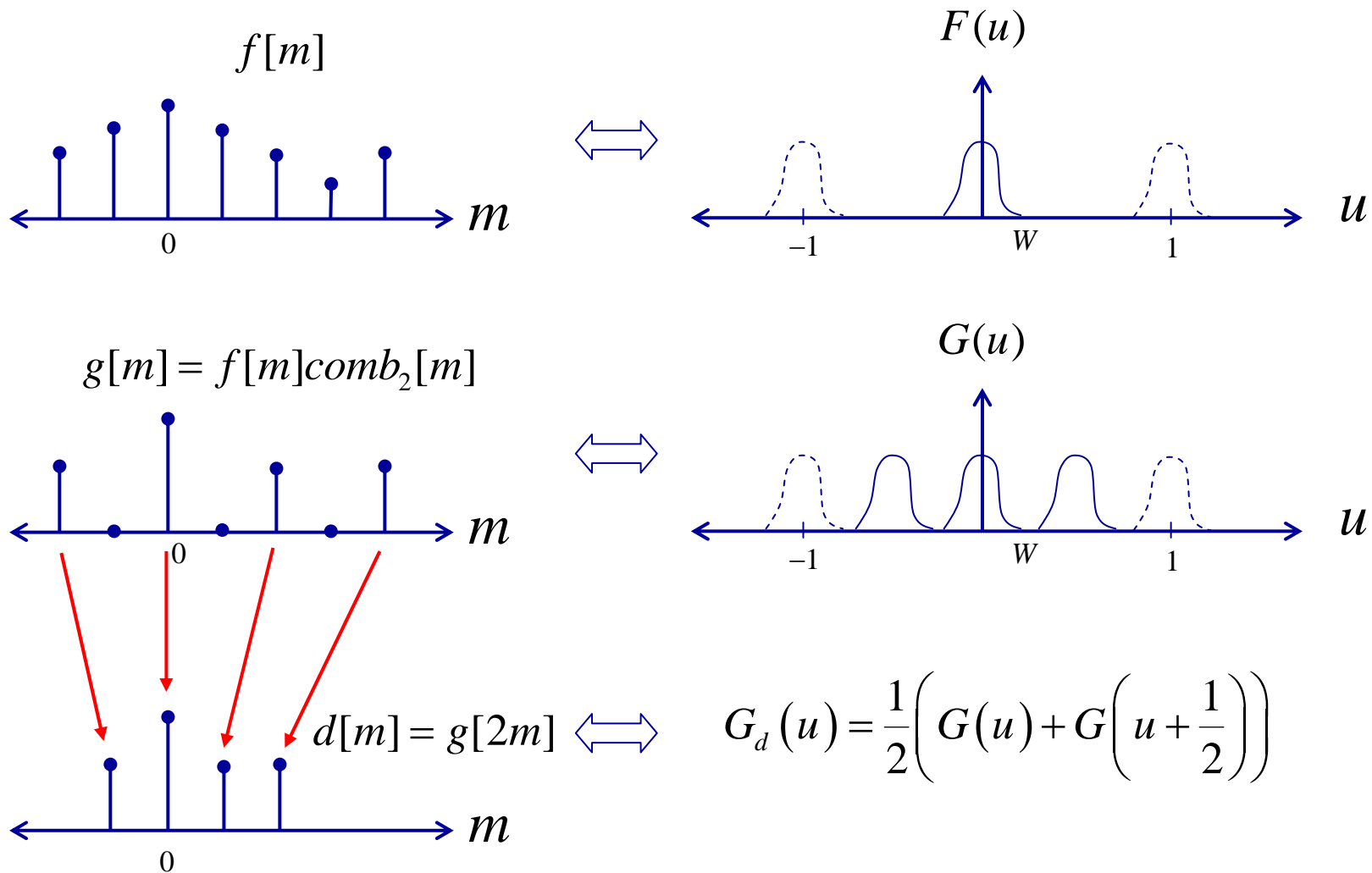
# Downsampling



Downsampling makes the repetitions get closer to each other  $\rightarrow$  risk of aliasing



# Downsampling



# Downsampling

$$g[m, n] = f[m, n] \text{comb}_{M, N}[m, n]$$

$$d[m, n] = g[Mm, Nn]$$

$$G(u, v) = \frac{1}{MN} \sum_{k \in N_k} \sum_{l \in N_l} F\left(u - \frac{k}{M}, v - \frac{l}{N}\right)$$

where

$$N_k = \left\{ k \text{ such that } \frac{-1}{2} \leq u - \frac{k}{M} < \frac{1}{2} \right\}$$

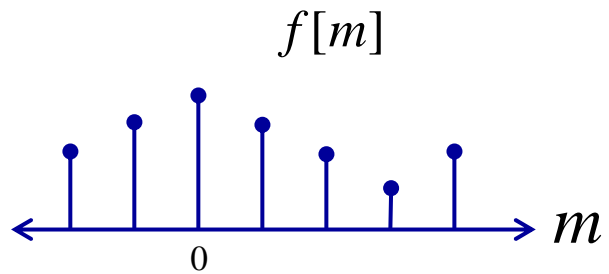
$$N_l = \left\{ l \text{ such that } \frac{-1}{2} \leq v - \frac{l}{N} < \frac{1}{2} \right\}$$

Additional repetitions in the basic period  $(-1/2, 1/2)$

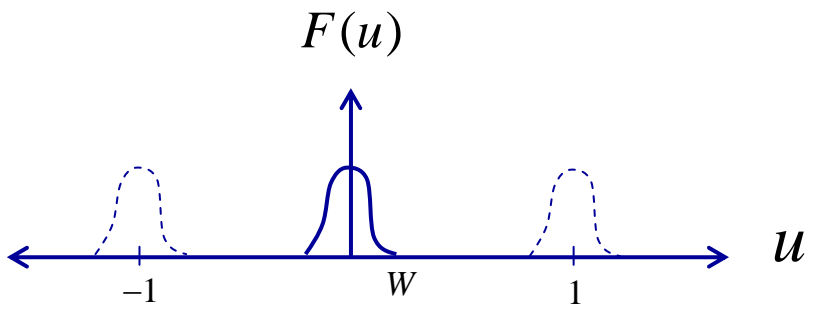
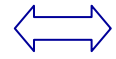
$$M = 2, N = 2$$

$$G(u, v) = \frac{1}{4} \left\{ F(u, v) + F\left(u, v - \frac{1}{2}\right) + F\left(u - \frac{1}{2}, v\right) + F\left(u - \frac{1}{2}, v - \frac{1}{2}\right) \right\}$$

# Example



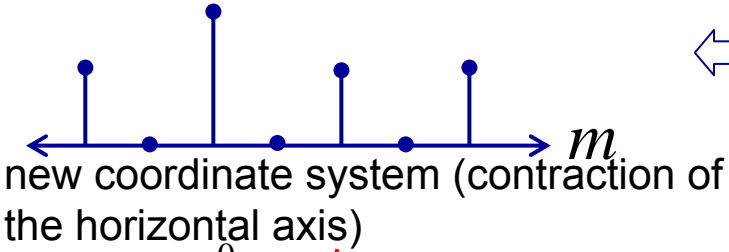
same coordinate system



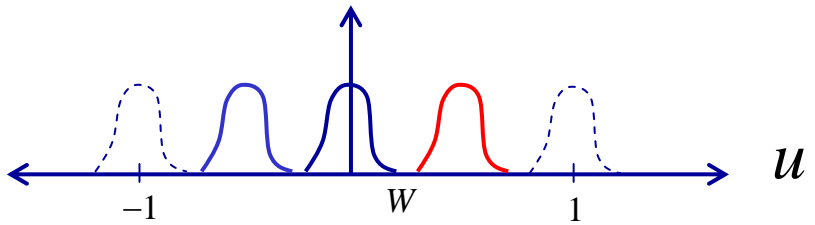
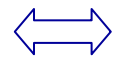
new spurious repetitions

$G(u)$

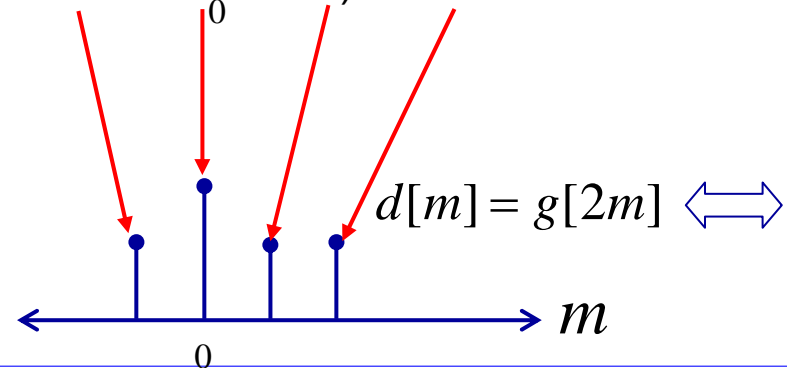
$$g[m] = f[m] \text{comb}_2[m]$$



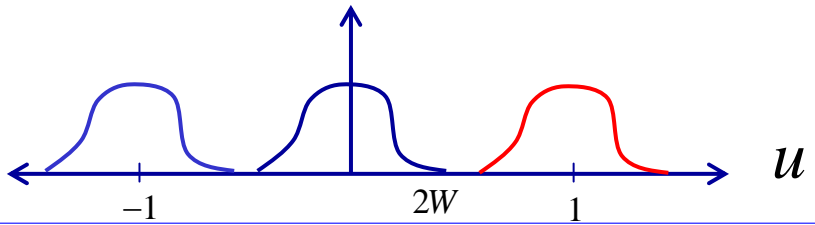
new coordinate system (contraction of the horizontal axis)



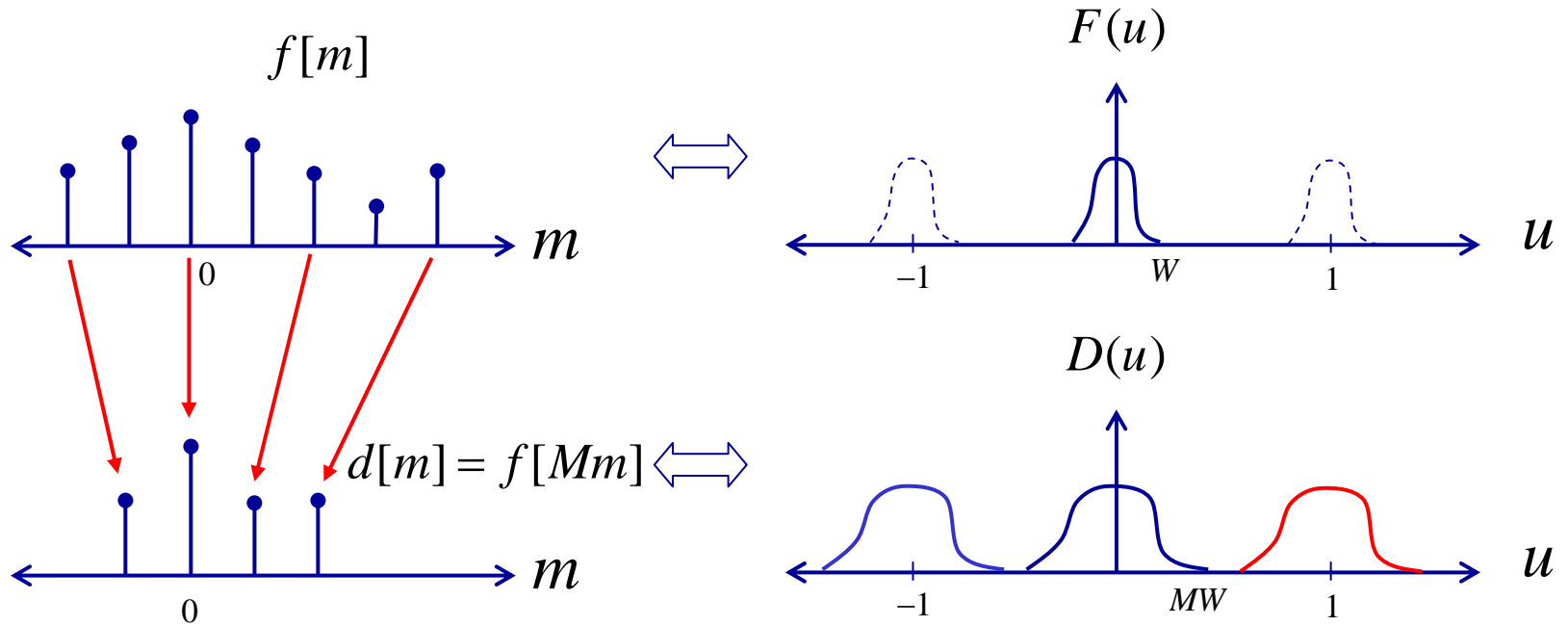
dilation of the frequency axis:  
doubling of the basic repetition  
bandwidth  $D(u)$



$$d[m] = g[2m]$$



# Example

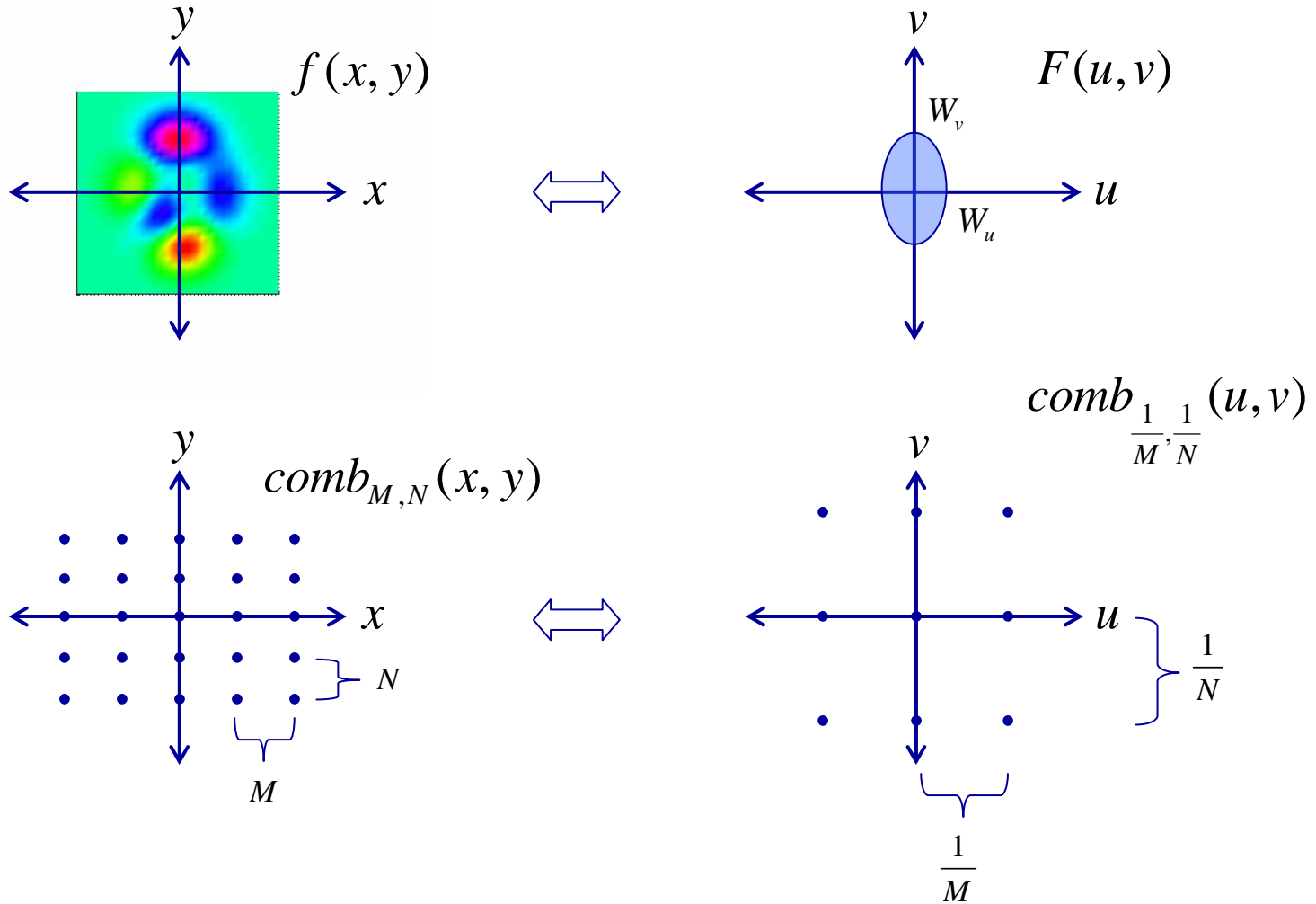


No aliasing if  $MW < \frac{1}{2}$

# Aliasing in images

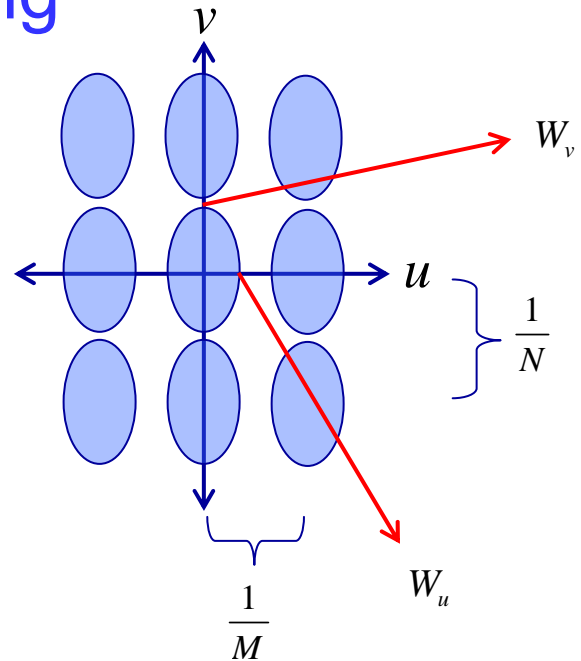
- Without the anti-aliasing filter the recovered image (subsampling+upsampling) is different from the original.
- With anti-aliasing filter (low-pass), the *smoothed* version of the original image can be recovered by interpolation

# Sampling



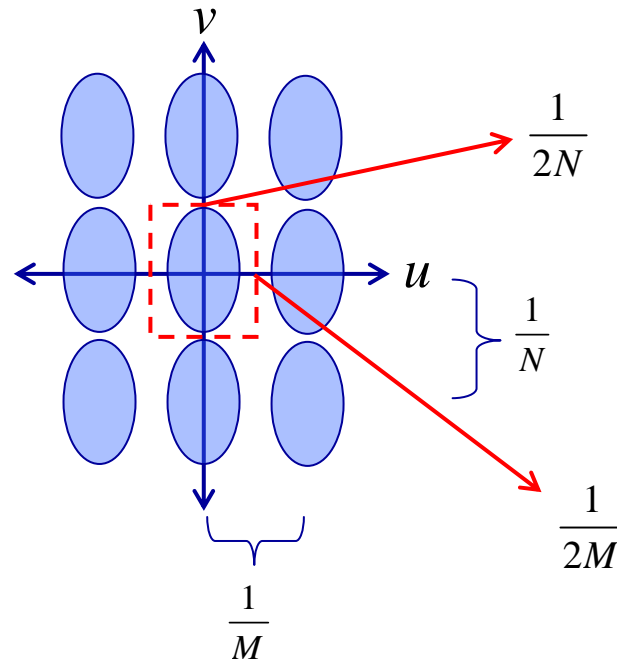
# Sampling

$$f(x, y) \text{comb}_{M,N}(x, y)$$



*No aliasing if  $\frac{1}{M} > 2W_u$  and  $\frac{1}{N} > 2W_v$*

# Interpolation



*Ideal reconstruction  
filter:*

$$H(u, v) = \begin{cases} MN, & \text{for } u \leq \frac{1}{2M} \text{ and } v \leq \frac{1}{2N} \\ 0, & \text{otherwise} \end{cases}$$



# Anti-Aliasing

```
a=imread('barbara.tif');
```



# Anti-Aliasing

```
a=imread('barbara.tif');  
b=imresize(a,0.25);  
c=imresize(b,4);
```



# Anti-Aliasing

```
a=imread('barbara.tif');  
b=imresize(a,0.25);  
c=imresize(b,4);
```

```
H=zeros(512,512);  
H(256-64:256+64, 256-64:256+64)=1;
```

```
Da=fft2(a);  
Da=fftshift(Da);  
Dd=Da.*H;  
Dd=fftshift(Dd);  
d=real(iff2(Dd));
```



# Ideal Reconstruction Filter: 2D box

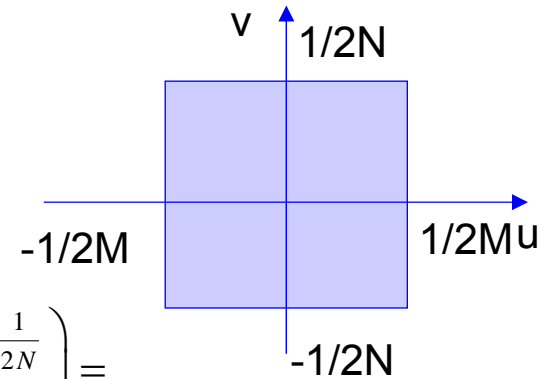
$$h(x, y) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} H(u, v) e^{j2\pi(ux+vy)} du dv = \int_{\frac{1}{2N}}^{\frac{1}{2N}} \int_{\frac{-1}{2M}}^{\frac{1}{2M}} MNe^{j2\pi(ux+vy)} du dv$$

$$= \int_{\frac{-1}{2M}}^{\frac{1}{2M}} Me^{j2\pi ux} du \int_{\frac{-1}{2N}}^{\frac{1}{2N}} Ne^{j2\pi vy} dv$$

$$= MN \frac{1}{j2\pi x} \left( e^{j2\pi x \frac{1}{2M}} - e^{-j2\pi x \frac{1}{2M}} \right) \times \frac{1}{j2\pi y} \left( e^{j2\pi y \frac{1}{2N}} - e^{-j2\pi y \frac{1}{2N}} \right) =$$

$$= \frac{1}{\frac{\pi}{M} x} \frac{1}{2j} \left( e^{j\pi x \frac{1}{M}} - e^{-j\pi x \frac{1}{M}} \right) \times \frac{1}{\frac{\pi}{N} y} \frac{1}{2j} \left( e^{j\pi y \frac{1}{N}} - e^{-j\pi y \frac{1}{N}} \right) =$$

$$= \frac{\sin\left(\frac{\pi}{M} x\right)}{\frac{\pi}{M} x} \times \frac{\sin\left(\frac{\pi}{N} y\right)}{\frac{\pi}{N} y}$$



$$\sin(x) = \frac{1}{2j} (e^{jx} - e^{-jx})$$

## 2D sinc

