

# GEOMETRIA

## Formulario

### ★ CALCOLO VETTORIALE

• vettori geometrici

$$\underline{a} = (a_1, a_2, a_3)$$

coordinate cartesiane  
(ortogonali)

• prodotto scalare

$$\langle \underline{a}, \underline{b} \rangle = \sum_{i=1}^3 a_i b_i$$

$$\|\underline{a}\| := \langle \underline{a}, \underline{a} \rangle^{\frac{1}{2}} \quad \text{lunghezza (norma)} \\ \text{di } \underline{a}$$

• angolo tra  $\underline{a}$  e  $\underline{b}$

$$\cos \alpha = \frac{\langle \underline{a}, \underline{b} \rangle}{\|\underline{a}\| \|\underline{b}\|}$$

$$\underline{a} \neq \underline{0} \\ \underline{b} \neq \underline{0}$$

• ortogonalità:

$$\langle \underline{a}, \underline{b} \rangle = 0$$

• prodotto vettoriale

$$\underline{a} \times \underline{b} = \begin{vmatrix} \underline{i} & \underline{j} & \underline{k} \\ a_1 & a_2 & a_3 \\ b_1 & b_2 & b_3 \end{vmatrix}$$

$$\|\underline{a} \times \underline{b}\| = \|\underline{a}\| \|\underline{b}\| |\sin \alpha| = \left( \|\underline{a}\|^2 \|\underline{b}\|^2 - \langle \underline{a}, \underline{b} \rangle^2 \right)^{\frac{1}{2}}$$

$$\underline{a} \parallel \underline{b} \quad (\underline{a}, \underline{b} \text{ l.o.d.}) \quad : \quad \underline{a} \times \underline{b} = \underline{0}$$

(parallelismo)

• prodotto misto

$$\det(\underline{a}, \underline{b}, \underline{c}) = \langle \underline{a}, \underline{b} \times \underline{c} \rangle \\ \equiv |\underline{a}, \underline{b}, \underline{c}|$$

• complanarità

$$\text{di } \underline{a}, \underline{b}, \underline{c} \quad \langle \underline{a}, \underline{b} \times \underline{c} \rangle = 0 \\ (\underline{a}, \underline{b}, \underline{c} \text{ l.o.d.})$$

### ★ CURVE

$$\underline{r} = \underline{r}(t)$$

$$t \in I$$

$$\dot{\underline{r}} = \frac{d\underline{r}}{dt}$$

$$\dot{\underline{r}} \neq \underline{0}$$

curve regolari

• lunghezza d'arco

$$ds = \|\dot{\underline{r}}\| dt$$

$$/ = \frac{d}{ds}$$

$$\|\underline{r}'\| = 1$$

$$\underline{t} = \underline{r}' = \frac{\underline{\dot{r}}}{\|\underline{\dot{r}}\|} \quad \text{versore tangente}$$

$$\underline{n} = \frac{\underline{r}''}{\|\underline{r}''\|} \quad \|\underline{r}''\| = R \quad \text{curvatura}$$

• normale principale

$R > 0$ : birregolarità

$$\underline{b} = \underline{t} \times \underline{n}$$

• versore binormale

Formule di Frenet:

$$\begin{cases} \underline{t}' = R \underline{n} \\ \underline{n}' = -R \underline{t} - \tau \underline{b} \\ \underline{b}' = \tau \underline{n} \end{cases}$$

$\tau$ : torsione

• Formule generali per  $R$  e  $\tau$

$$R = \frac{\|\underline{\dot{r}} \times \underline{\ddot{r}}\|}{\|\underline{\dot{r}}\|^3} = \frac{\left[ \|\underline{\dot{r}}\|^2 \|\underline{\ddot{r}}\|^2 - \langle \underline{\dot{r}}, \underline{\ddot{r}} \rangle^2 \right]^{\frac{1}{2}}}{\|\underline{\dot{r}}\|^3}$$

$$G = \frac{1}{R} \quad \text{raggio di curvatura}$$

curva piana:  $R = \frac{x''y' - y''x'}{(x'^2 + y'^2)^{3/2}}$   
con segno

$$\tau = \langle \underline{b}', \underline{n} \rangle = - \frac{|\underline{r}', \underline{r}'', \underline{r}''''|}{\underbrace{\|\underline{r}''\|^2}_{R^2}} = - \frac{|\underline{\dot{r}}, \underline{\ddot{r}}, \underline{\ddot{\ddot{r}}}|}{\left( \|\underline{\dot{r}}\|^2 \|\underline{\ddot{r}}\|^2 - \langle \underline{\dot{r}}, \underline{\ddot{r}} \rangle^2 \right)}$$

$$= - \frac{\langle \underline{\dot{r}} \times \underline{\ddot{r}}, \underline{\ddot{\ddot{r}}} \rangle}{\|\underline{\dot{r}} \times \underline{\ddot{r}}\|^2}$$

• sfera osculatrice

$$C = P + G \underline{n} + \frac{G'}{\tau} \underline{b} \quad \tau \neq 0$$

centro

$$R = \sqrt{G^2 + \left( \frac{G'}{\tau} \right)^2}$$

raggio

★ SUPERFICIE

$\Gamma = \Gamma(u, v)$   
 $(u, v) \in \mathcal{R}$  regione

$\underline{N} = \frac{\underline{r}_u \times \underline{r}_v}{\|\underline{r}_u \times \underline{r}_v\|}$

$\underline{r}_u \times \underline{r}_v \neq \underline{0}$   
 (regolarità)

• forme fondamentali

I  $\begin{cases} E = \langle \underline{r}_u, \underline{r}_u \rangle \\ F = \langle \underline{r}_u, \underline{r}_v \rangle \\ G = \langle \underline{r}_v, \underline{r}_v \rangle \end{cases}$       II  $\begin{cases} e = \langle \underline{r}_{uu}, \underline{N} \rangle \\ f = \langle \underline{r}_{uv}, \underline{N} \rangle \\ g = \langle \underline{r}_{vv}, \underline{N} \rangle \end{cases}$

$\frac{\langle \underline{r}_{uu}, \underline{r}_u \times \underline{r}_v \rangle}{\|\underline{r}_u \times \underline{r}_v\|}$

$\frac{\langle \underline{r}_{uv}, \underline{r}_u \times \underline{r}_v \rangle}{\|\underline{r}_u \times \underline{r}_v\|}$

$\frac{\langle \underline{w}, \underline{w} \rangle}{\|\underline{w}\|^2}$

II  $\frac{\langle \underline{w}, \underline{w} \rangle}{\|\underline{w}\|^2} = R_m =$

$\frac{e \dot{u}^2 + 2f \dot{u} \dot{v} + g \dot{v}^2}{E \dot{u}^2 + 2F \dot{u} \dot{v} + G \dot{v}^2}$

$\frac{\langle \underline{r}_{uu}, \underline{r}_u \times \underline{r}_v \rangle}{\|\underline{r}_u \times \underline{r}_v\|} = \sqrt{EG - F^2}$  ecc.

$\underline{w} \in T_p \Sigma$   
 $\neq \underline{0}$

curvatura normale nella direzione determinata da  $\underline{w}$

$K = \frac{eg - f^2}{EG - F^2}$

• curvatura gaussiana  
 $= R_1 R_2$

$\underline{w} = \underline{r}_u \dot{u} + \underline{r}_v \dot{v}$

$H = \frac{1}{2} \frac{eG - 2Ff + Eg}{EG - F^2} = \frac{1}{2} (R_1 + R_2)$

• curv. principali

$R_m = R_1 \cos^2 \vartheta + R_2 \sin^2 \vartheta$

• curvatura media

Eulero

• curvatura principali:  $R_i^2 - 2H R_i + K = 0$

• linee di curvatura (direzioni principali)

$\begin{vmatrix} \dot{v}^2 & -\dot{u} \dot{v} & \dot{u}^2 \\ E & F & G \\ e & f & g \end{vmatrix} = 0$

• linee asintotiche (direzioni asintotiche)

$e \dot{u}^2 + 2f \dot{u} \dot{v} + g \dot{v}^2 = 0$

★ Formule di Weingarten

$m_{\beta\beta}(\underline{\beta}) = \int \underline{r}_x, \underline{r}_y - dN$

$\begin{pmatrix} \frac{eG - fF}{EG - F^2} & \frac{fG - gF}{EG - F^2} \\ -\frac{eF + fE}{EG - F^2} & \frac{gE - fF}{EG - F^2} \end{pmatrix}$

★ operatore di forma

$F = 0 \sim \begin{pmatrix} -\frac{f}{E} & +\frac{f}{E} \\ +\frac{f}{G} & -\frac{g}{G} \end{pmatrix}$

• Simboli di Christoffel

$$ds^2 = g_{ij} dx^i dx^j$$

$i, j, k = 1, 2$   
 \* convenzione di Einstein  
 [qui si somma su  $k = 1, 2$ ]

$$\Gamma_{jk}^i = \frac{1}{2} g^{ih} \left( \frac{\partial g_{kh}}{\partial x^j} + \frac{\partial g_{jh}}{\partial x^k} - \frac{\partial g_{jk}}{\partial x^h} \right)$$

elementi della matrice inversa di  $(g_{ij})$

• equazione del trasporto parallelo

$$\dot{w}^i + \Gamma_{kh}^i w^k w^h = 0 \quad i=1, 2$$

• equazione delle geodetiche

$$\ddot{x}^i + \Gamma_{kh}^i \dot{x}^k \dot{x}^h = 0 \quad i=1, 2$$

• Equazioni di Lagrange

nel nostro caso

$$\frac{d}{dt} \frac{\partial L}{\partial \dot{q}_i} - \frac{\partial L}{\partial q_i} = 0$$

$$L = \frac{1}{2} g_{ij} \dot{x}^i \dot{x}^j$$

$\Rightarrow$  eq. geodetica

se  $\dot{\phantom{x}} = \dot{\phantom{t}} = \frac{d}{ds}$

$$g_{ij} \dot{x}^i \dot{x}^j = 1 \quad \text{"conservazione dell'energia"}$$

se  $\frac{\partial L}{\partial q} = 0 \Rightarrow \frac{\partial L}{\partial \dot{q}} = \text{cost}$  (integrale primo)

• Formula di Riemann per la curvatura

se  $F=0$   $K = -\frac{1}{2\sqrt{E\alpha}} \left[ \left( \frac{E_{\nu\nu}}{\sqrt{E\alpha}} \right)_{\nu} + \left( \frac{G_{\nu\nu}}{\sqrt{E\alpha}} \right)_{\nu} \right]$