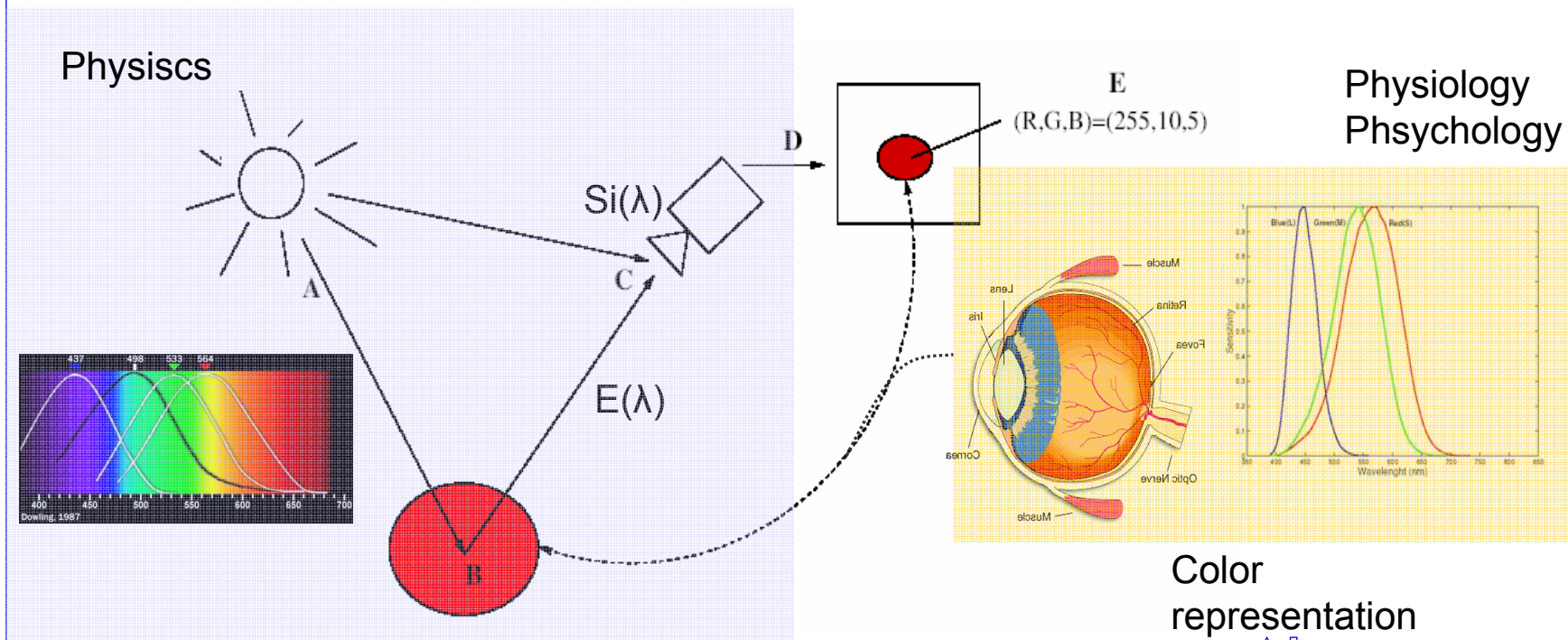


# Color imaging

# Color science

- Color vision
  - *Seeing* colors
  - Foundations of color vision
  - Trichromatic model
- Color naming
  - *Attaching labels* to colors
- Colorimetry & Photometry
  - *Measuring* colors: radiometric & photometric units
- Applications
  - Image rendering, cross-media color reproduction, image analysis, feature extraction, image classification, data mining...

# What is color?



$$C_i = \int_{\lambda} E(\lambda) S_i(\lambda) d\lambda$$

$S_i(\lambda)$ : sensitivity of the  $i^{\text{th}}$  sensor

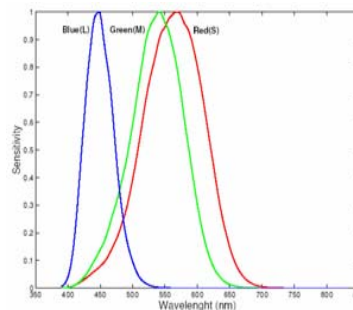
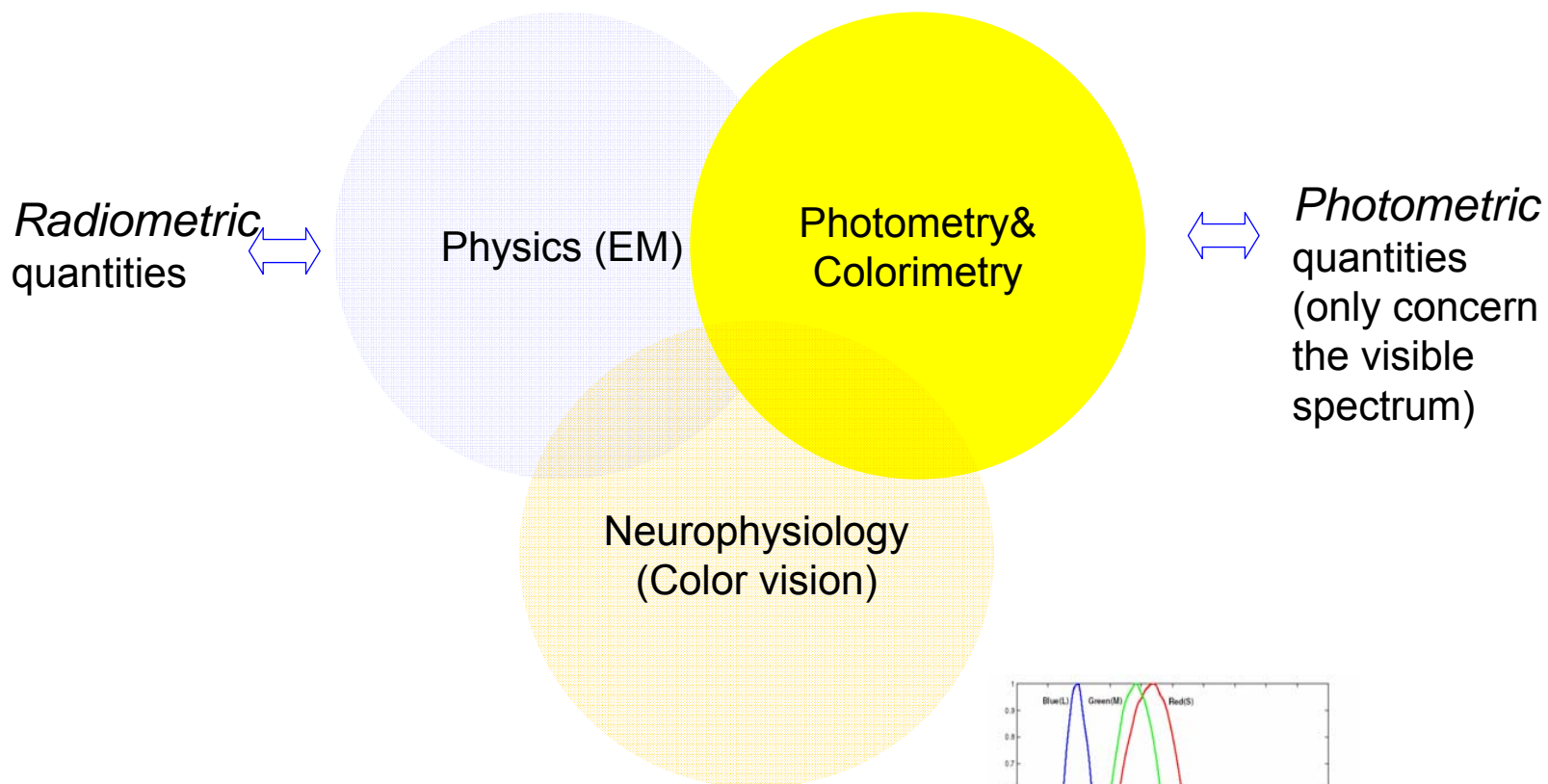
$E(\lambda)$ : Spectral Power Distribution (SPD) of the diffused light

Color representation

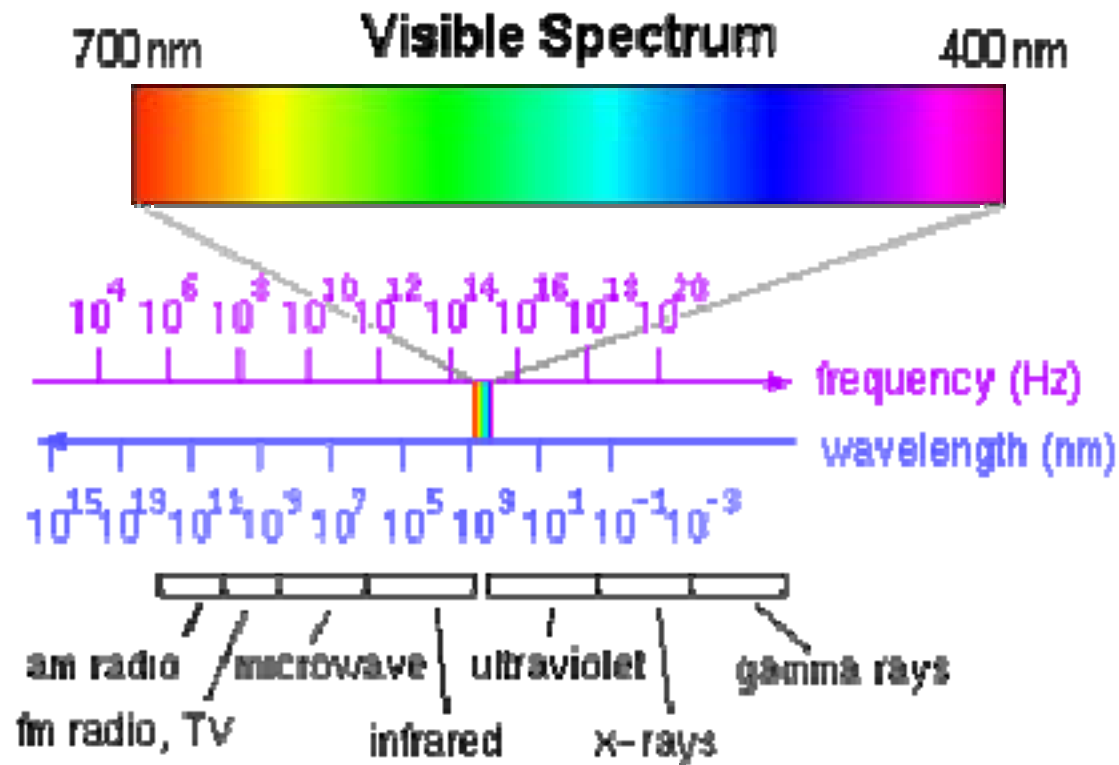
Modeling

Color perception

# What is color?



# Colorimetry



# Color models

- A color model is a 3D unique representation of a color
- There are different color models and the use of one over the other is problem oriented. For instance
  - RGB color model is used in hardware applications like PC monitors, cameras and scanners
  - CMY color model is used in color printers
  - YIQ model in television broadcast
  - In color image manipulation the two models widely used are HSI and HSV.

# Color models

- Colorimetric color models
  - Based on the principles of trichromacy
  - Allow to predict if two colors match in appearance in given observation conditions
  - CIE XYZ
  - Perceptually uniform color models (CIELAB, CIELUV)
- User-oriented color models
  - Emphasize the intuitive color notions of brightness, hue and saturation
    - HSV (Hue, saturation, Value)
    - HSI (Hue, Saturation, Intensity)
    - HSL (Hue, Saturation, Lightness)

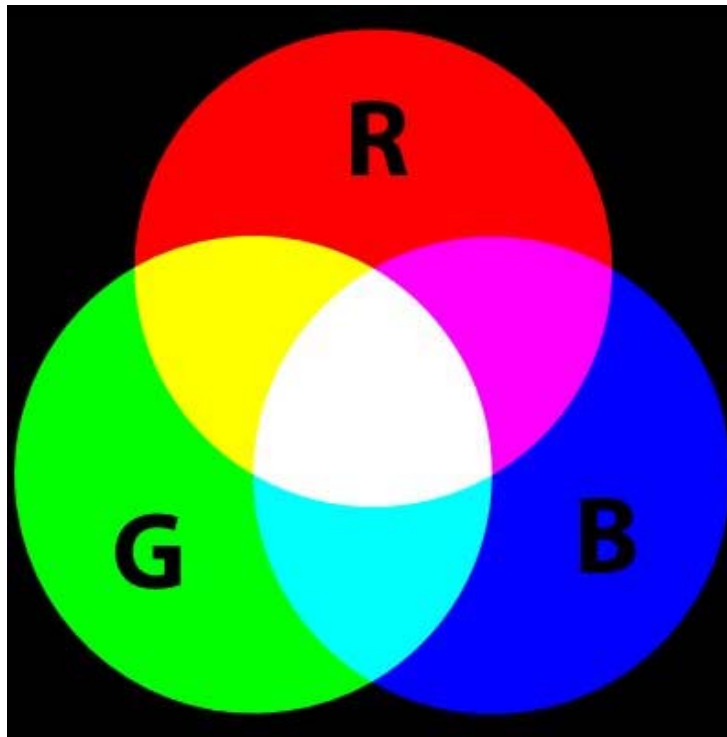
# Color models

- Device-oriented color models
  - The color representation depends on the device.
- Concerns both acquisition and display devices
  - Acquisition
    - The value of the color numerical descriptors depend on the spectral sensitivity of the camera sensors
  - Display
    - A color with given numerical descriptors appears different if displayed on another device or if the set-up changes
    - In RGB for instance, the R,G and B components depend on the chosen red, green and blue primaries as well as on the reference white
    - Amounts of ink expressed in CMYK or digitized video voltages expressed in RGB
  - RGB, Y'CbCr, Y'UV, CMY, CMYK
  - Towards device independence: sRGB

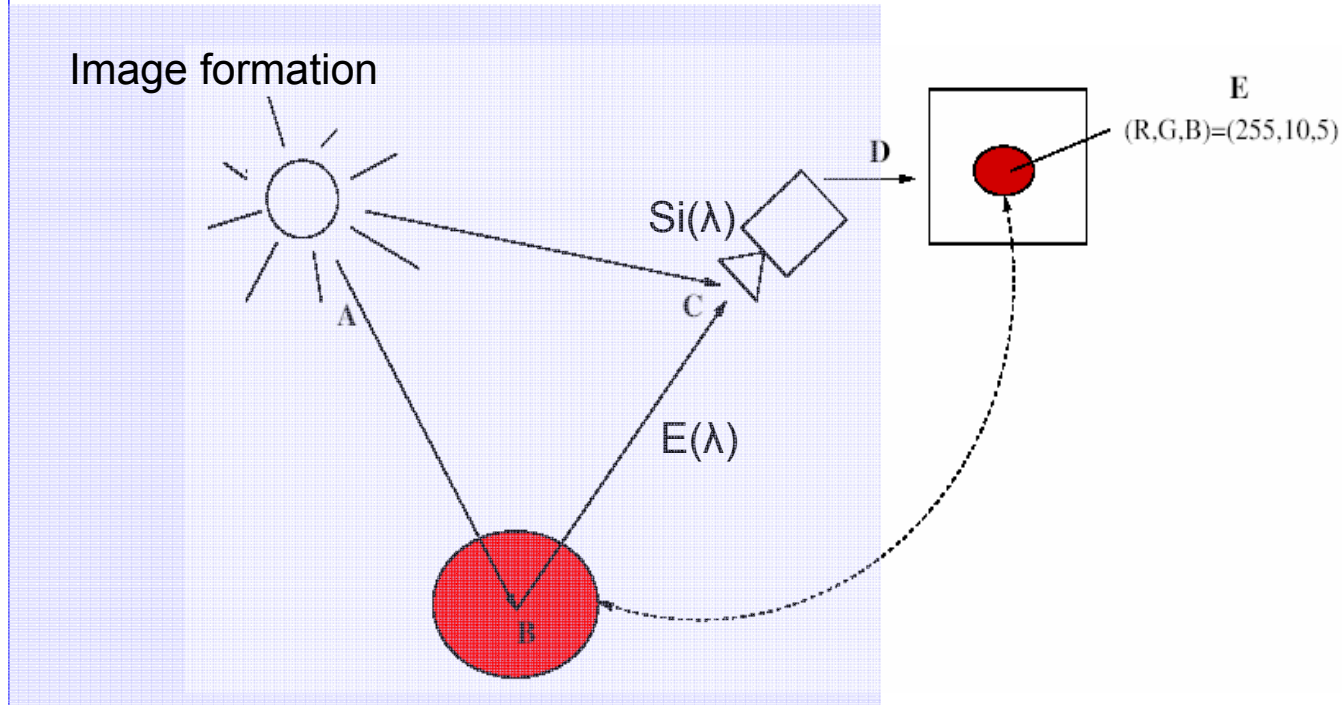


# RGB color model

- Additive color model
  - The additive reproduction process usually uses red, green and blue light to produce the other colors



# RGB color model



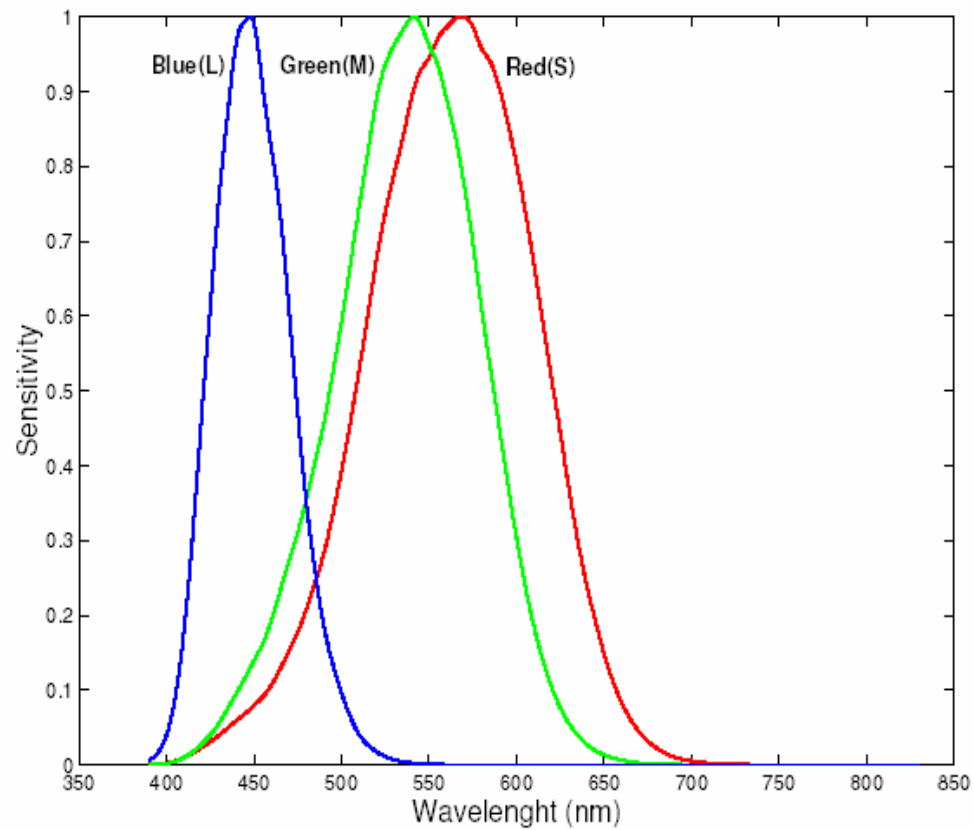
$$C_i = \int_{\lambda} E(\lambda) S_i(\lambda) d\lambda$$

$S_i(\lambda)$ : sensitivity of the  $i^{\text{th}}$  sensor

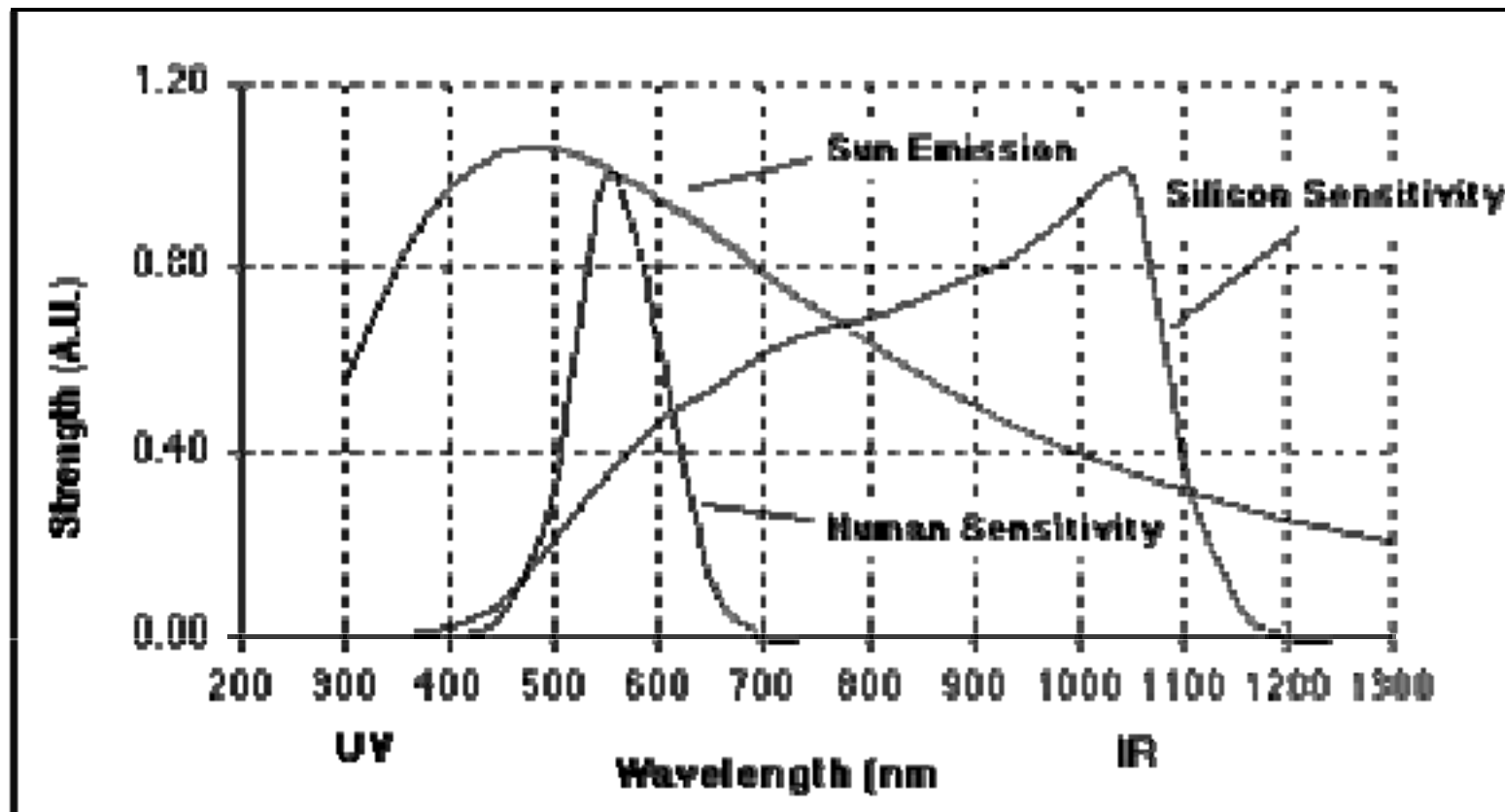
$E(\lambda)$ : Spectral Power Distribution (SPD) of the diffused light

# Spectral sensitivities

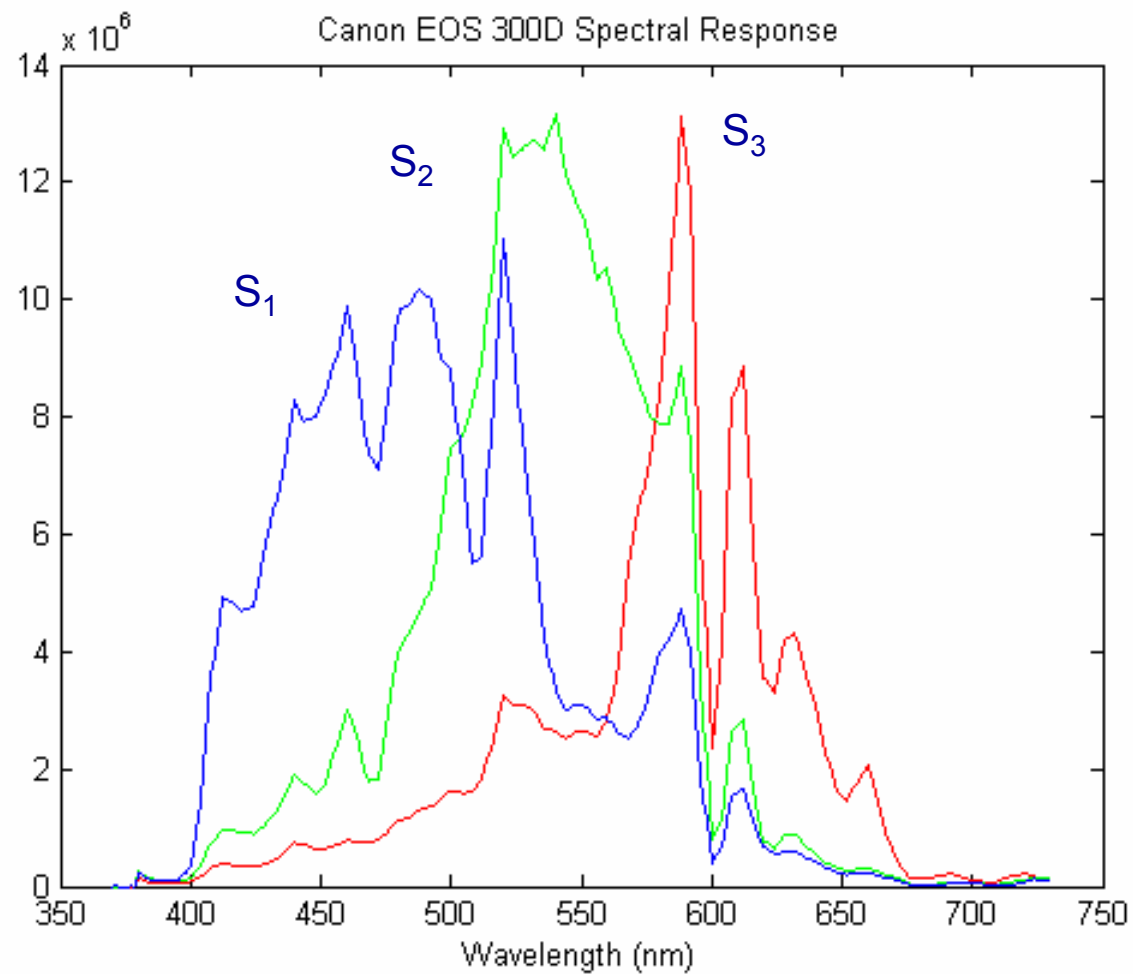
Target: spectral sensitivity of the eye



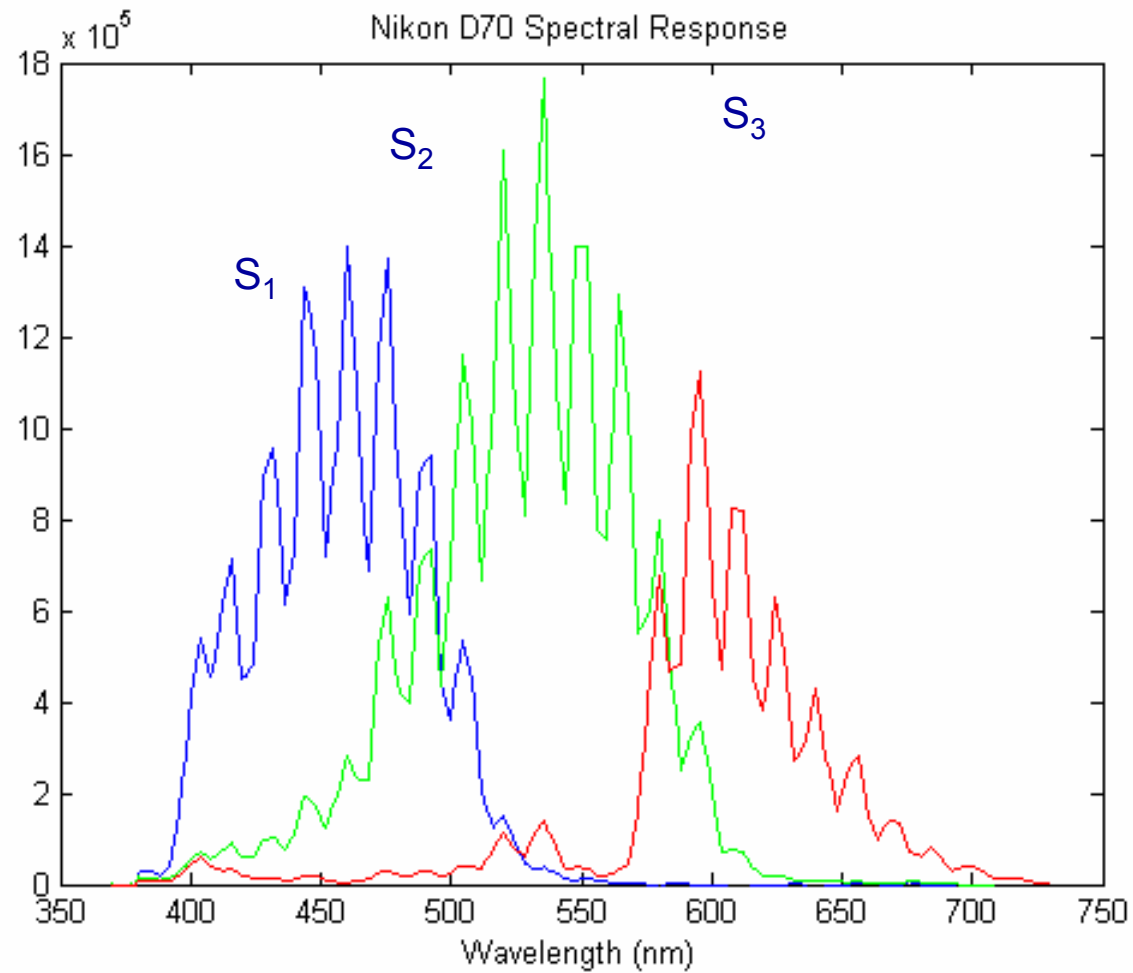
## Broad range sensitivity



# Sensor sensitivity: Ex. 1



# Spectral sensitivity: Ex. 2

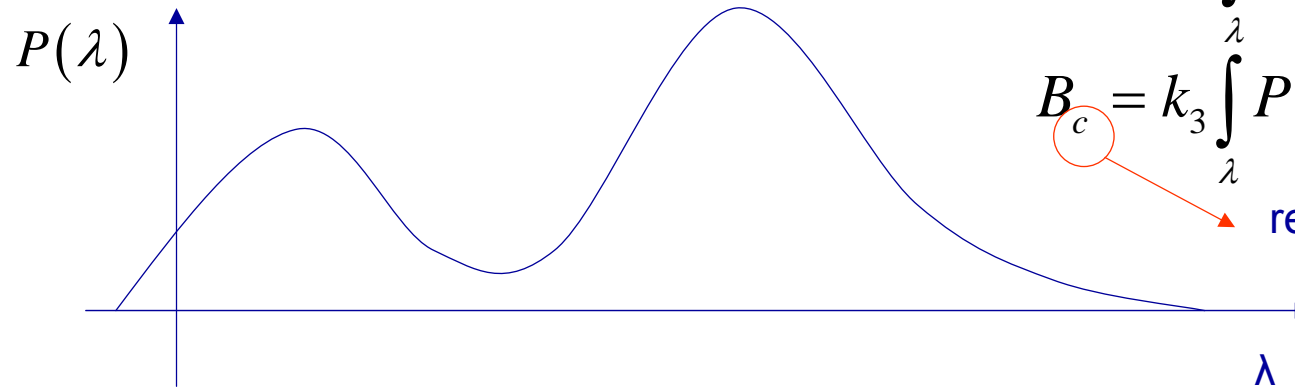


# RGB model

$$C_i = \int_{\lambda} P(\lambda) S_i(\lambda) d\lambda$$

$P(\lambda)$ : PSD (Power Spectral Density of the incident light)

$S_i(\lambda)$ : spectral sensitivity of the "red", "green" and "blue" sensors



$$R_c = k_1 \int_{\lambda} P(\lambda) S_1(\lambda) d\lambda$$

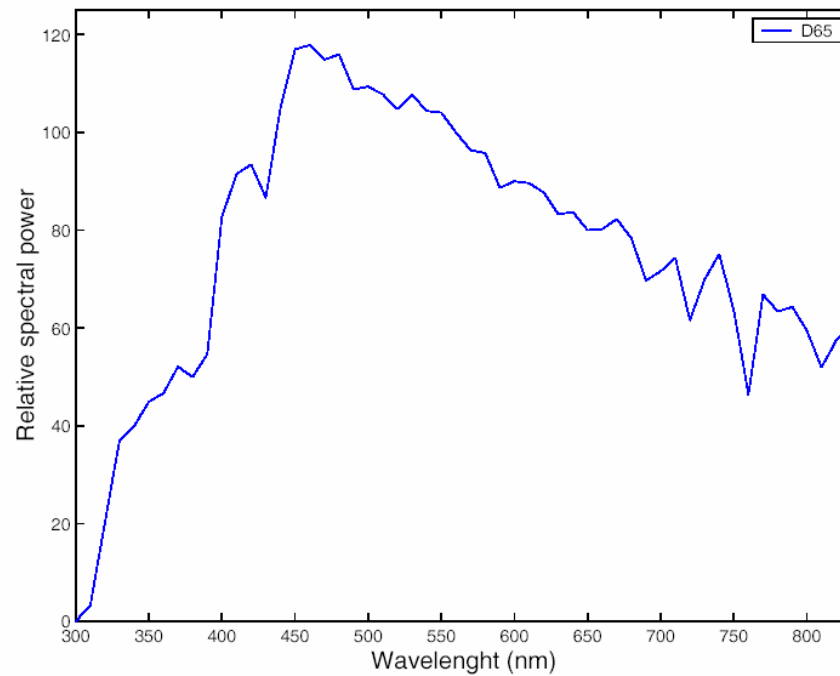
$$G_c = k_2 \int_{\lambda} P(\lambda) S_2(\lambda) d\lambda$$

$$B_c = k_3 \int_{\lambda} P(\lambda) S_3(\lambda) d\lambda$$

relative to the camera

# Reference white

- The reference white is the light source that is chosen to approximate the white light
  - D65, D50





# Reference white

- The reference white,  $E(\lambda)$ , will be given the maximum tristimulus values in all channels ( $R=G=B=255$ )
- The numerical values of the R,G,B coordinates of a generic PSD  $P(\lambda)$  will depend on the choice of  $E(\lambda)$

$$R_{Ec} = k_1 \int_{\lambda} E(\lambda) S_1(\lambda) d\lambda = 255$$

$$G_{Ec} = k_2 \int_{\lambda} E(\lambda) S_2(\lambda) d\lambda = 255 \rightarrow k_1, k_2, k_3$$

$$B_{Ec} = k_3 \int_{\lambda} E(\lambda) S_3(\lambda) d\lambda = 255$$

# RGB tristimulus values

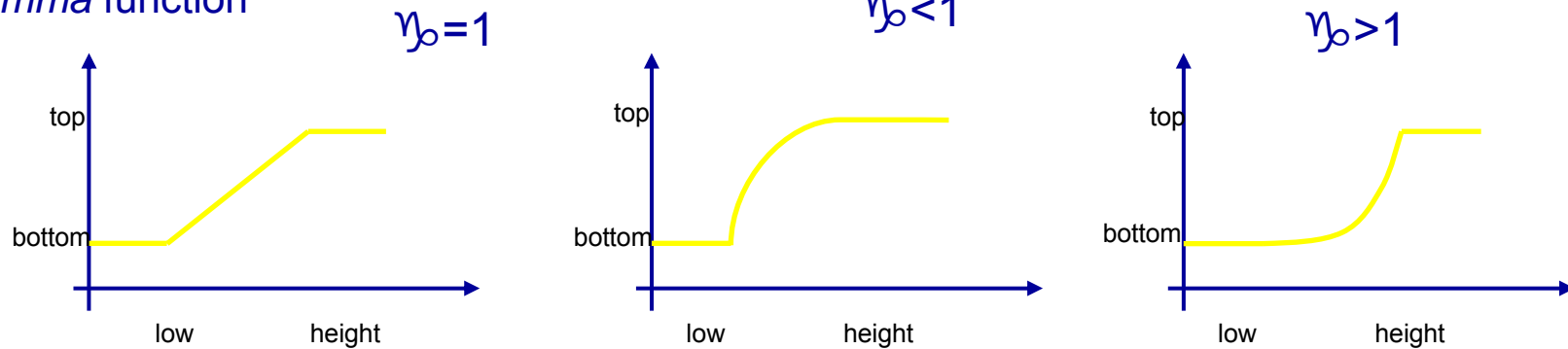
- The R,G,B coordinates does not have an absolute meaning, as their value depend on
  - The spectral sensitivity of the sensors that are used in the capture device
  - The reference white
- Thus, R,G,B values of the same physical stimulus (image) acquired with different cameras are different, in general
- Gamut: set of colors that is “manageable” by the device
  - Acquisition devices: set of colors that are represented by the device
  - → gamut mapping

# RGB model

- Similar considerations apply to rendering devices: the rendering of a color with given tristimulus coordinates (R,G,B) will depend on
  - The spectral responses of the emitters
    - phosphors for a CRT
    - color filters in a LCD
  - The calibration of the device
    - As for the acquisition devices, the color corresponding to the rendered white must be set
    - To define the entire gamut for a monitor, you only need mark the points on the diagram that represent the colors the monitor actually produces. You can measure these colors with either a colorimeter or a photospectrometer along with software that ensures the monitor is showing 100 percent red for the red measurement, 100 percent green for the green measurement, and 100 percent blue for the blue measurement.
  - The linearity of the monitor transfer function (gamma)

# Gamma function

Gamma function

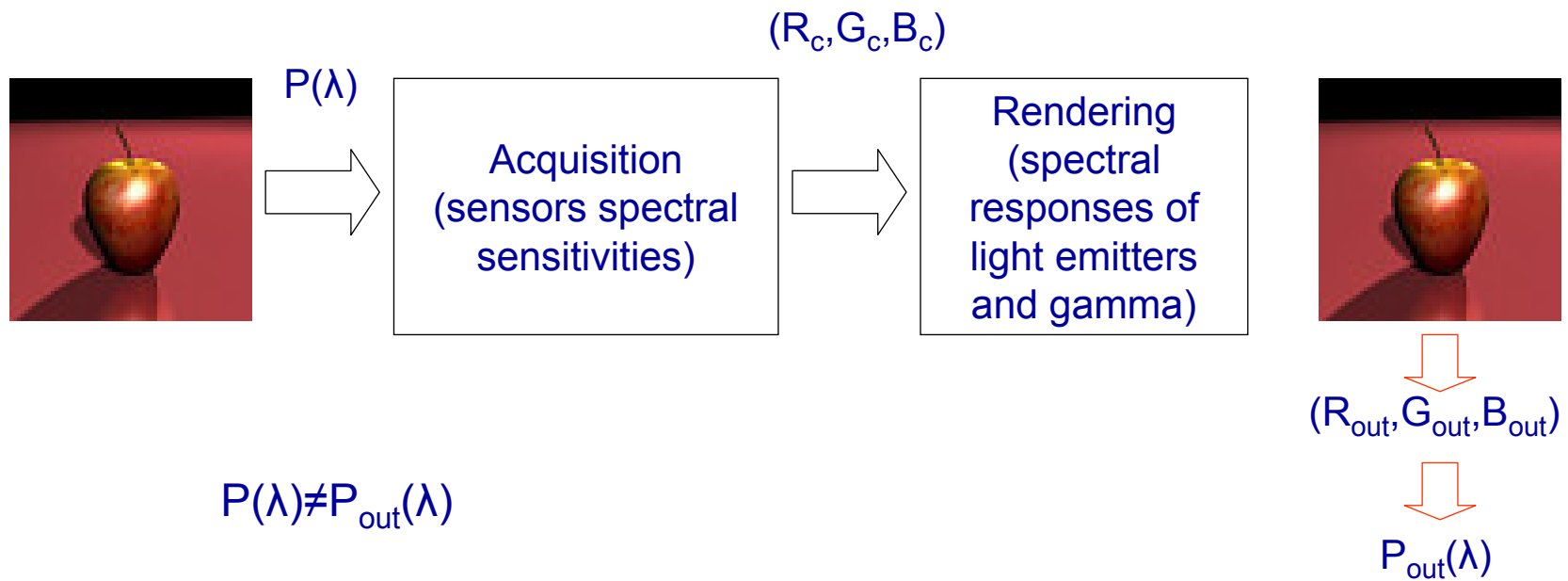


- Typical CRT monitors: gamma=2.2
- The non-linearity of the monitor can be compensated by non-uniform scaling of the RGB coordinates at input (*RGB linearization*)
- This led to the definition of the sRGB color model

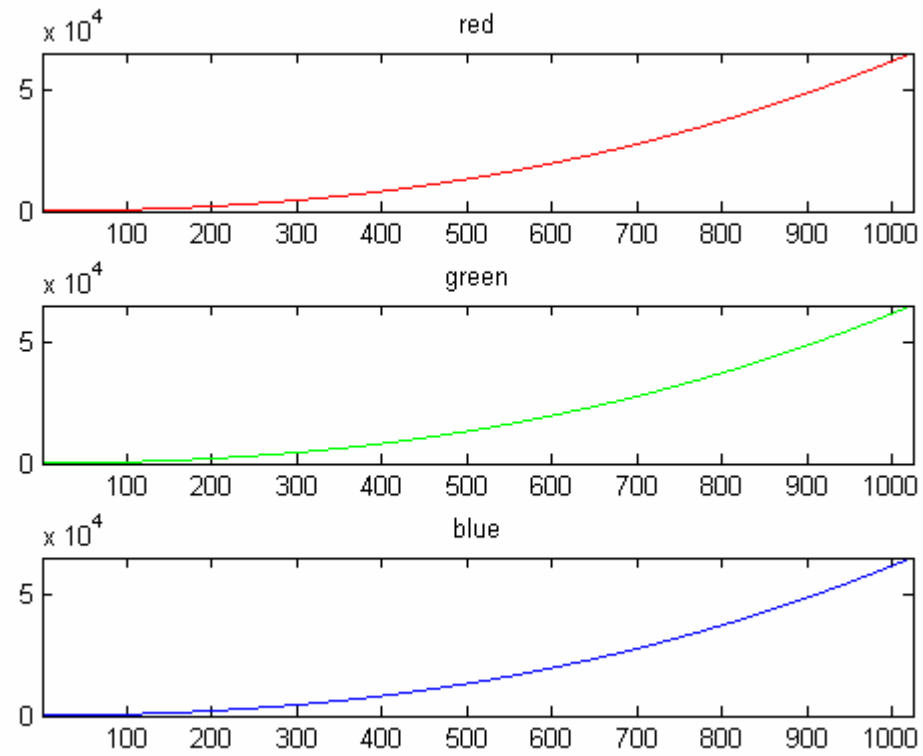
# RGB model: rendering ex.

- The RGB values depend on the phosphores coordinates
  - Different for the different reproduction media (CRT, television displays)
  - Example:
    - Red phosphore:  $x=0.68, y=0.32$
    - Green phosphore:  $x=0.28, y=0.60$
    - Blue phosphore:  $x=0.15, y=0.07$
  - Given the  $x,y$  coordinates of the phosphores, the reference white point and the illuminant (D65), the RGB coordinates can be calculated
  - Calibration
    - the  $R=G=B=100$  points must match in appearance with the white color as observed by 10 deg observer under the D65 illuminant
    - The brightness of the three phosphores is non linear with the RGB values. A suitable correction factor must be applied (Gamma correction)

# RGB model

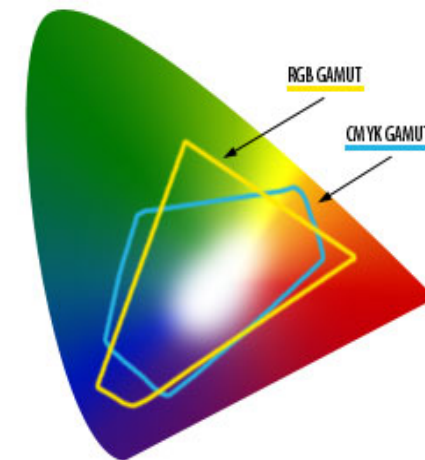


# sRGB



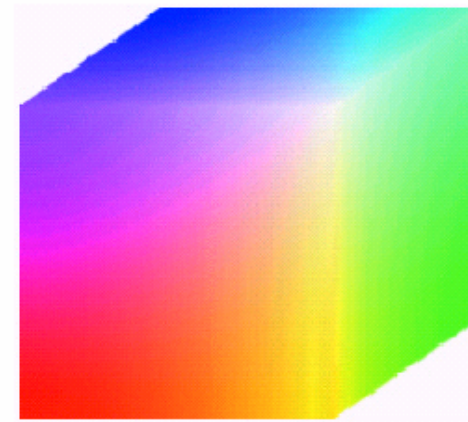
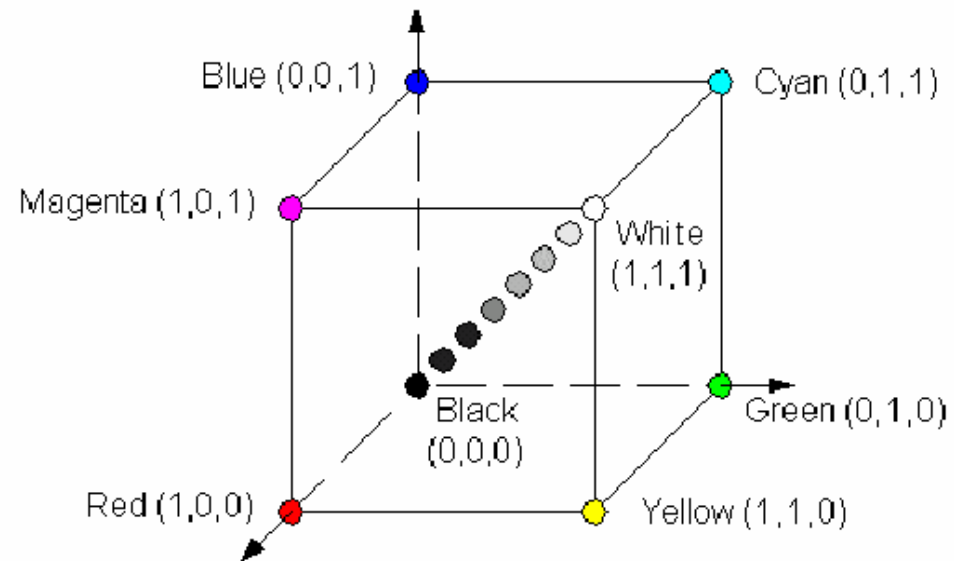
# sRGB

- RGB specification that is based on the average performance of personal computer displays. This solution is supported by the following observations:
  - Most computer monitors are similar in their key color characteristics - the phosphor chromaticities (primaries) and transfer function → RGB primaries,  $\gamma$  value
  - Reference viewing environments are defined for standard RGB
    - Luminance level 80 cd/m<sup>2</sup>
    - Illuminant White  $x = 0.3127$ ,  $y = 0.3291$  (D65)
    - Image surround 20% reflectance
    - Encoding Ambient Illuminance Level 64 lux
    - Encoding Ambient White Point  $x = 0.3457$ ,  $y = 0.3500$  (D50)
    - Encoding Viewing Flare 1.0%
    - Typical Ambient Illuminance Level 200 lux
    - Typical Ambient White Point  $x = 0.3457$ ,  $y = 0.3500$  (D50)
    - Typical Viewing Flare 5.0%



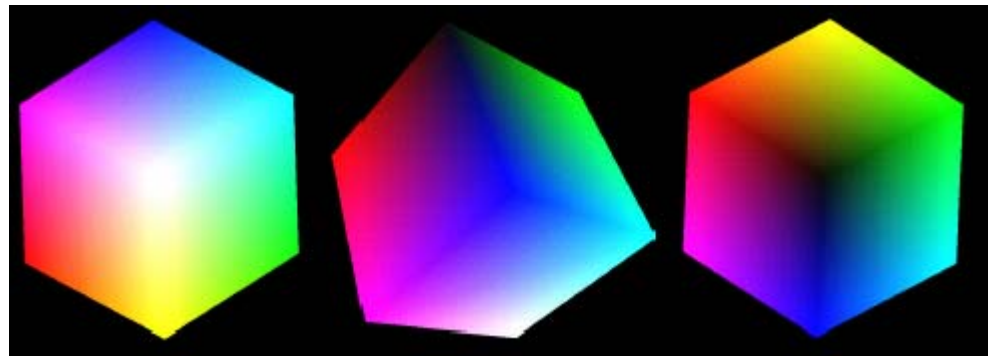


# RGB model



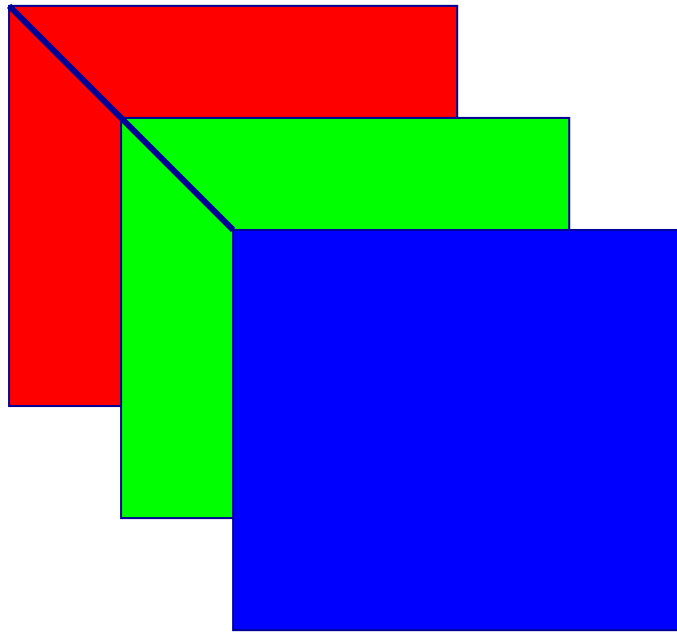
# RGB model

- Normalized values in  $[0,1]$  (chromaticity coordinates) may be convenient for some applications
- For a given device, the set of manageable colors lies inside the RGB cube
  - The R,G,B values must be represented as CIE coordinates

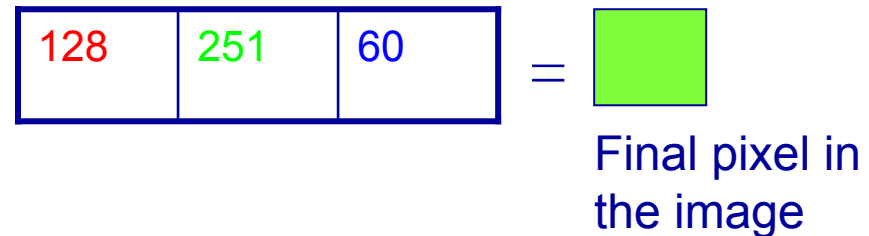


# RGB model

(0,0)



A single pixel consists of three components.

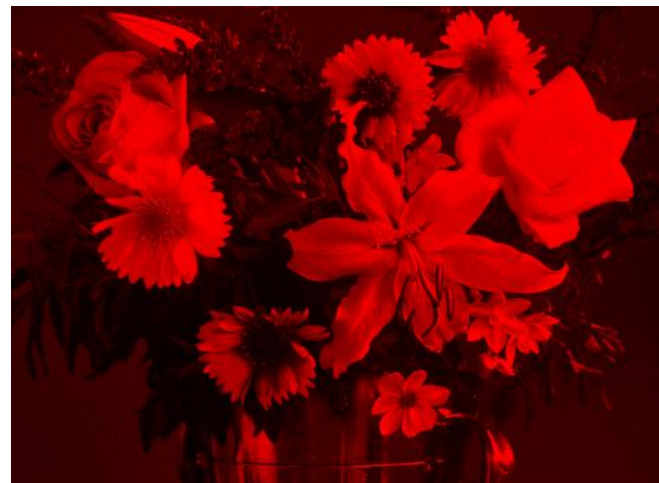


If R,G, and B are represented with 8 bits (24-bit RGB image), the total number of colors is  $256^3=16,777,216$

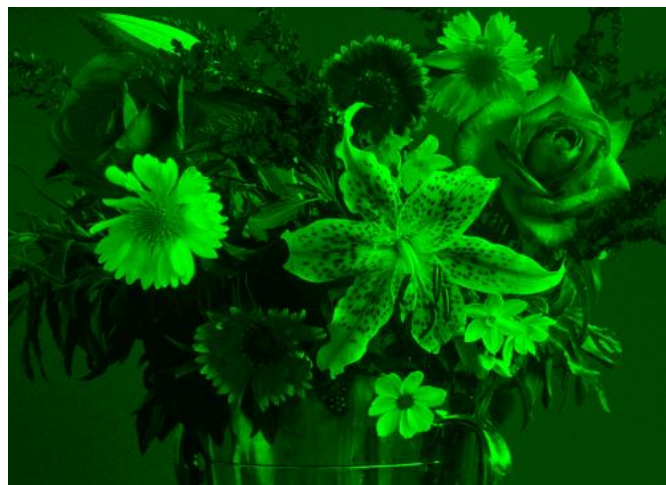
## Example RGB



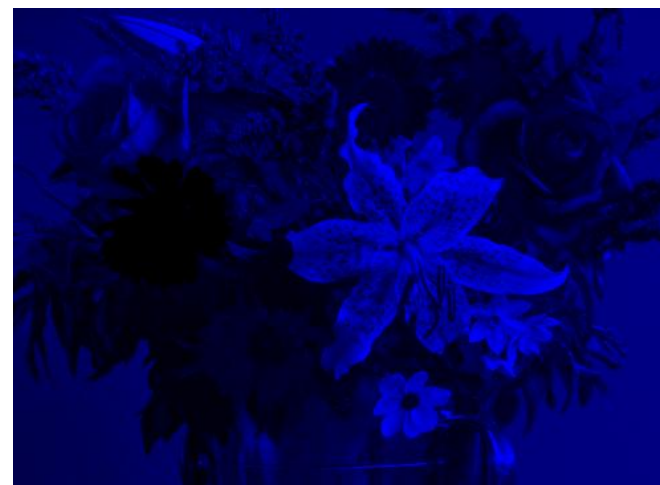
Original Image



R-Component



G-Component



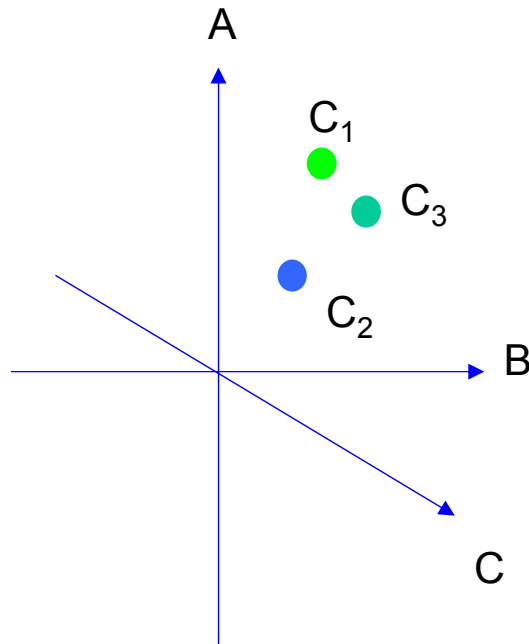
B-Component

# Uniform color scales

Attributes: hue, saturation (chroma), brightness (lightness)

- **Brightness**
  - The attribute of a visual sensation according to which a visual stimulus appears to be more or less “intense”, or to emit more or less light
  - Ranges from “bright” to “dim”
- **Lightness**
  - The attribute of a visual sensation according to which a visual stimulus appears to be more or less “intense”, or to emit more or less light *in proportion to that emitted by a similarly illuminated area perceived as “white”*
  - Relative brightness
  - Ranges from “light” to “dark”
- **Colorfulness**
  - The attribute of a visual sensation according to which a visual stimulus appears to be more or less “chromatic”
- **Chroma**
  - The attribute of a visual sensation which permits a judgment to be made of the degree to which a chromatic stimulus differs from an “achromatic” stimulus of the same brightness
- **Saturation**
  - The attribute of a visual sensation which permits a judgment to be made of the degree to which a chromatic stimulus differs from an “achromatic” stimulus regardless of their brightness
- Chroma and saturation are often considered as equivalent

# Perceptually uniform color models



Perceptual distance:

- Scaling the perceptual similarity among color samples
  - C<sub>1</sub> is most similar to C<sub>3</sub> than it is to C<sub>2</sub>

Measurable distance

- Metric in the color space
  - Euclidean distance among the color samples

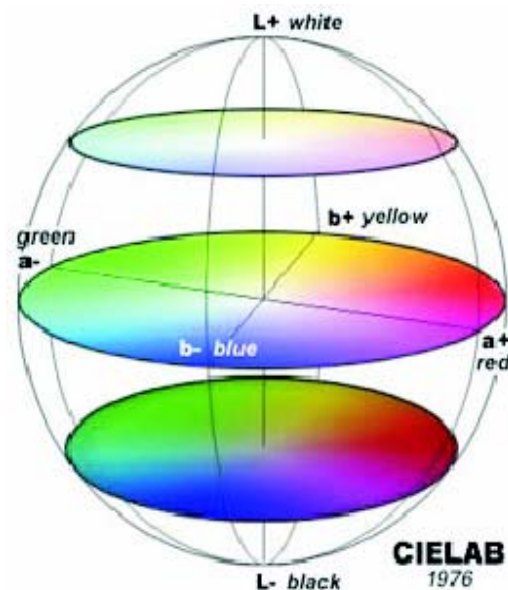
Does the perceptual distance match with the measurable distance among colors?

$$d(C_1C_3) \stackrel{?}{\leq} d(C_1C_2)$$

**Color models whose metric is representative of the perceptual distance are *perceptually uniform***

# Perceptually uniform Color models: Lab

CIE 1976 L\*a\*b\* (CIELAB)



$X_n, Y_n, Z_n$  : reference white

Tristimulus values for a nominally white object-color stimulus. Usually, it corresponds to the spectral radiance power of one of the CIE standard illuminants (as D65 or A), reflected into the observer's eye by a perfect reflecting diffuser. Under these conditions,  $X_n, Y_n, Z_n$  are the tristimulus values of the standard illuminant with  $Y_n=100$ .

Hint: the diffuse light (★ color) depends on both the physical properties of the surface and the illuminant

For:  $\frac{Y}{Y_n}, \frac{X}{X_n}, \frac{Z}{Z_n} \geq 0.01$

$$L^* = 116\left(\frac{Y}{Y_n}\right)^{1/3} - 16$$

$$a^* = 500\left[\left(\frac{X}{X_n}\right)^{1/3} - \left(\frac{Y}{Y_n}\right)^{1/3}\right]$$

$$b^* = 200\left[\left(\frac{Y}{Y_n}\right)^{1/3} - \left(\frac{Z}{Z_n}\right)^{1/3}\right]$$

otherwise

$$L^* = 116 \left[ f\left(\frac{Y}{Y_n}\right) - \frac{16}{116} \right]$$

$$a^* = 500 \left[ f\left(\frac{X}{X_n}\right) - f\left(\frac{Y}{Y_n}\right) \right]$$

$$b^* = 200 \left[ f\left(\frac{Y}{Y_n}\right) - f\left(\frac{Z}{Z_n}\right) \right]$$

$$f\left(\frac{Y}{Y_n}\right) = \begin{cases} \left(\frac{Y}{Y_n}\right)^{1/3} & \text{for } \frac{Y}{Y_n} > 0.008856 \\ 7.787\frac{Y}{Y_n} + \frac{16}{116} & \text{for } \frac{Y}{Y_n} \leq 0.008856 \end{cases}$$

# User-oriented CM

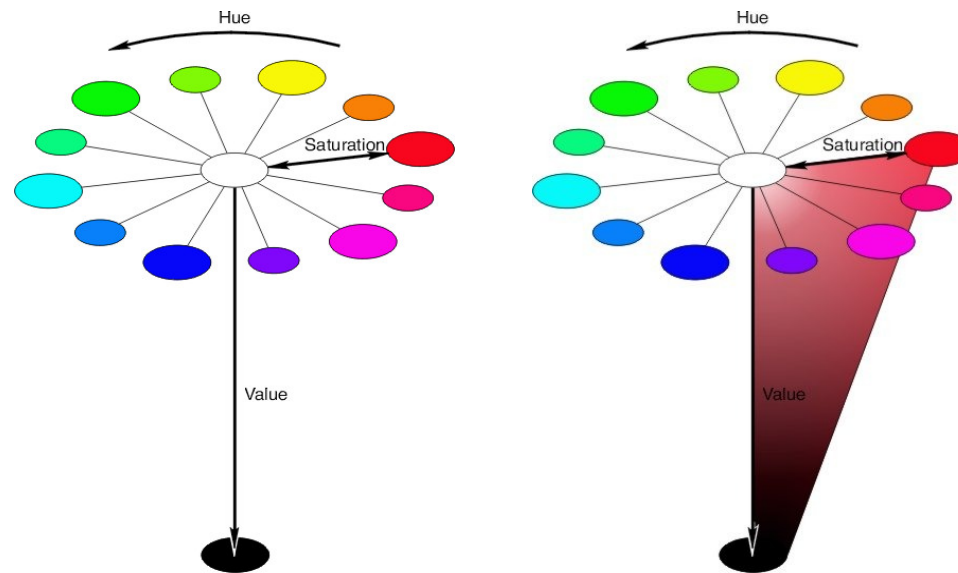
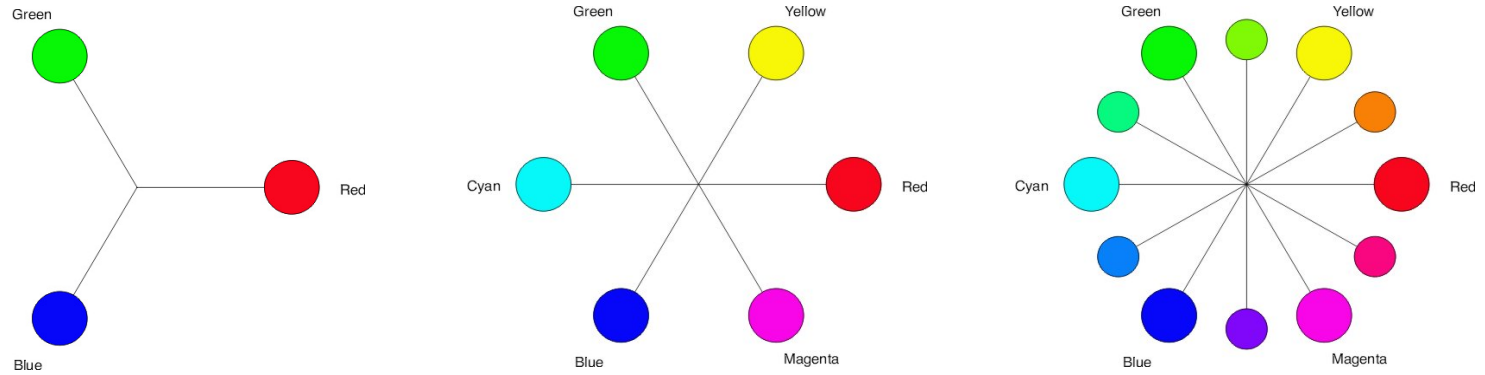
- HSV (Hue, Saturation, and Value). Sometimes variations include HSB (Brightness), HSL (Lightness/Luminosity), HIS (Intensity)
  - The hue of a color places it on the color wheel where the color spectrum (rainbow) is evenly spaced
  - The saturation or chroma of a hue defines its intensity
    - Decreasing the saturation via a contrast control adds gray.
  - The value of a hue defines how bright or dark a color is
  - They all are effectively the RGB space twisted so that the neutral diagonal becomes the lightness axis, the saturation the distance from the central lightness axis and the hue the position around the center.
  - The only difference between these models is the measurement of saturation, or the strength of the colour



# User-oriented CM

- Drawbacks
  - Singularities in the transform (such as undefined hue for achromatic points)
  - Sensitivity to small deviations of RGB values near the singularities
  - Numerical instability when operating on hue due to its angular nature

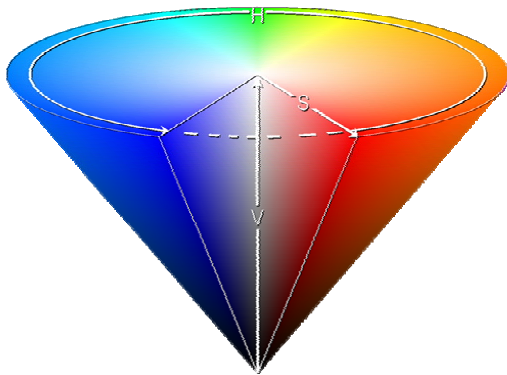
# User-oriented CM: HSV



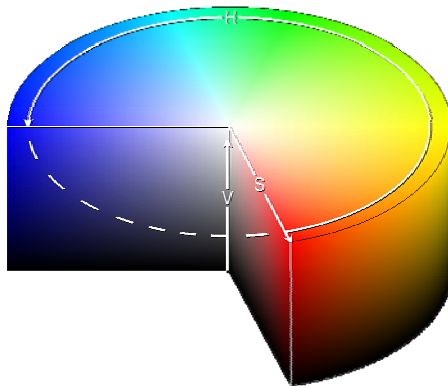
# HSV, HSL

Hue, Saturation, Value (Brightness)

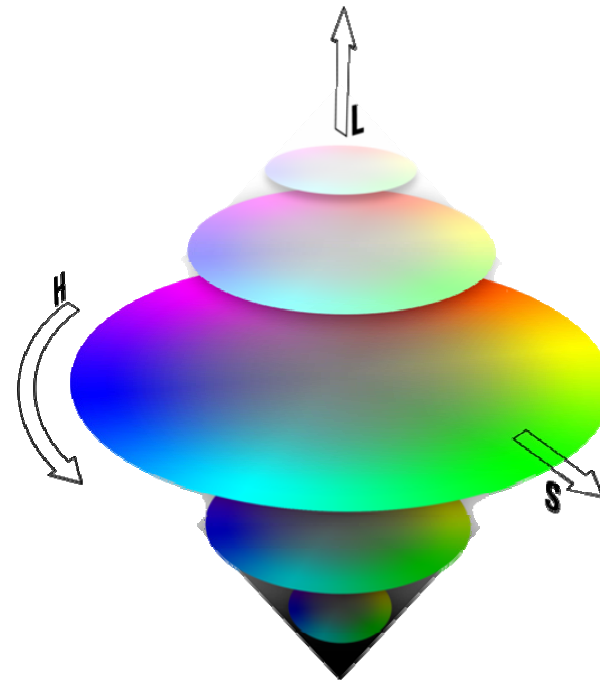
HSV cone



HSV cylinder



Hue, Saturation, Lightness

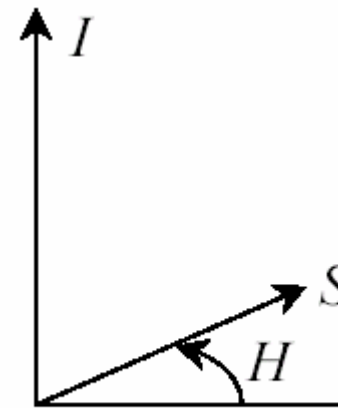


# HSI (HSV, HSL) Color Space

- Recall:
  - **Hue** is color attribute that describes a pure color
  - **Saturation** gives the measure to which degree the pure color is diluted by white light.
- 1. Intensity (Value or Lightness) component  $I$  (V,L), is decoupled from the chromaticity information!
- 2. Hue and saturation can be accessed independently from illumination

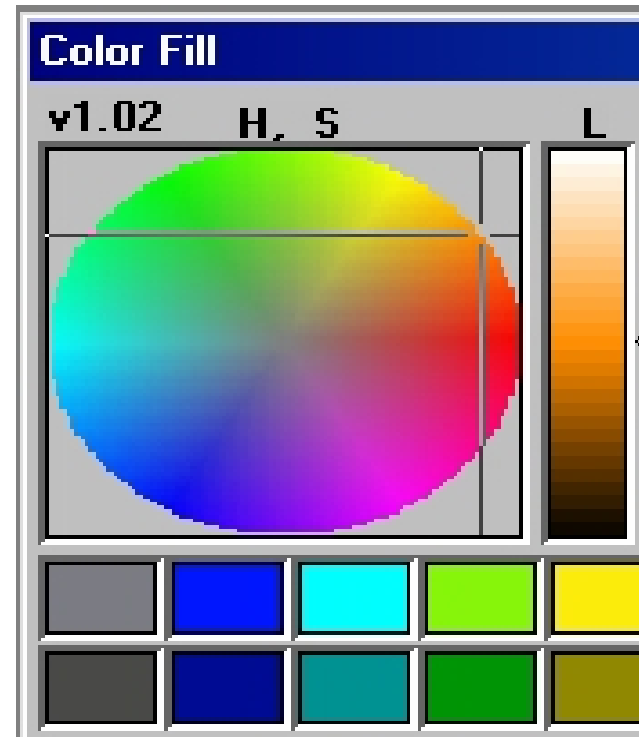
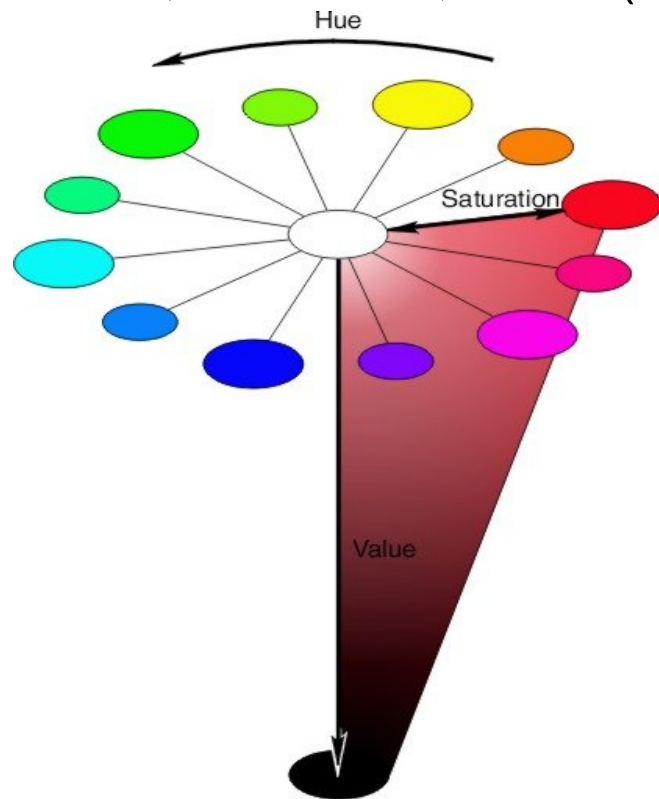
# HSI model

- Two values (H & S) encode *chromaticity*
- Convenient for *designing* colors
- Hue H is defined by an angle between 0 and  $2\pi$ :
  - “red” at angle of 0;
  - “green” at  $2\pi/3$ ;
  - “blue” at  $4\pi/3$
- Saturation S models the *purity* of the color
  - S=1 for a completely pure or saturated color
  - S=0 for a shade of “gray”



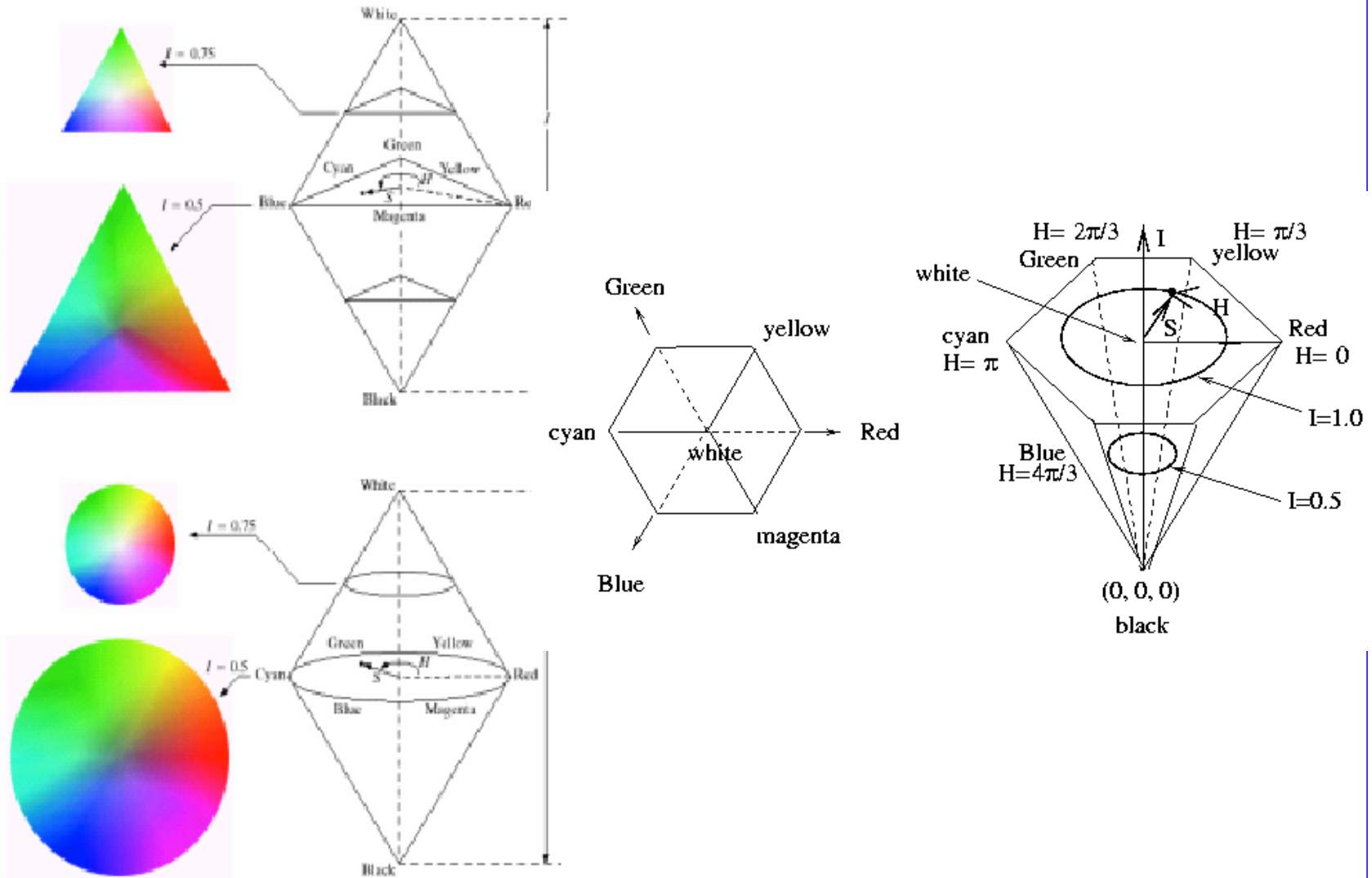
# HSI-like model

- Hue, Saturation, Value (HSV) model



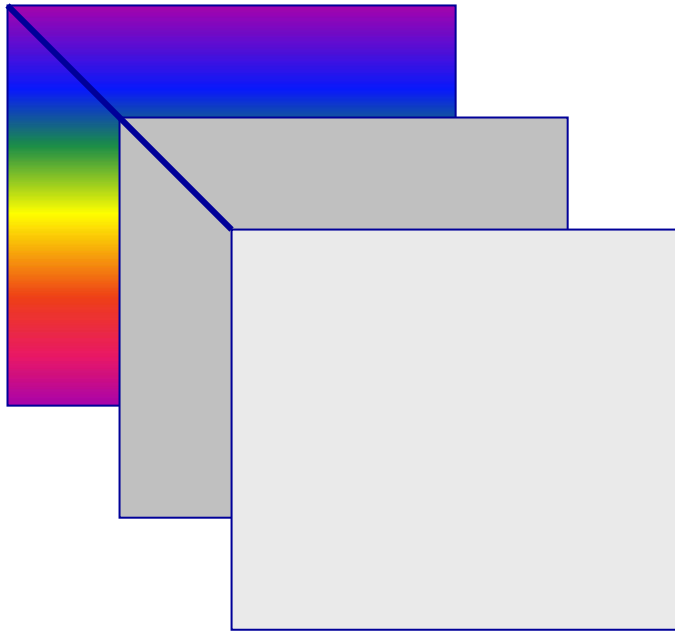
from [http://www2.ncsu.edu/scivis/lessons/colormodels/color\\_models2.html#saturation.](http://www2.ncsu.edu/scivis/lessons/colormodels/color_models2.html#saturation)

# Variations on the theme



# HSI Representation

(0,0)



A single pixel consists of three components.

Each pixel is a **Vector / Array**.

128	251	60
-----	-----	----

=



Pixel-Vector in  
the computer  
memory

Final pixel in  
the image

Caution! Sometimes pixels are not stored as vectors. Instead, first is stored the complete hue component, then the complete sat., then the intensity.



# HSI Examples

Original Image



Hue



Saturation



Intensity



## Editing saturation of colors



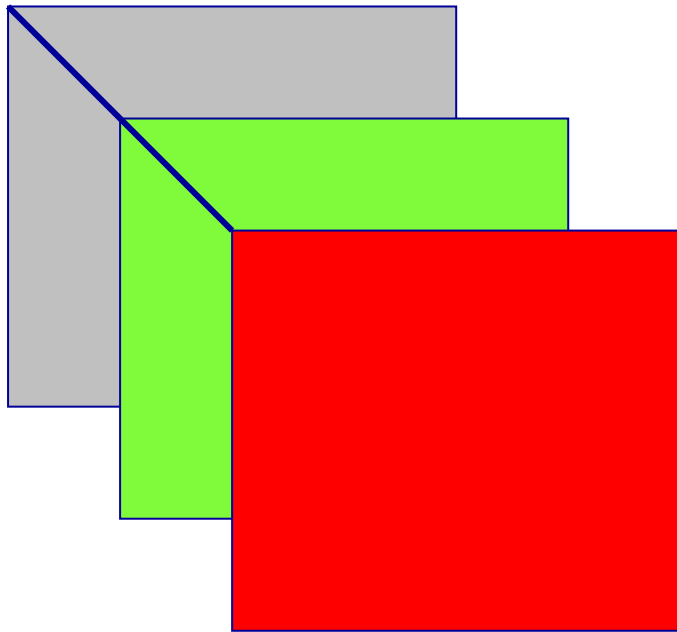
(Left) Image of food originating from a digital camera;  
(center) saturation value of each pixel decreased 20%;  
(right) saturation value of each pixel increased 40%.

# YUV Color model

- PAL TV standard
  - YCbCr similar, used in JPEG and MPEG
  - YIQ (similar) used in NTSC
- Color channels
  - Y: luminance
  - UV: chrominance. These are often downsampled exploiting the lower cutting frequency and sensitivity of the human visual system with respect to the luminance component

# YUV reppresentation

(0,0)



A single pixel consists of three components.  
Each pixel is a Vector / Array.

128	251	60
-----	-----	----



Pixel-Vector in  
the computer  
memory

Final pixel in  
the image

Same Caution as before applies here!



# YUV example

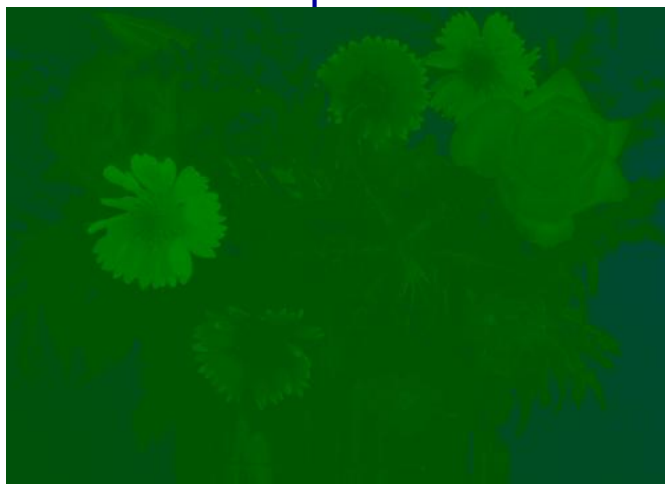
Original Image



Y-Component



U-Component



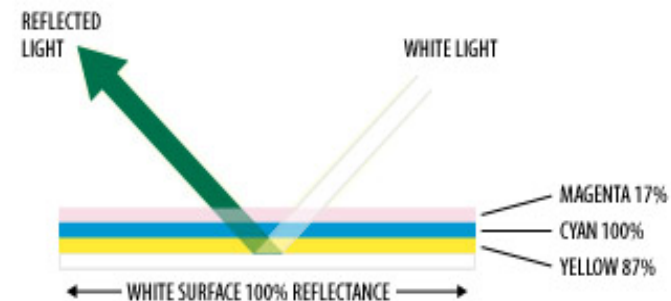
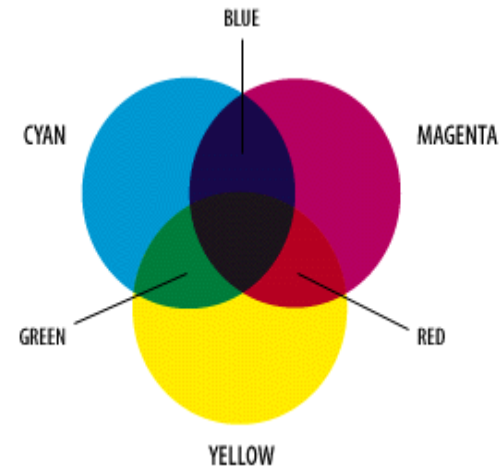
V-Component



# Device-oriented color models: CMY(K)

- Color subtraction
  - Cyan, Magents, Yellow filters
    - The Y filter removes B and transmits the R and G
    - The M filter removes G and transmits R and B
    - The C filter removes R and transmits G and B
  - Adjusting the transparency of these filters the amounts of R, G and B can be controlled

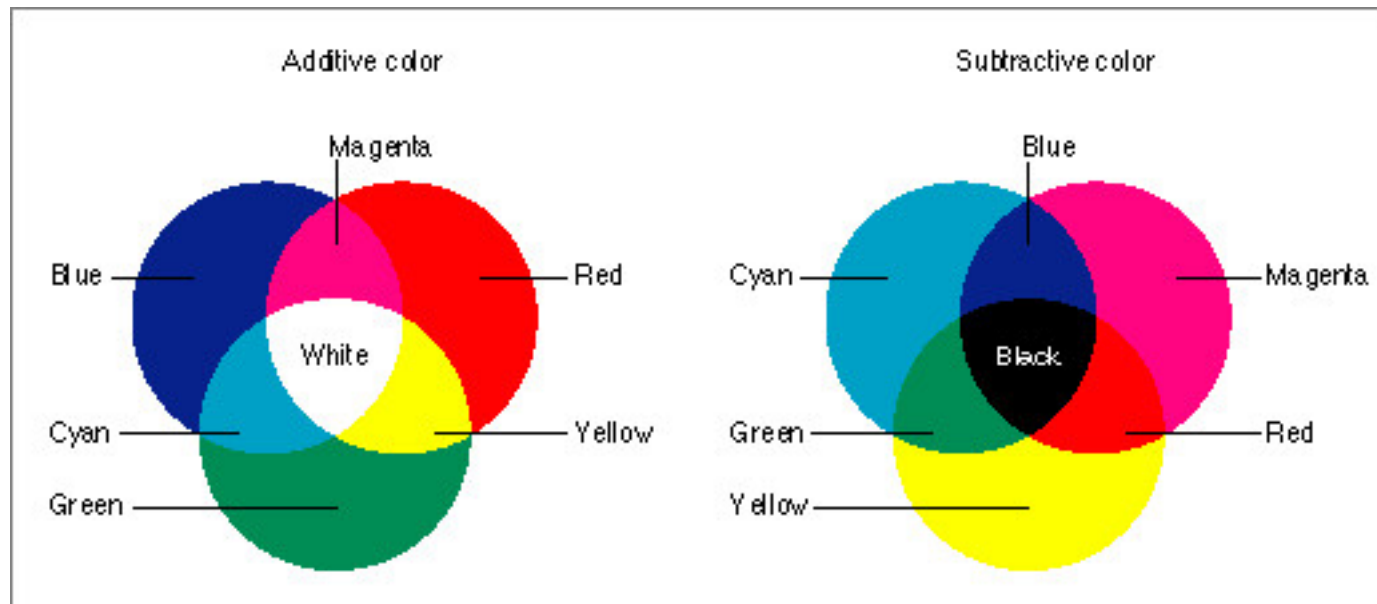
cyan=white-red  
magenta=white-green  
yellow=white-blue



# CMY model

- CMY (Cyan, Magenta, Yellow)
- Used in printing devices
- Subtractive color synthesis
- CMYK: adding the black ink
  - Equal amounts of C,M and Y should produce black, but in practice a dark brown results. A real black ink is then added to the printer

# CYM(K)



- cyan (C) absorbs red
- magenta (M) absorbs green
- yellow (Y) absorbs blue

$$\begin{bmatrix} C \\ M \\ Y \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} - \begin{bmatrix} R \\ G \\ B \end{bmatrix}$$



# Summary

- References
  - B. Wandell, “Foundations of visions”
  - Wyszecki&Stiles, “Color science, concepts, methods, quantitative data and formulae”, Wiley Classic Library
  - D. Malacara, “Color vision and colorimetry, theory and applications”, SPIE Press