

Reliable Systems Engineering

Tom Henzinger

EPFL

1. What do we do?
2. Why do we do it?
3. How do we do it?

We catch bugs.



We catch bugs.



bug *n* an unexpected defect, fault, flaw, or imperfection ⟨the software is full of ~s⟩

Windows

An exception 06 has occurred at 0028:C11B3ADC in VxD DiskTSD(03) + 00001660. This was called from 0028:C11B40C8 in VxD voltrack(04) + 00000000. It may be possible to continue normally.

- * Press any key to attempt to continue.
- * Press CTRL+ALT+RESET to restart your computer. You will lose any unsaved information in all applications.

Press any key to continue



June 4, 1996

The European Ariane 5 rocket explodes 40 s into its maiden flight due to a software bug.



1997	Mars Rover loses contact
1999	Mars Climate Orbiter is lost
1999	Mars Polar Lander is lost
2004	Mars Rover freezes



August 14, 2003

A programming error has been identified as the cause of the Northeast power blackout. The failure occurred when **multiple computer systems trying to access the same information at once** got the equivalent of busy signals.

[Associated Press]

Price tag: \$ 6-10 billion

ISAT GeoStar 45
23:15 EST 14 Aug. 2003

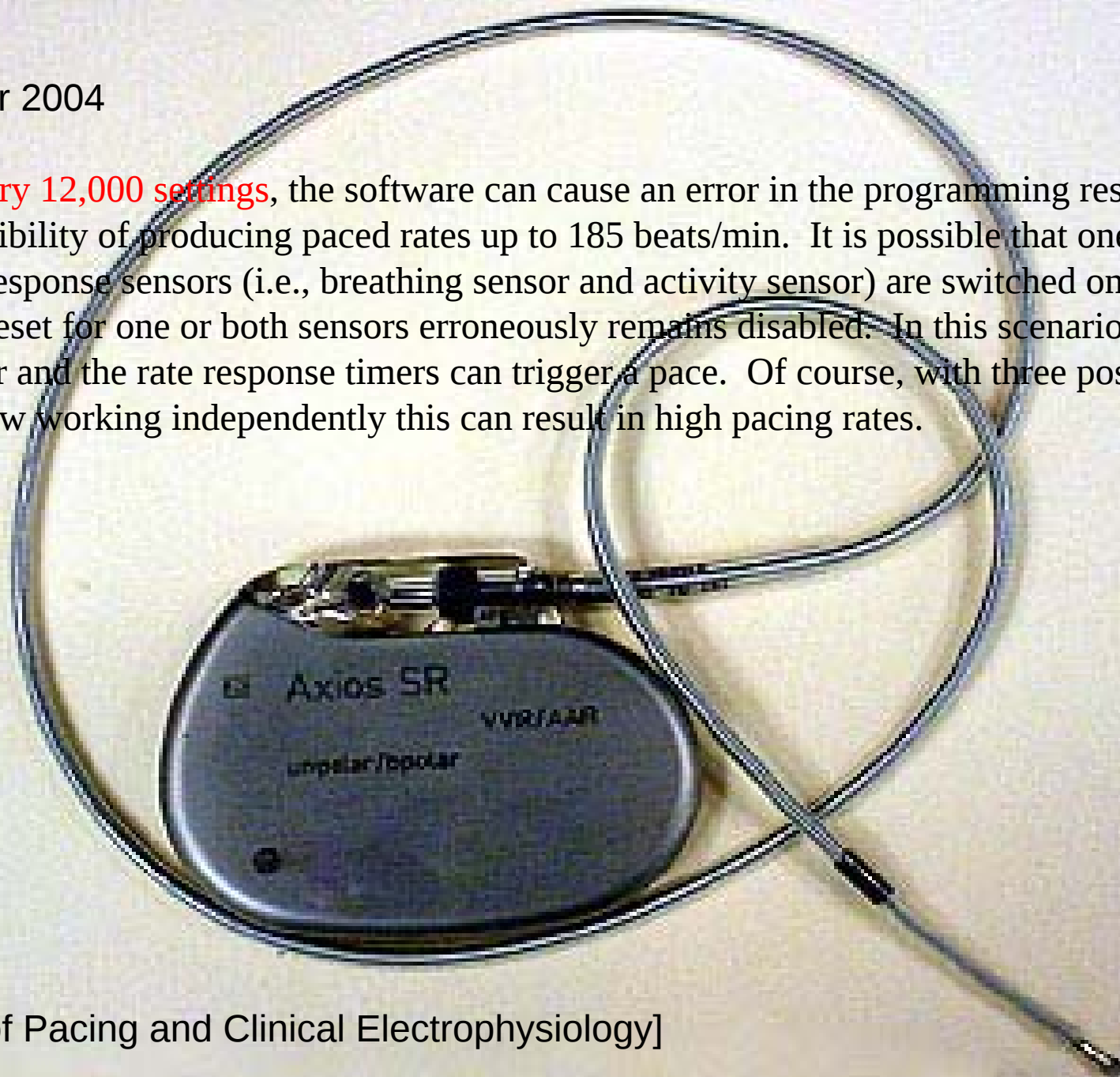


2002 study by NIST:

Software bugs cost the US economy \$ 60 billion annually
(0.6 % of GDP).

December 2004

In **1 of every 12,000 settings**, the software can cause an error in the programming resulting in the possibility of producing paced rates up to 185 beats/min. It is possible that one or both rate response sensors (i.e., breathing sensor and activity sensor) are switched on, but the timer reset for one or both sensors erroneously remains disabled. In this scenario, the clock timer and the rate response timers can trigger a pace. Of course, with three possible triggers now working independently this can result in high pacing rates.



[Journal of Pacing and Clinical Electrophysiology]



Postbank

January 1-7, 2002

Ganz ohne Geheimzahl konnten Postbank-Kunden bis Montag mit ihrer Sparcard unbegrenzt Geld abheben. “Wir haben bereits nach wenigen Tagen den Fehler bei der neu installierten Software bemerkt und korrigiert. Wir wissen nur von einem einzigen Fall in Hamburg, wo der Softwarefehler zufaellig entdeckt wurde. Der Betroffene muss das abgehobene Geld zurueckgeben.”

[Sueddeutsche Zeitung]



Boeing could not assemble and integrate the fly-by-wire system until it solved problems with the databus and the flight management software. Solving these problems took more than a year longer than Boeing anticipated. In April, 1995, the FAA certified the 777 as safe.

Total development cost:	\$ 3 billion
Software integration and validation cost:	one third of total

August 2005



Gerardo Dominguez/zrh.airlinerpictures.net

As a Malaysia Airlines jetliner cruised from Perth, Australia, to Kuala Lumpur, Malaysia, one evening last August, it suddenly took on a mind of its own and zoomed 3,000 feet upward. The captain disconnected the autopilot and pointed the Boeing 777's nose down to avoid stalling, but was jerked into a steep dive. He throttled back sharply on both engines, trying to slow the plane.

Instead, the jet raced into another climb. The crew eventually regained control and manually flew their 177 passengers safely back to Australia.

August 2005



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Investigators quickly discovered the reason for the plane's roller-coaster ride 38,000 feet above the Indian Ocean. A defective software program had provided incorrect data about the aircraft's speed and acceleration, confusing flight computers.

August 2005



Gerardo Dominguez/zrh.airlinerpictures.net

With well over five million lines of code used on the latest jetliners, it's increasingly difficult to detect and fix software problems before they surprise pilots. Plane makers are accustomed to testing metals and plastics under almost every conceivable kind of extreme stress, but **it's impossible to run a big computer program through every scenario** to detect the bugs that invariably crop up.

August 2005



Gerardo Dominguez/zrh.airlinerpictures.net

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Specialists say the biggest problems in aviation software don't stem from bugs in the code of a single program but rather from the **interaction between two different parts of a plane's computer system**. In extreme cases, foul-ups can lead to sudden loss of control, sometimes **not showing up until years** after aircraft are introduced into service. Malaysia Airlines Flight 124 is a case in point. Boeing's 777 jets started service in 1995 and had never experienced a similar emergency before.

August 2005



Gerardo Dominguez/zrh.airlinepictures.net

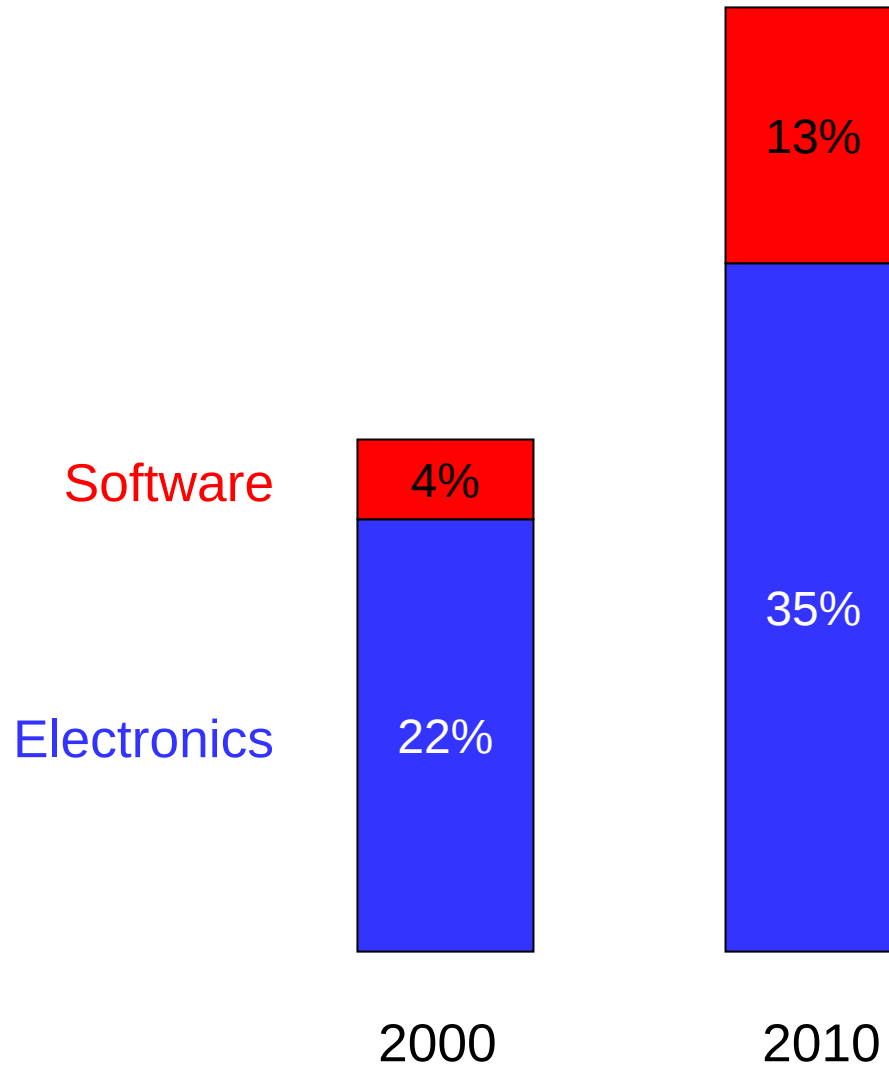
Soon after the incident, Boeing issued a safety alert advising that, in such circumstances, pilots should immediately disconnect the autopilot and might need to exert an unusually strong force on the controls for as long as two minutes to regain normal flight.

[Wall Street Journal; May 30, 2006]

500 horses
200 processors



Production Cost of Automobiles



December 4, 2006

The NHTSA said DaimlerChrysler is recalling 128,000 Pacifica sports utility vehicles because of a problem with the software governing the fuel pump and power train control. The defect could cause the engine to stall unexpectedly.

[Washington Post]



It's the Software, Stupid!

The value is in the software:

Microsoft is one of the three most valuable companies in the world.

It's the Software, Stupid!

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Microsoft is one of the three most valuable companies in the world.

The bugs are in the software:

What is more likely to crash: your modem or your browser?

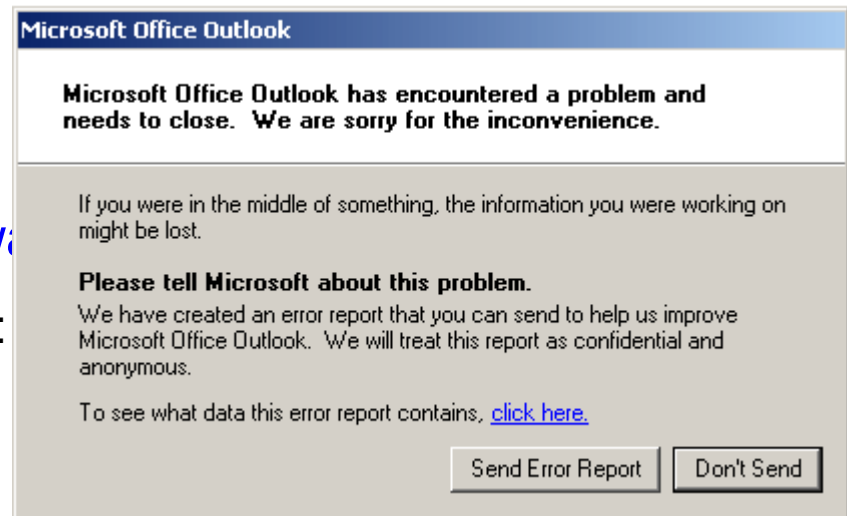
It's the Software, Stupid!

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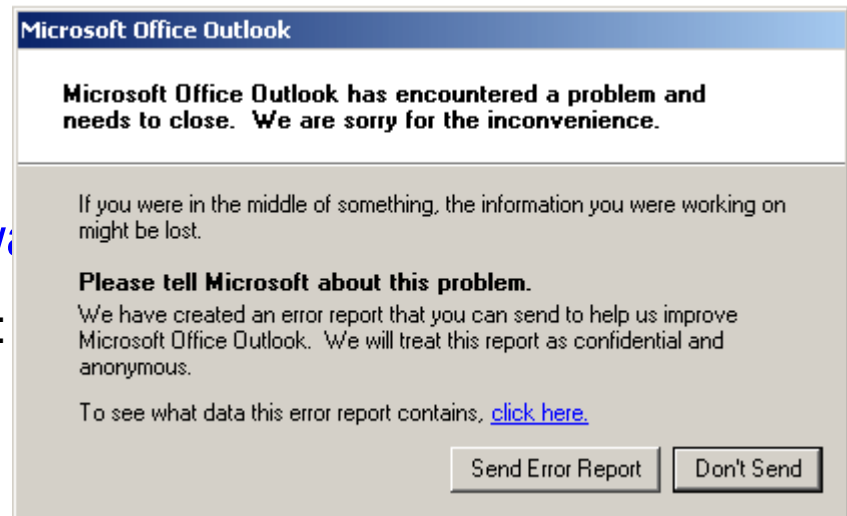
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It's the Software, Stupid!

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The challenges are in the software:

Is it that no smart people go into software engineering,
or is building software really *that* difficult?

Software truly is the most complex artifact we build routinely.
It's not surprising we rarely get it right.

Between 10^{69} and 10^{81}
atoms in the universe.



Between 10^{69} and 10^{81}
atoms in the universe.

10 MB cache >
 $10^{20,000,000}$ states.

Complexity Management in Engineering

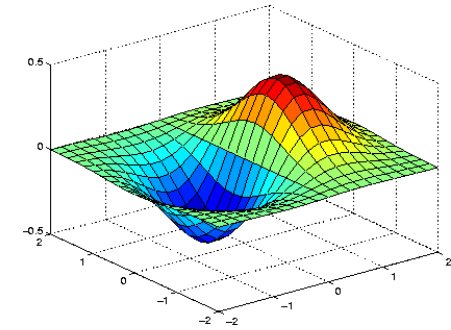


Build & test

System

Bridge
Aircraft
etc.

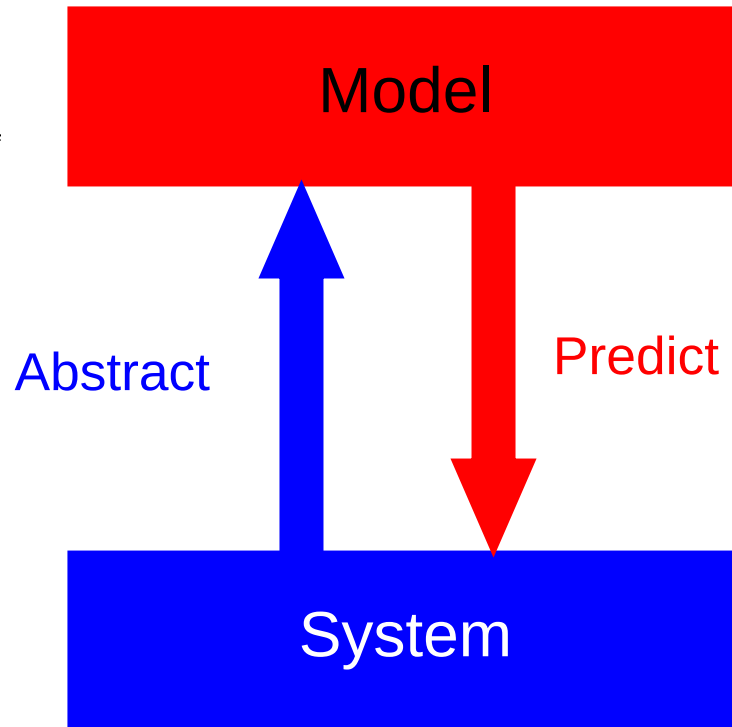
Complexity Management in Engineering



Calculate



Build & test



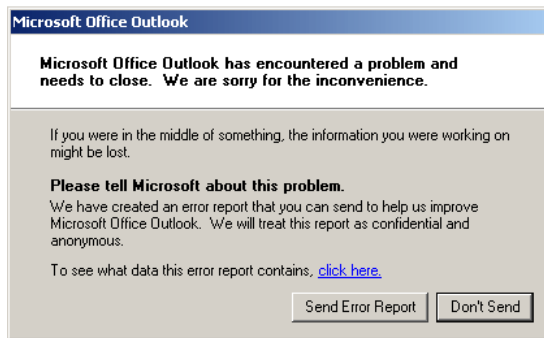
Applied
Mathematics

Bridge
Aircraft
etc.



Uptime: 123 years

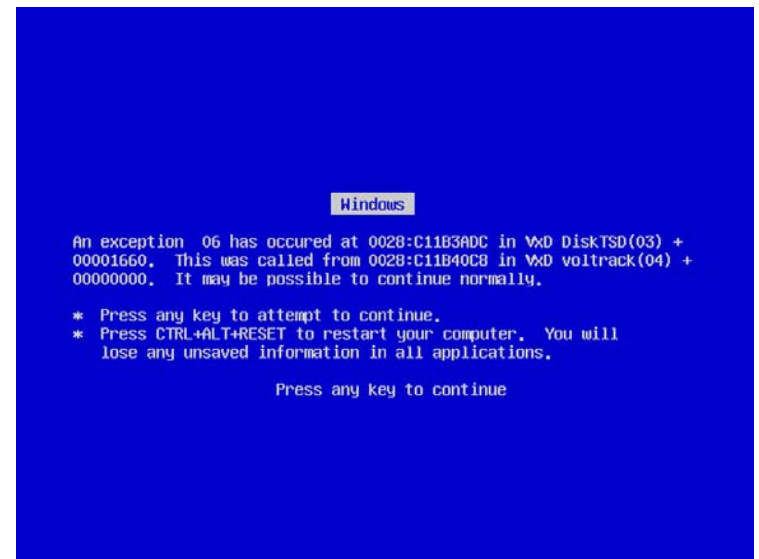
Complexity Management in Engineering



Build & test

System

Bridge
Aircraft
Software



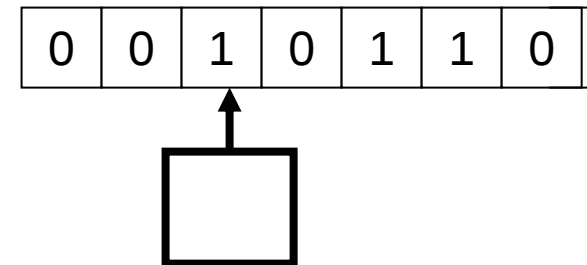
So, why don't we have a mathematics for building software?



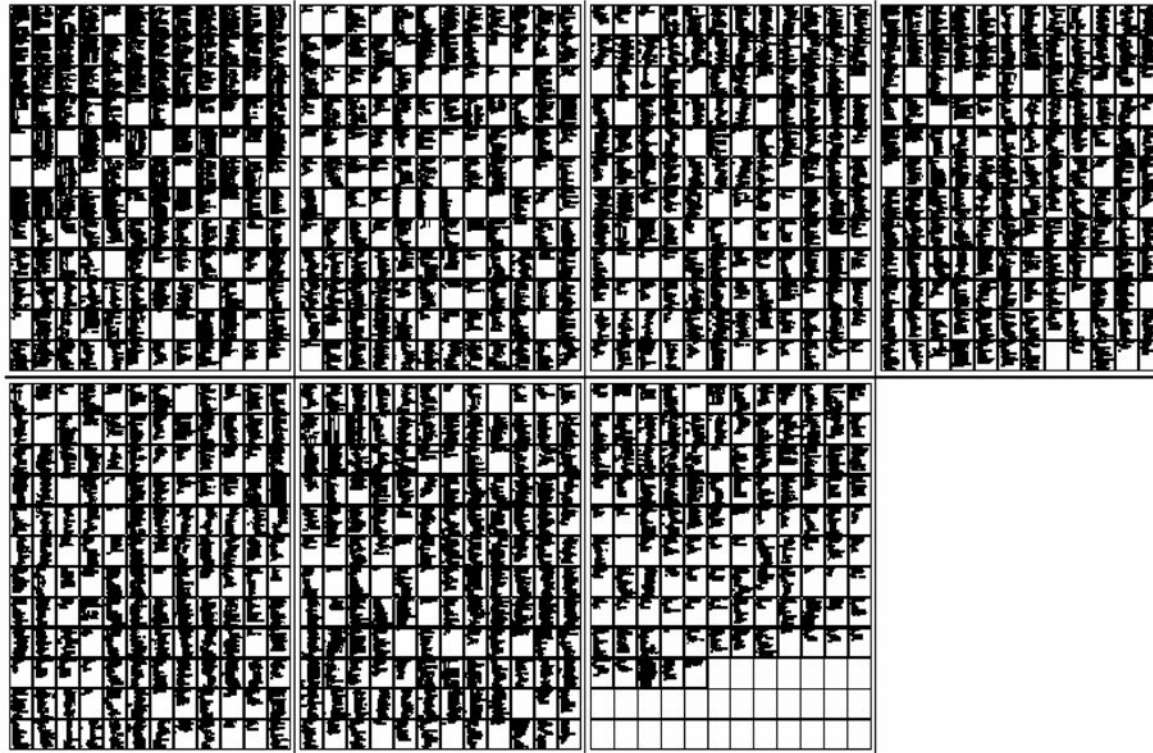
So, why don't we have a mathematics for building software?

We do, but it's not continuous.

- sensitive against perturbations
- difficult to overengineer
- difficult to abstract

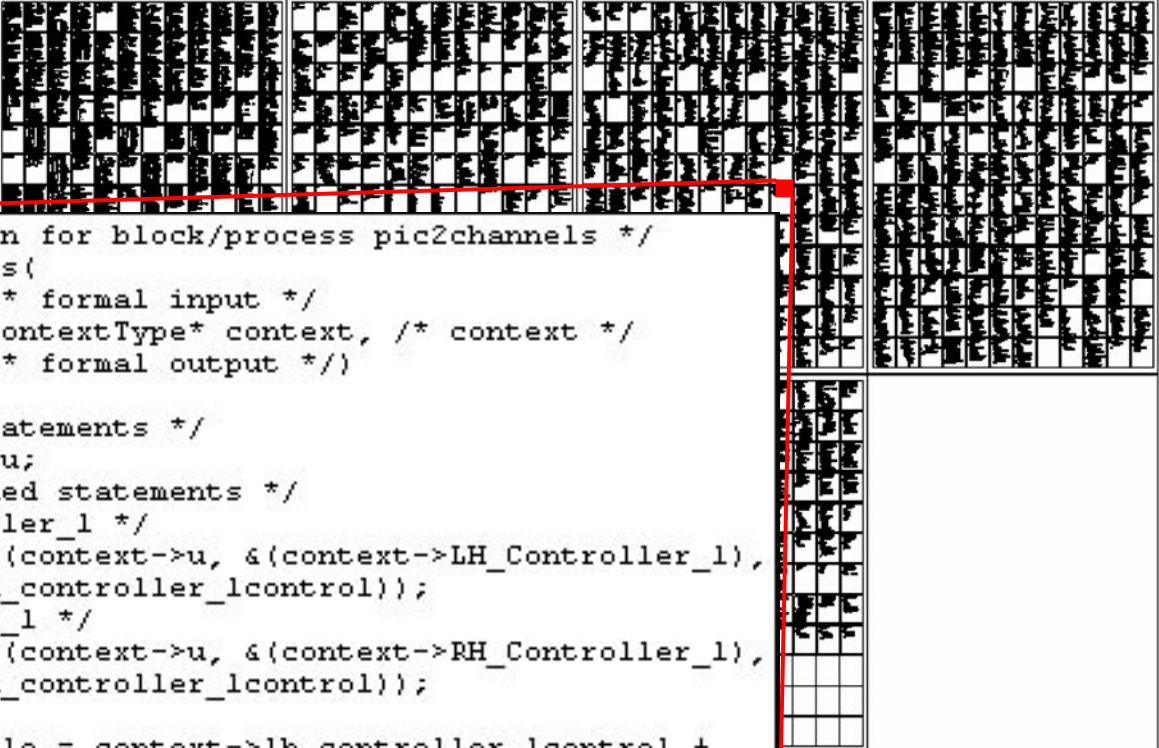


A Program



kbfilter.c
12,000 lines of code

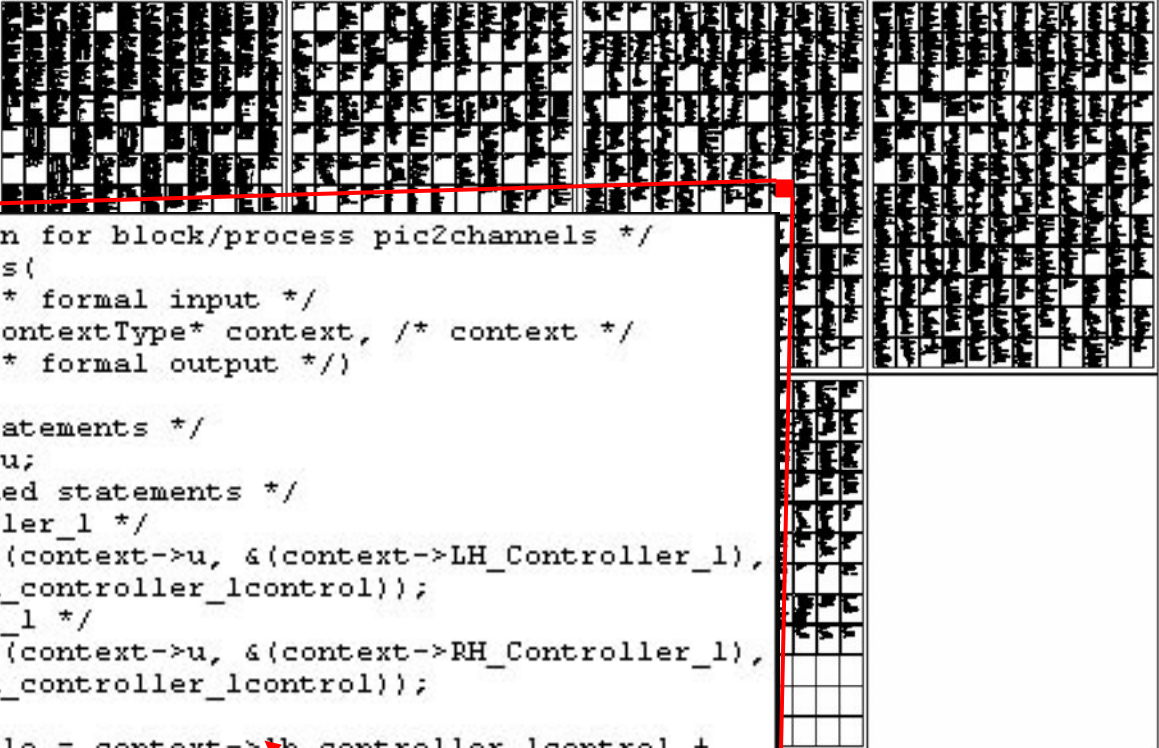
A Program



```
/* implementation for block/process pic2channels */
void pic2channels(
    realType u, /* formal input */
    pic2channelsContextType* context, /* context */
    realType* y /* formal output */)
{
    /* implied statements */
    context->u = u;
    /* user-defined statements */
    /* LH_Controller_1 */
    lh_controller(context->u, &(context->LH_Controller_1),
        &(context->lh_controller_lcontrol));
    /* RH_Controller_1 */
    rh_controller(context->u, &(context->RH_Controller_1),
        &(context->rh_controller_lcontrol));
    /* sum_1 */
    context->sum_lo = context->lh_controller_lcontrol +
        context->rh_controller_lcontrol;
    /* copy */
    context->y = context->sum_lo;
    /* implied statements */
    *y = context->y;
}
```

kbfilter.c
12,000 lines of code

A Program

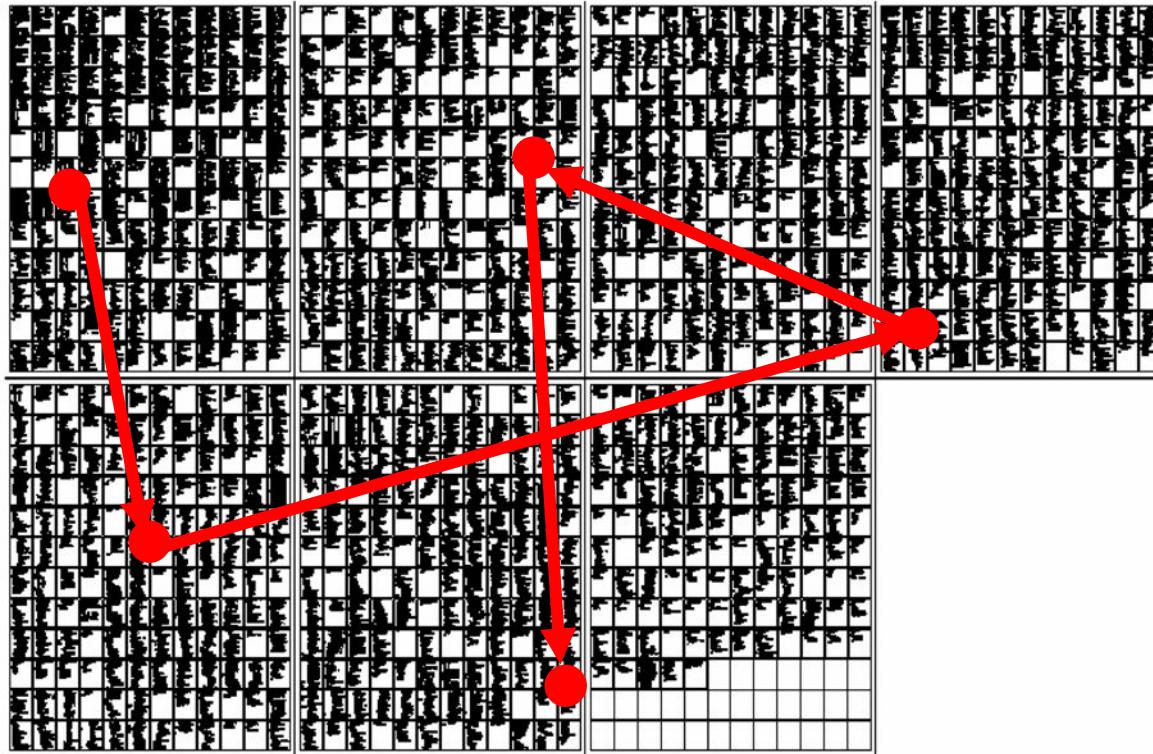


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/* implementation for block/process pic2channels */
void pic2channels(
    realType u, /* formal input */
    pic2channelsContextType* context, /* context */
    realType* y /* formal output */)
{
    /* implied statements */
    context->u = u;
    /* user-defined statements */
    /* LH Controller_1 */
    lh_controller(context->u, &(context->LH_Controller_1),
        &(context->lh_controller_lcontrol));
    /* RH Controller_1 */
    rh_controller(context->u, &(context->RH_Controller_1),
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    /* sum_1 */
    context->sum_lo = context->lh_controller_lcontrol +
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}
```



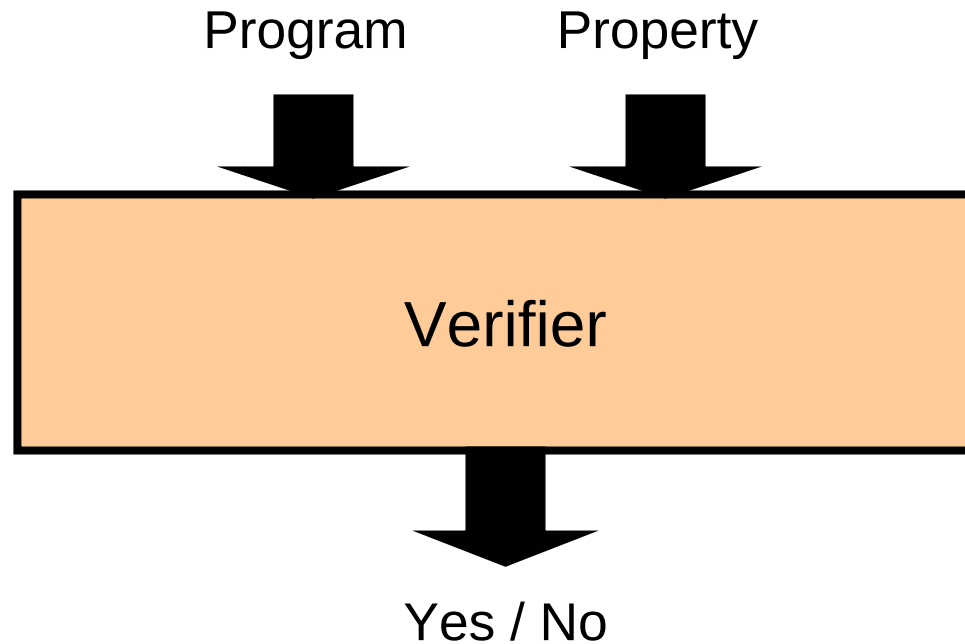
kbfilter.c
12,000 lines of code

An Error Trajectory



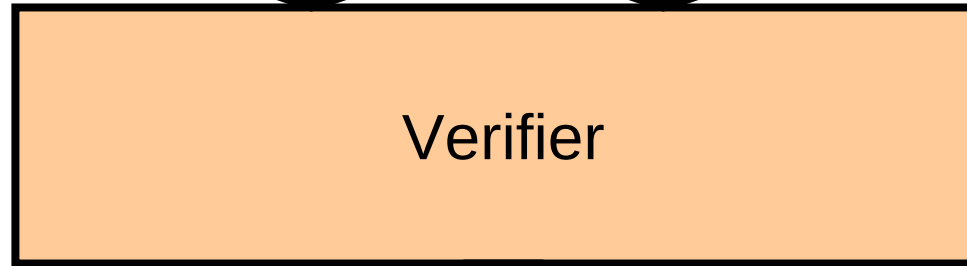
Programs are not continuous.

The Impossible Dream



Program

terminates



Verifier

Yes / No

Program

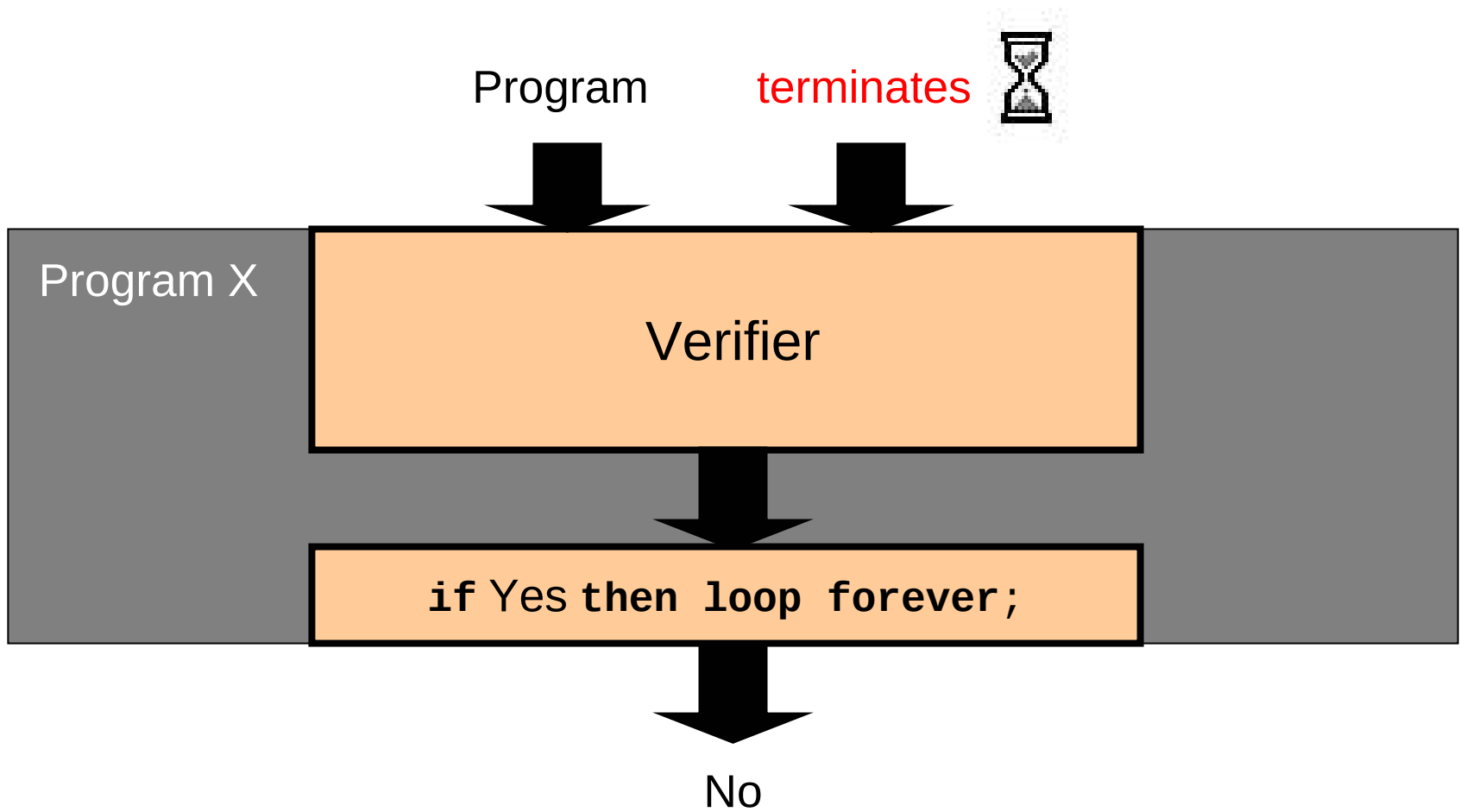
terminates

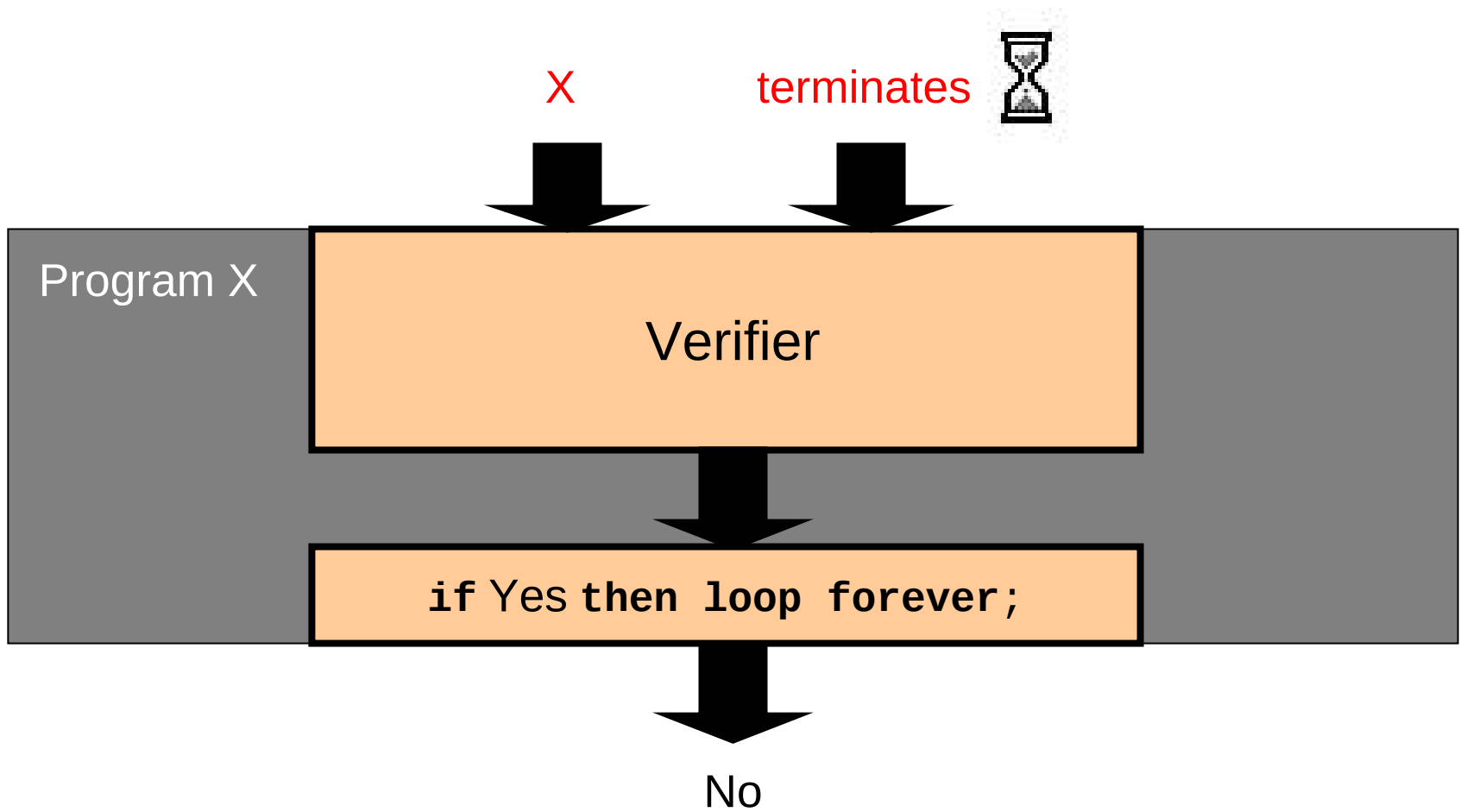


Verifier

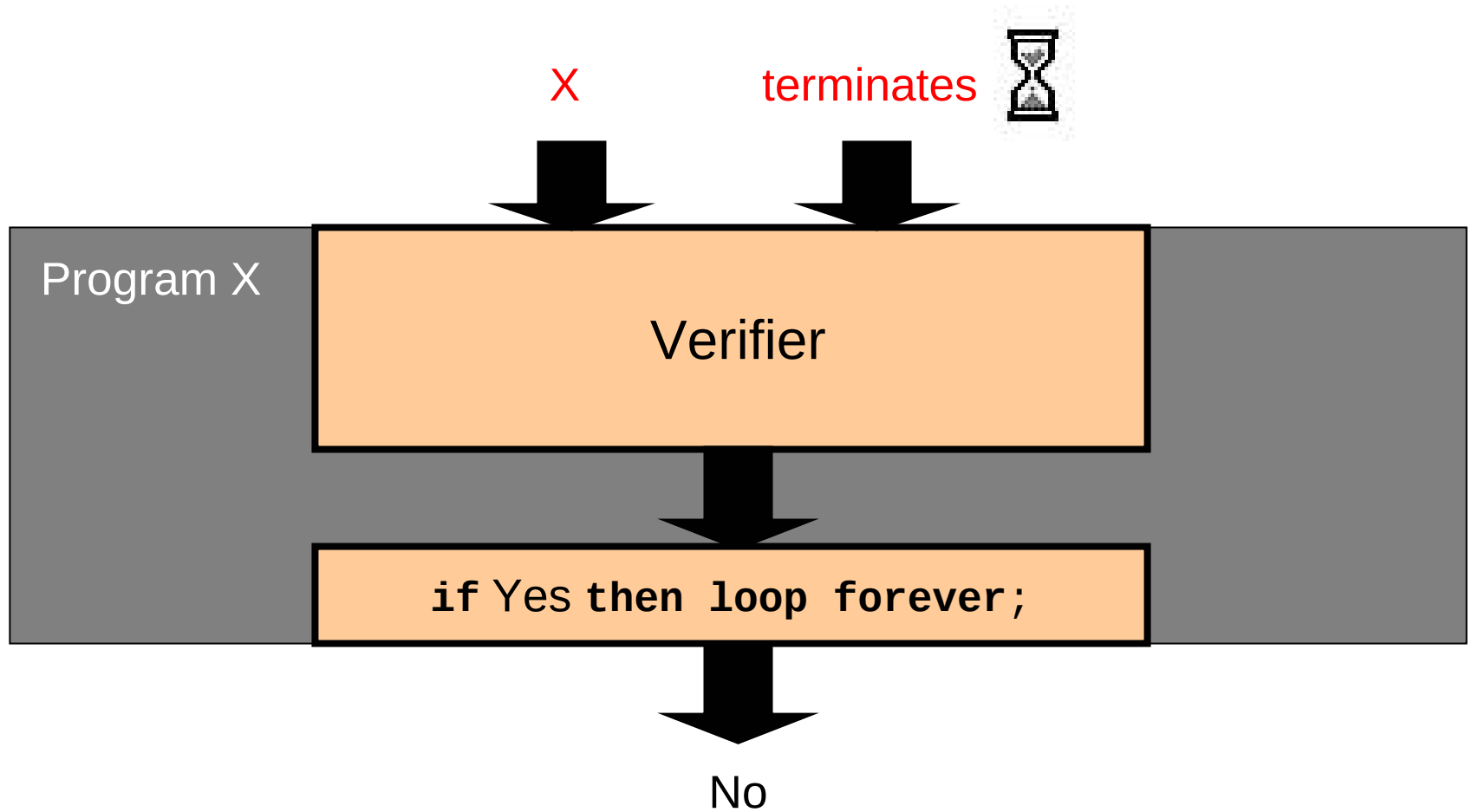
if Yes then loop forever;

No

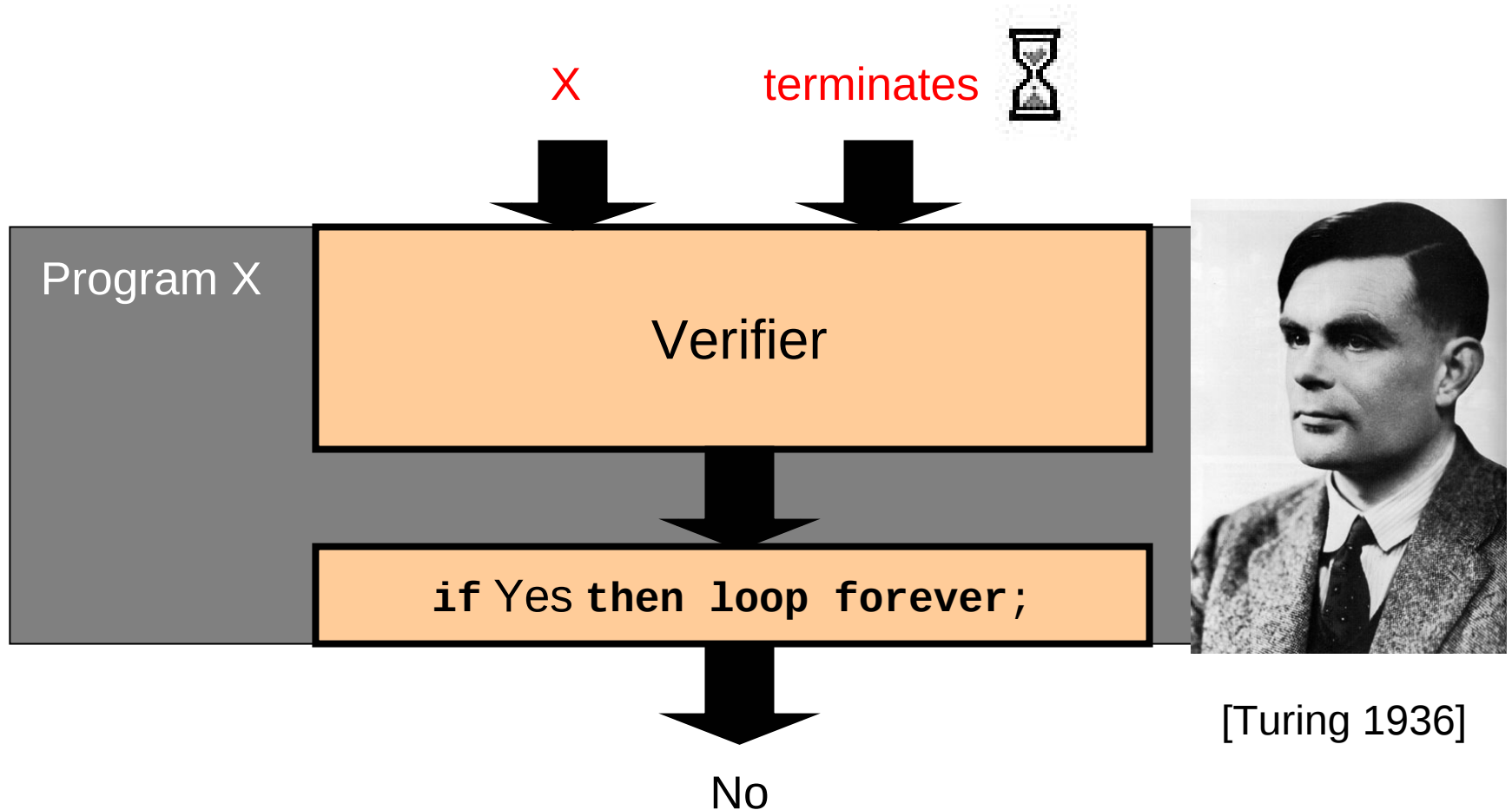




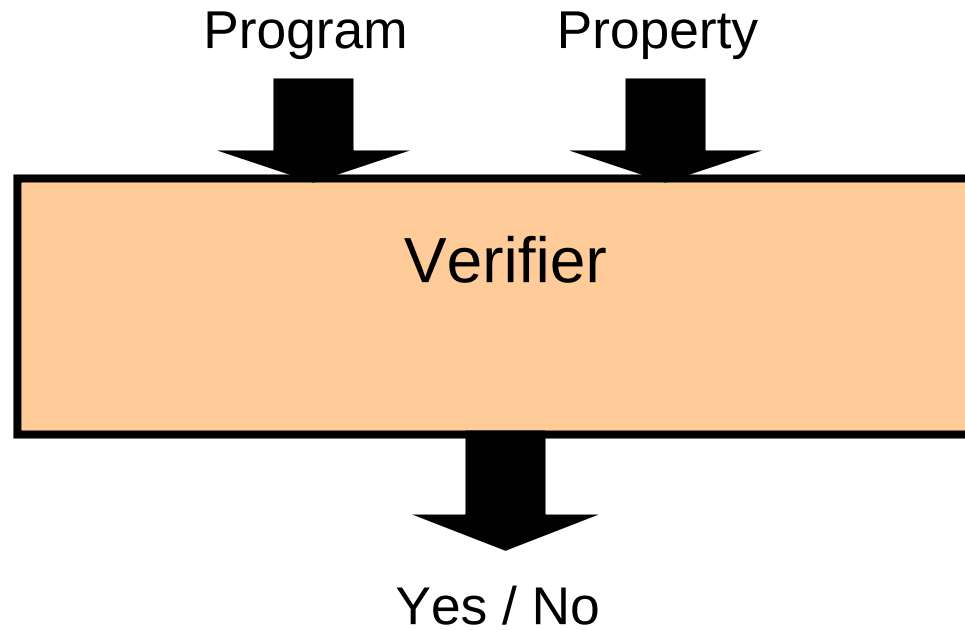
Does X terminate?



Conclusion: Verifier cannot exist!



The Impossible Dream



Abstract
Model

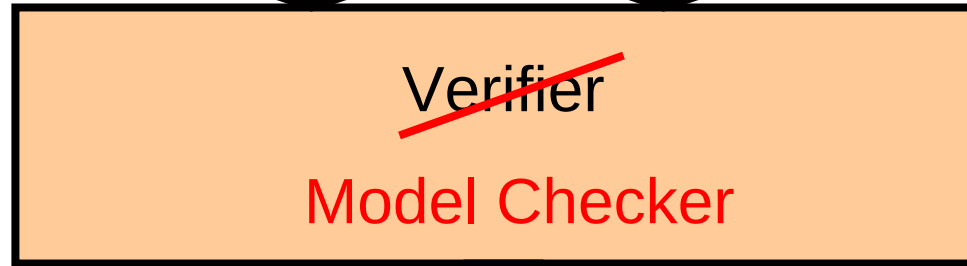
~~Program~~

Property

~~Verifier~~

Model Checker

Yes / No



Mathematical Modeling: A Tale of Two Cultures

Engineering

Differential Equations
Linear Algebra
Probability Theory

Computer Science

Mathematical Logic
Discrete Structures
Automata Theory

Our Methodology



1. Model Building:

capture relevant aspects of the system
formally (using logic and automata)

2. Model Checking:

implement **algorithms** for model analysis
[Clarke/Emerson; Queille/Sifakis 1981]

Two Examples

1 Concurrency Bugs

(due to interaction between two programs)

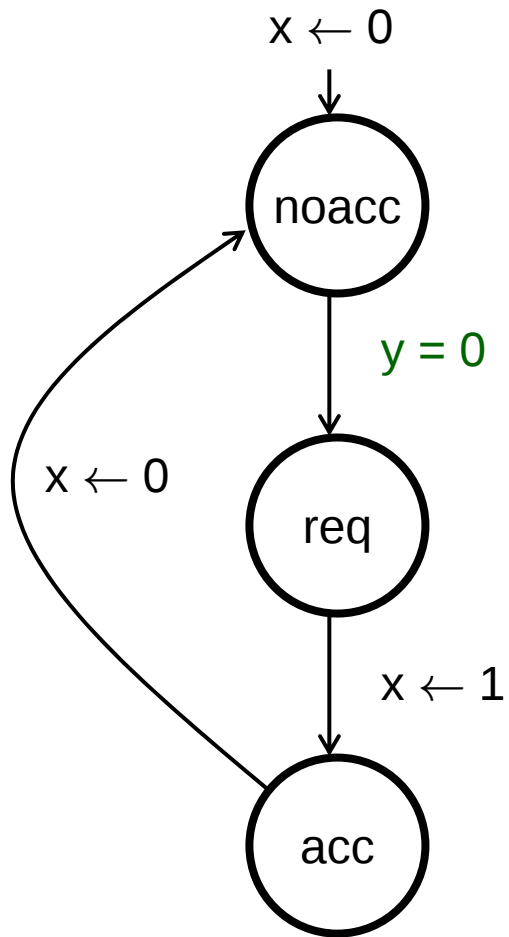
Model:	finite automata
Algorithm:	state graph exploration

2 Embedded Bugs

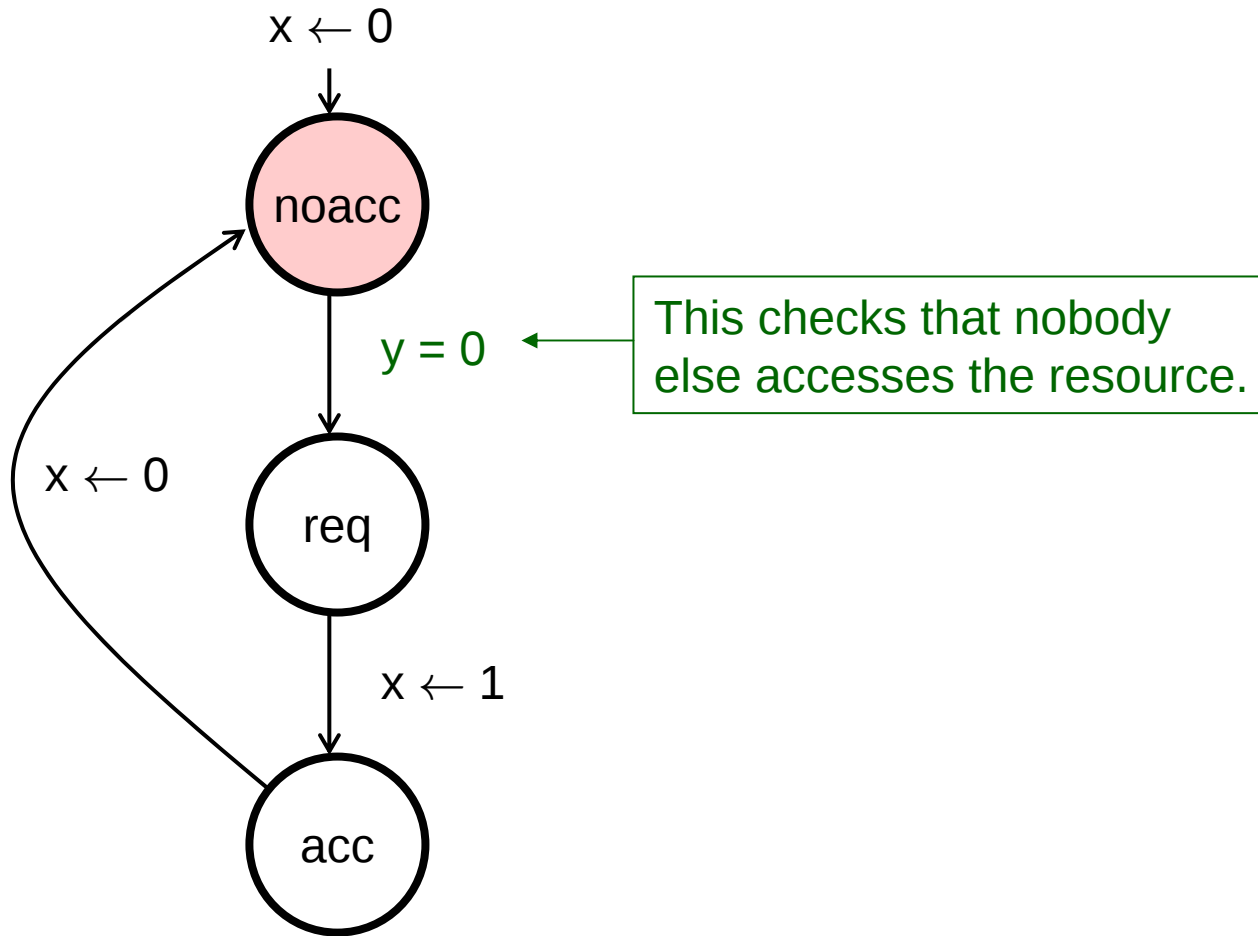
(due to interaction between a program and the physical world)

Model:	hybrid automata
Algorithm:	polyhedral state exploration

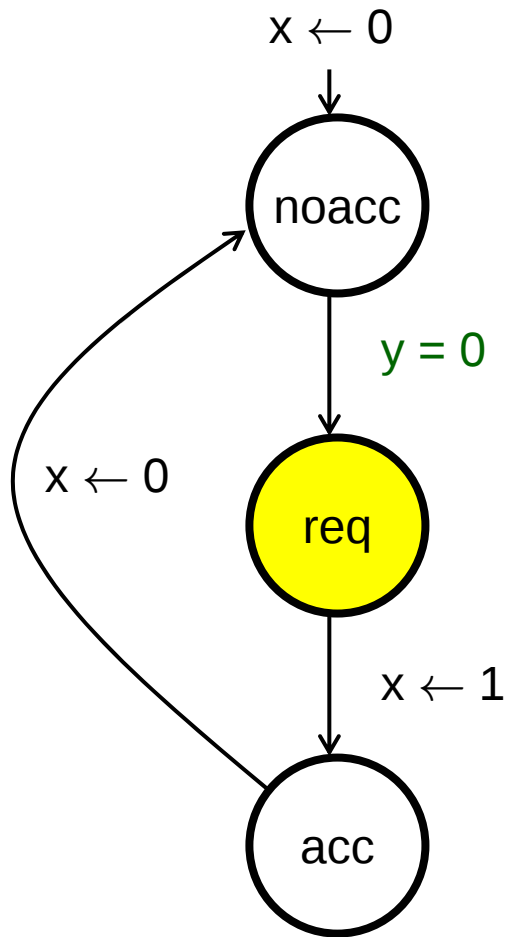
Access to a Shared Resource



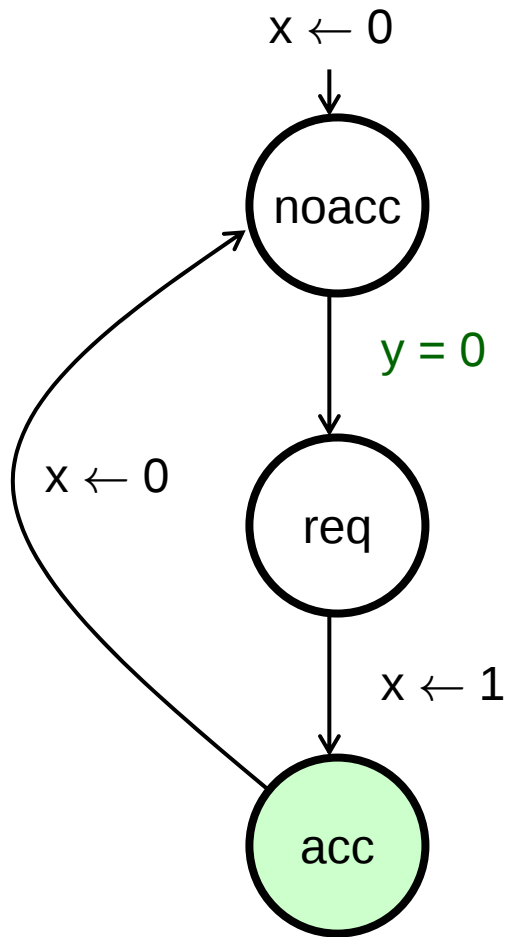
Access to a Shared Resource



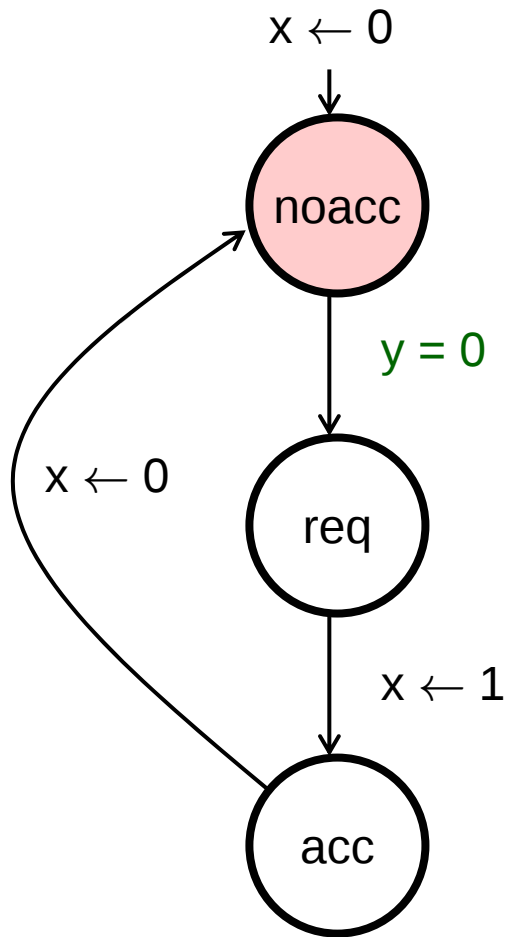
Access to a Shared Resource



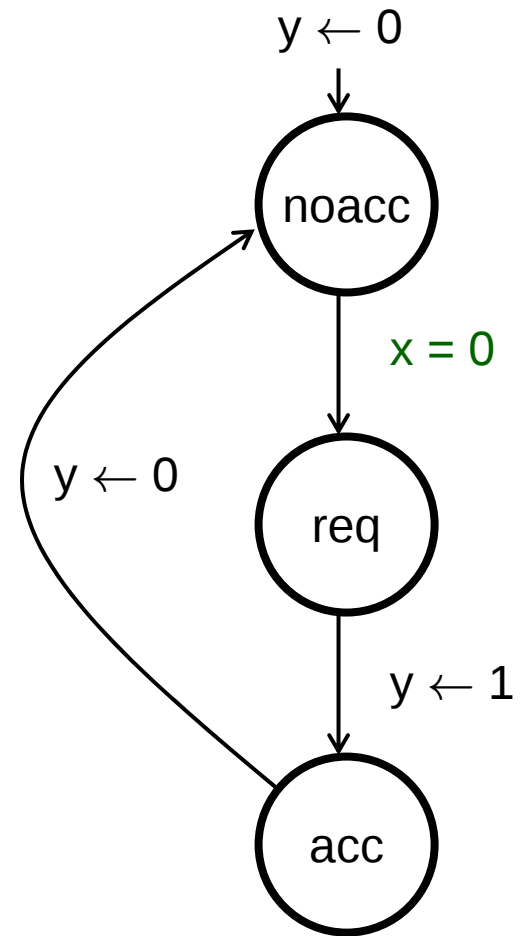
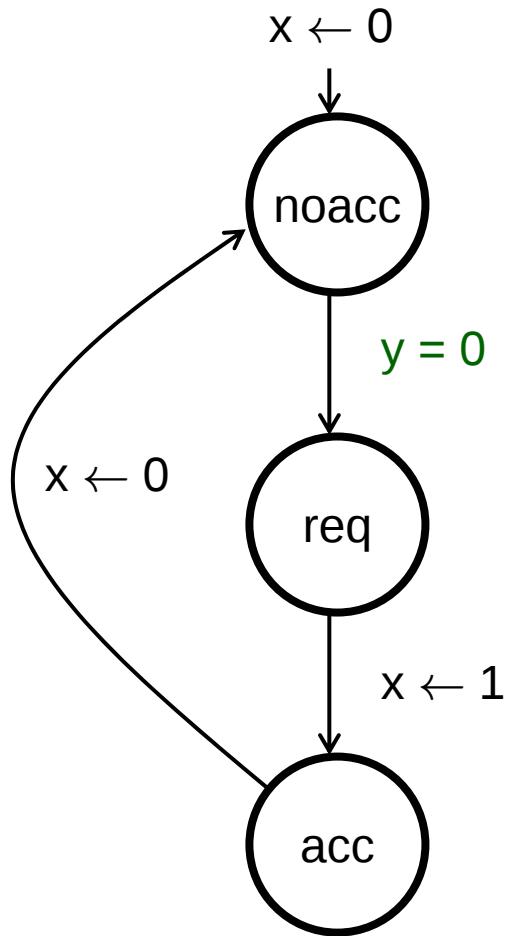
Access to a Shared Resource



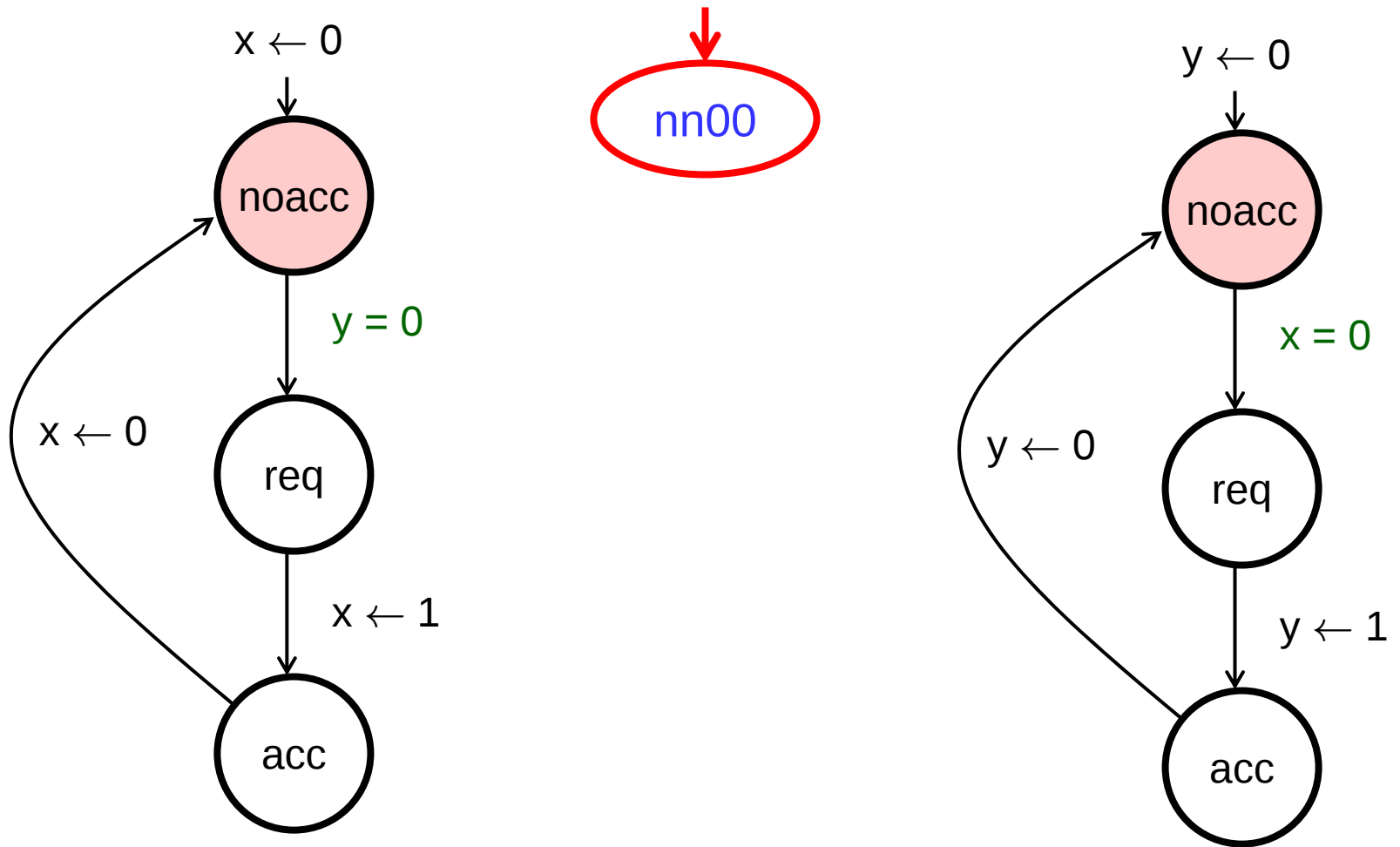
Access to a Shared Resource



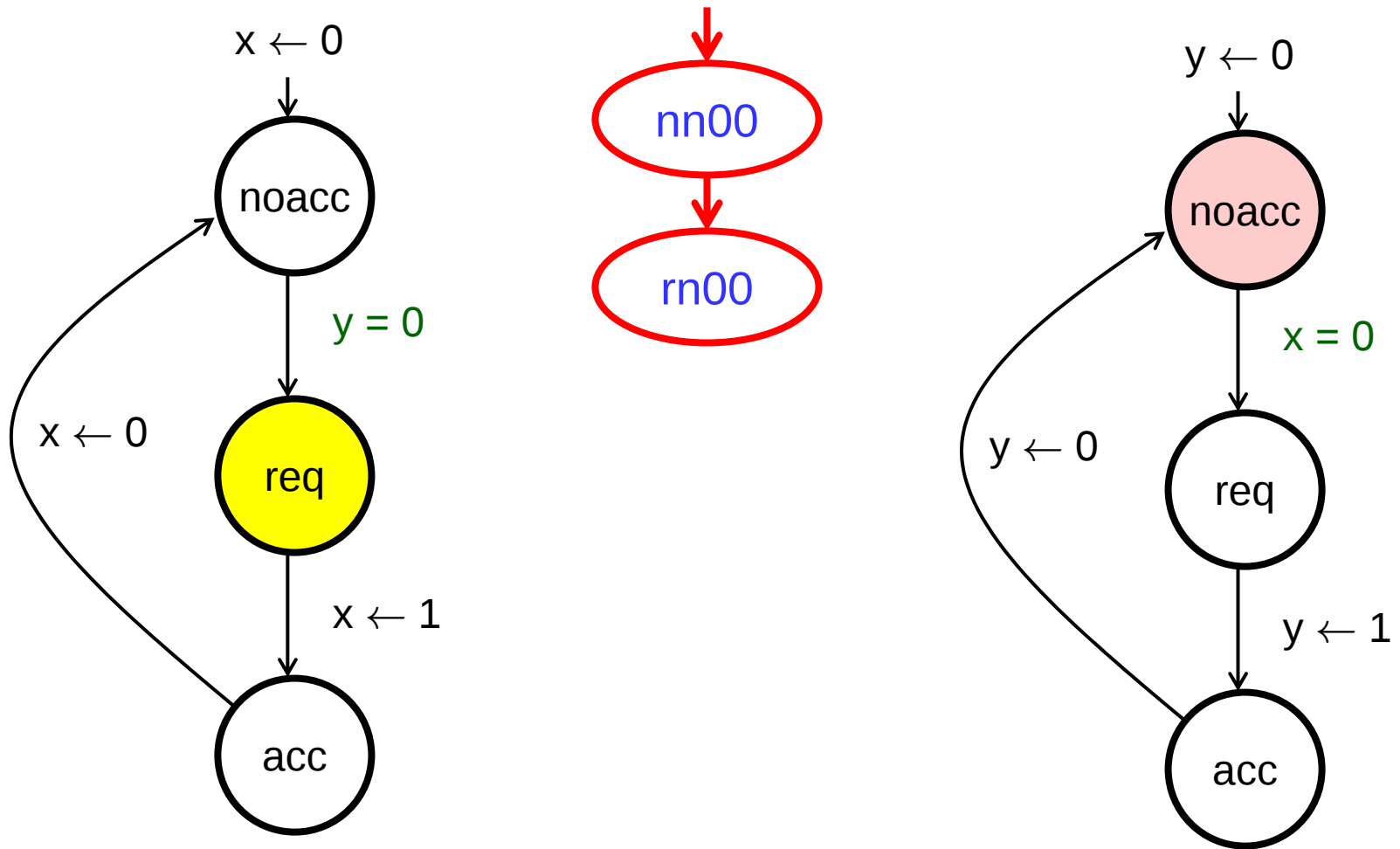
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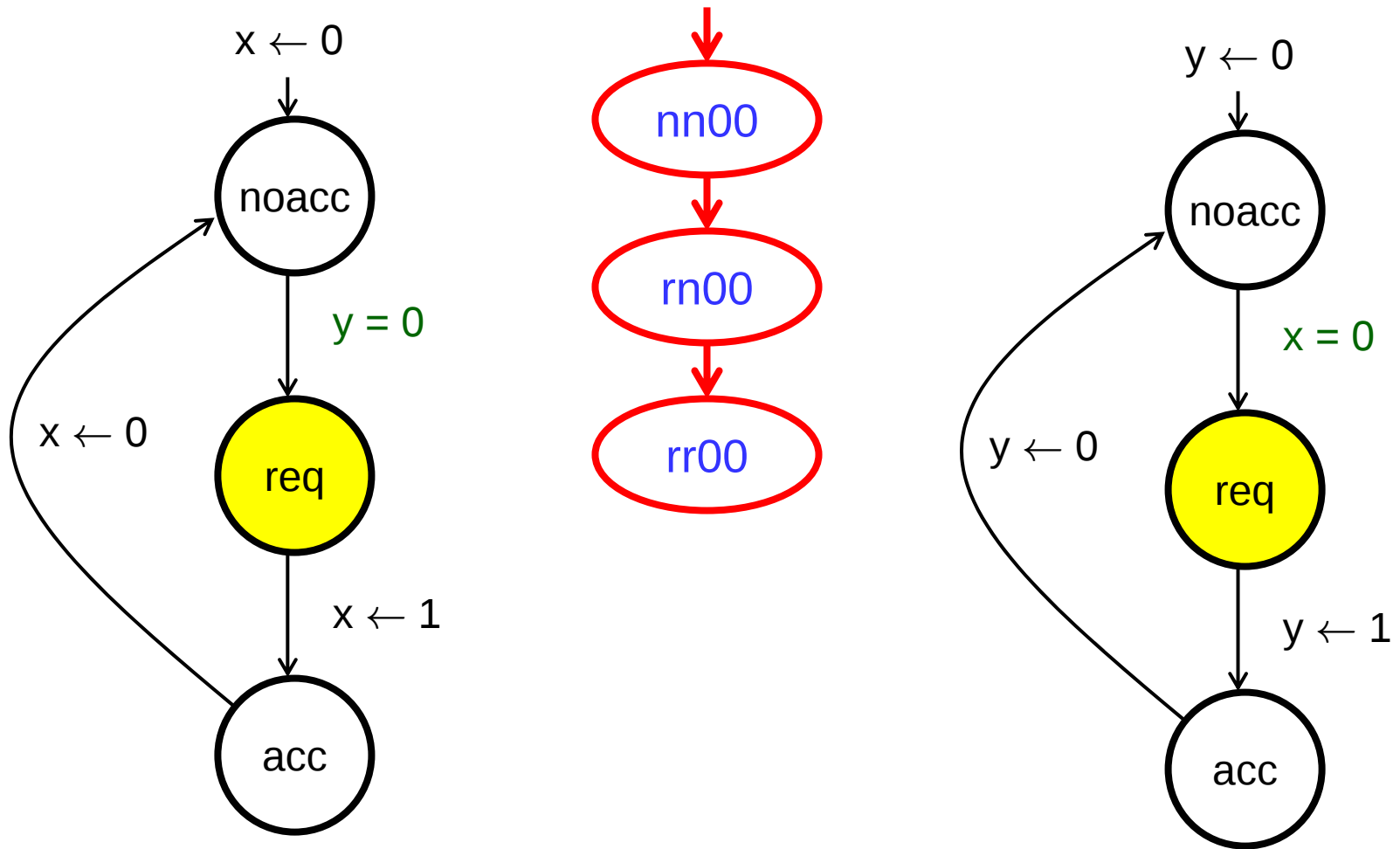
Access to a Shared Resource



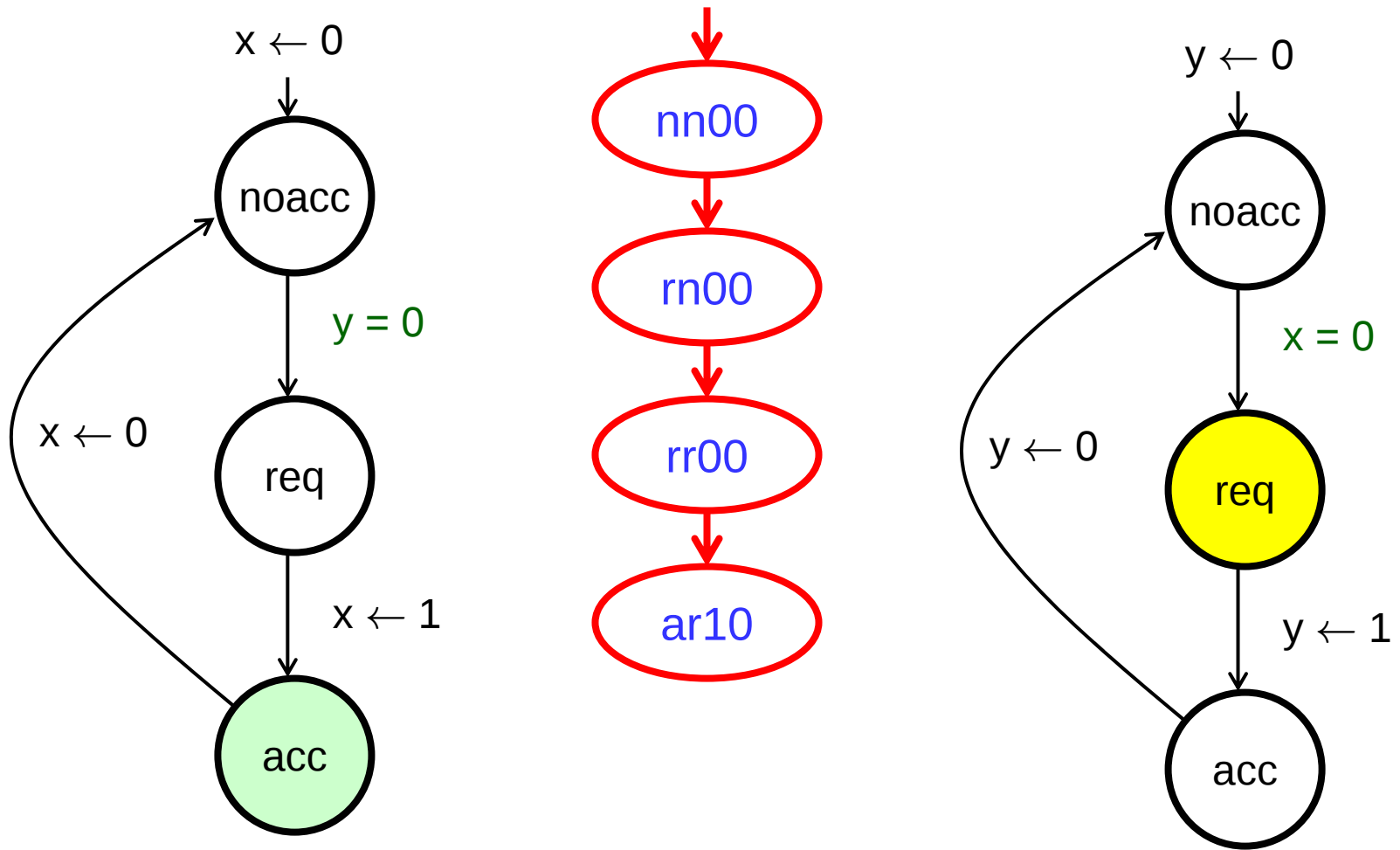
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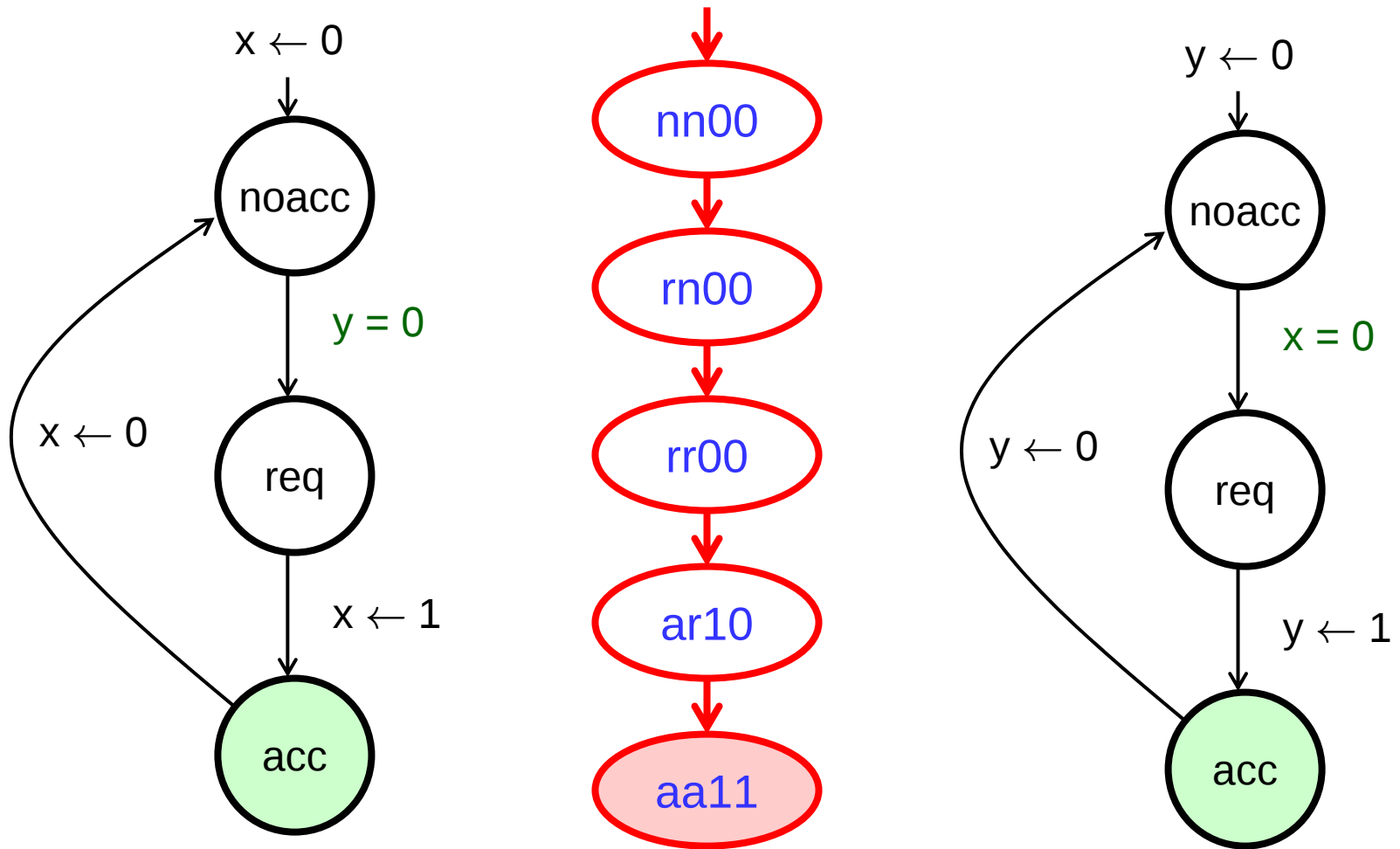
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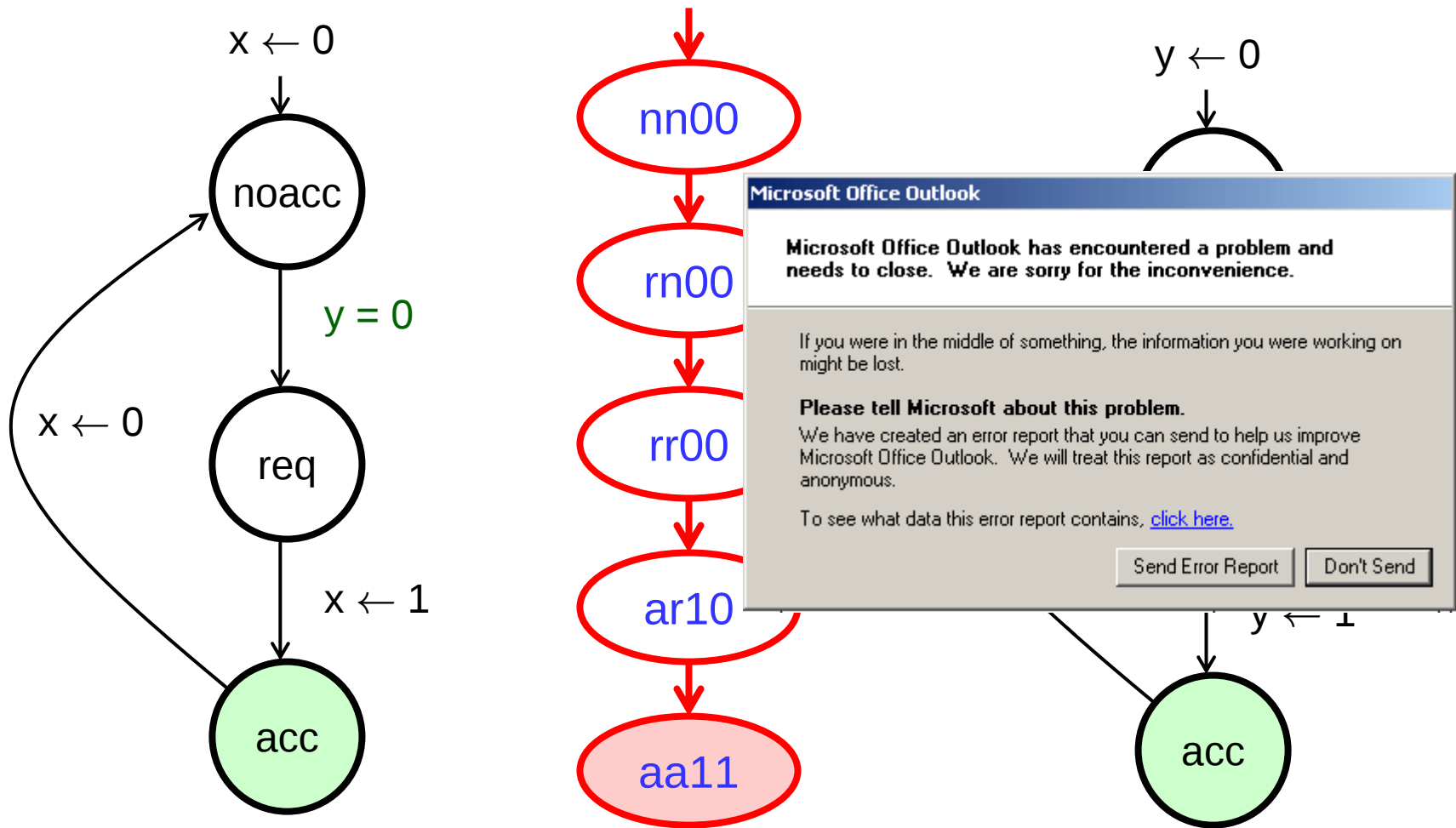
Access to a Shared Resource



Access to a Shared Resource

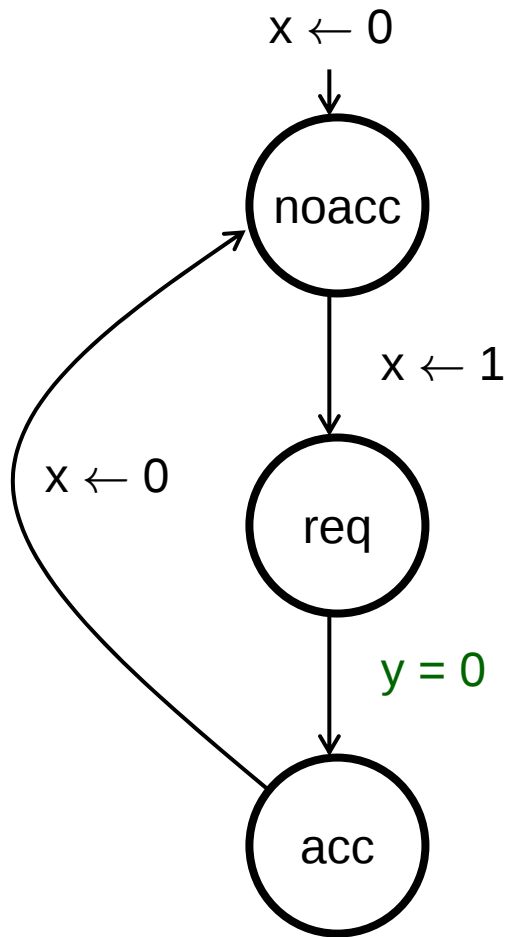


Access to a Shared Resource

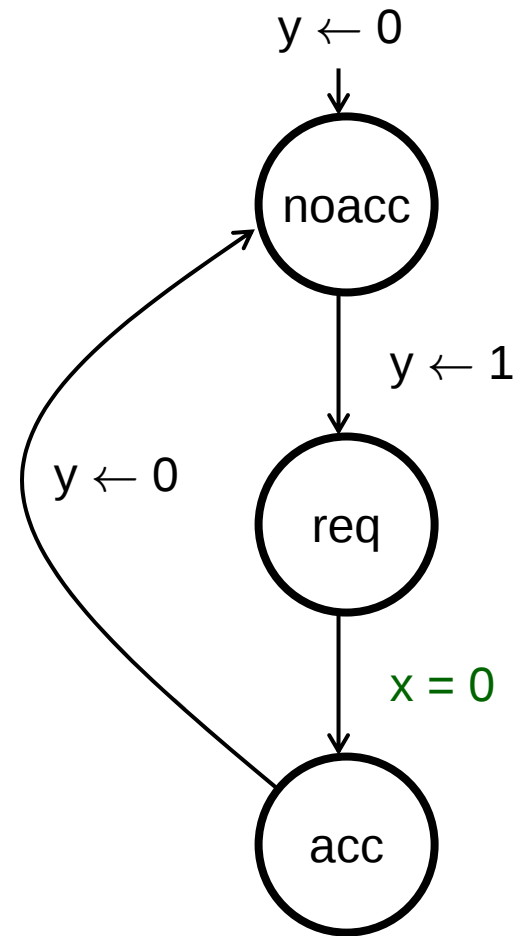
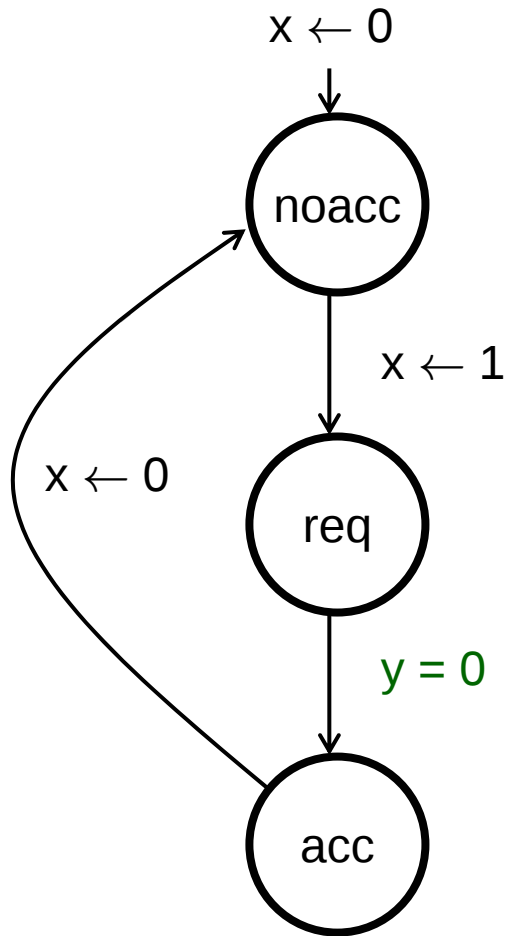


Violates safety.

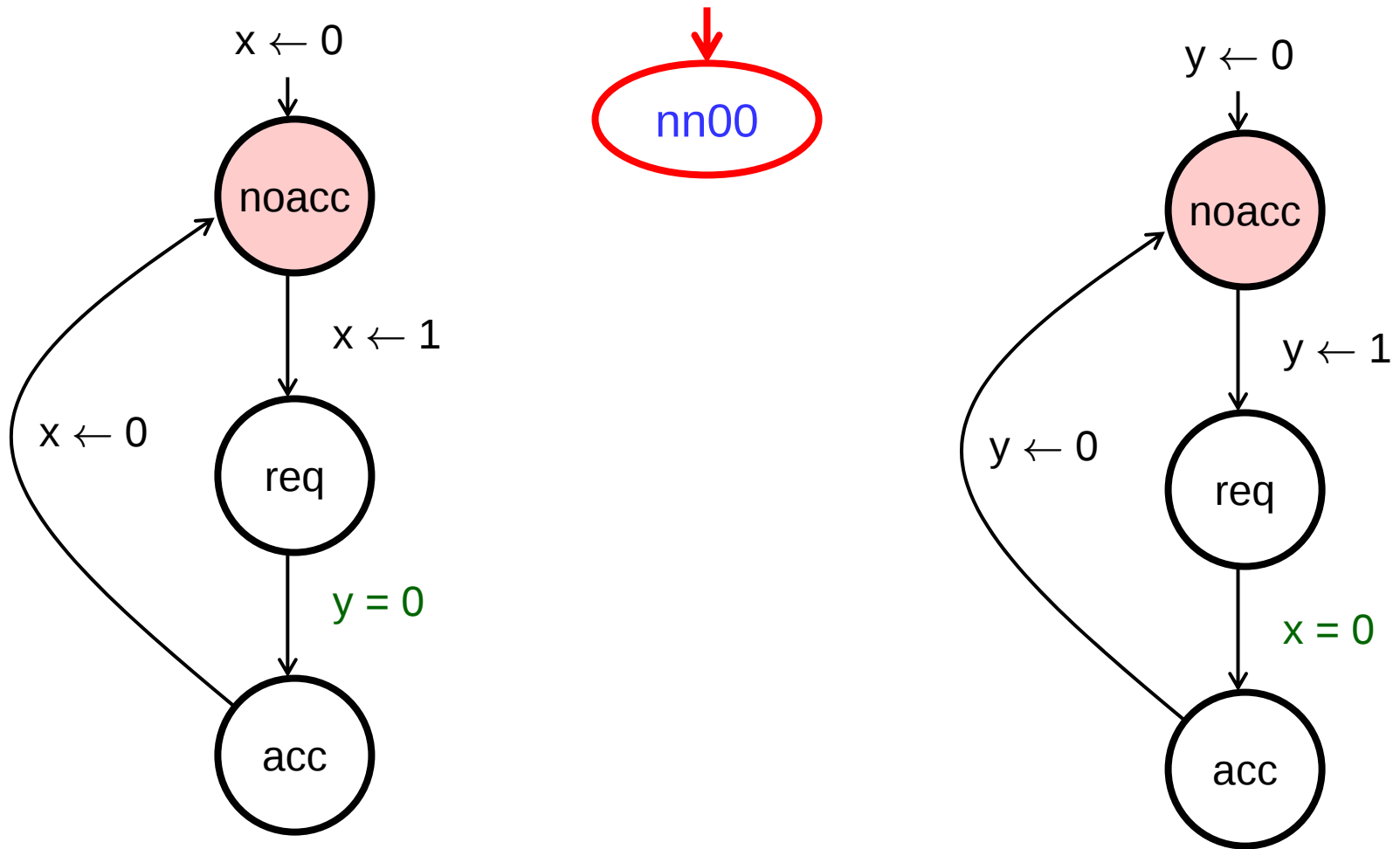
Second Attempt



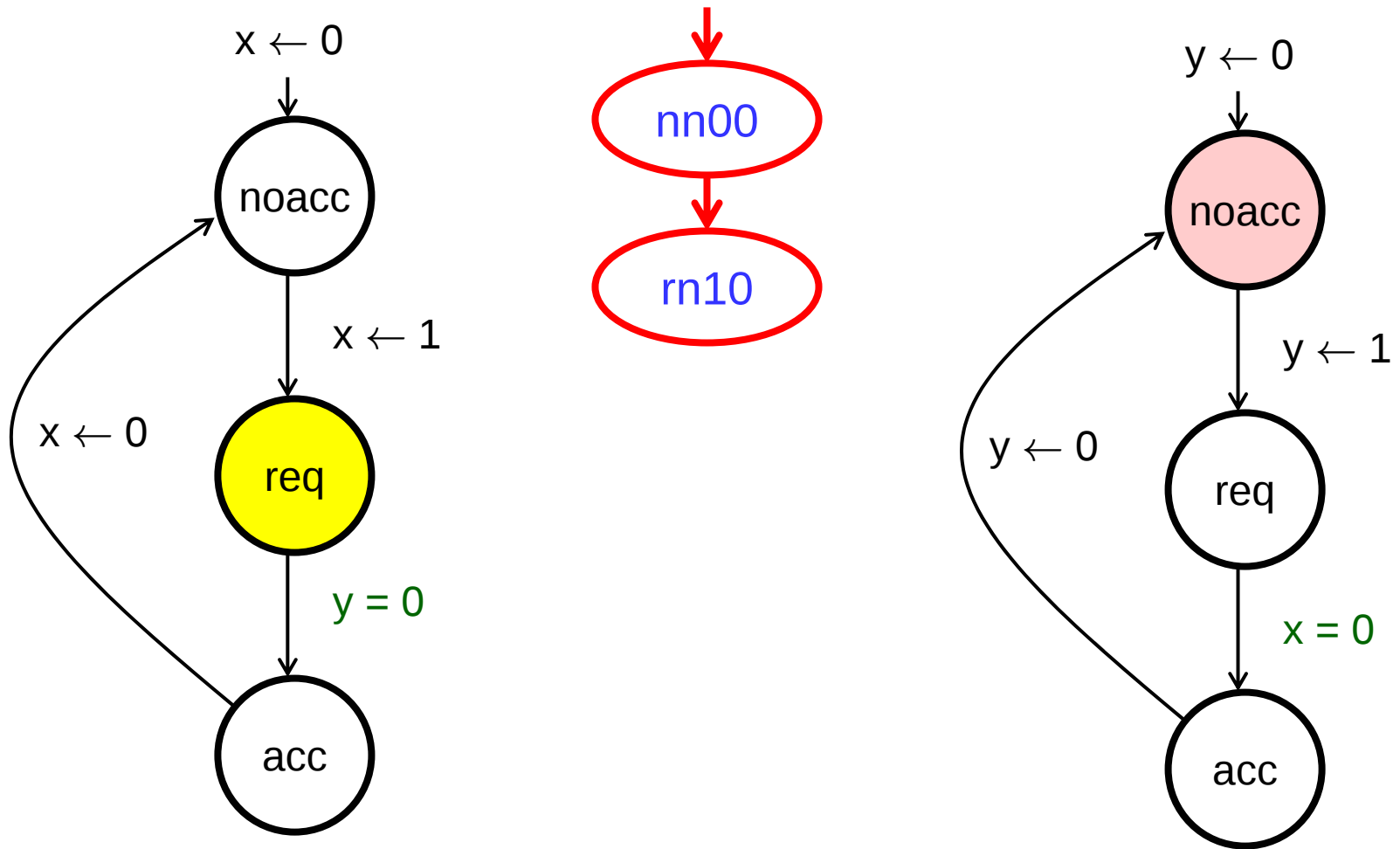
Second Attempt



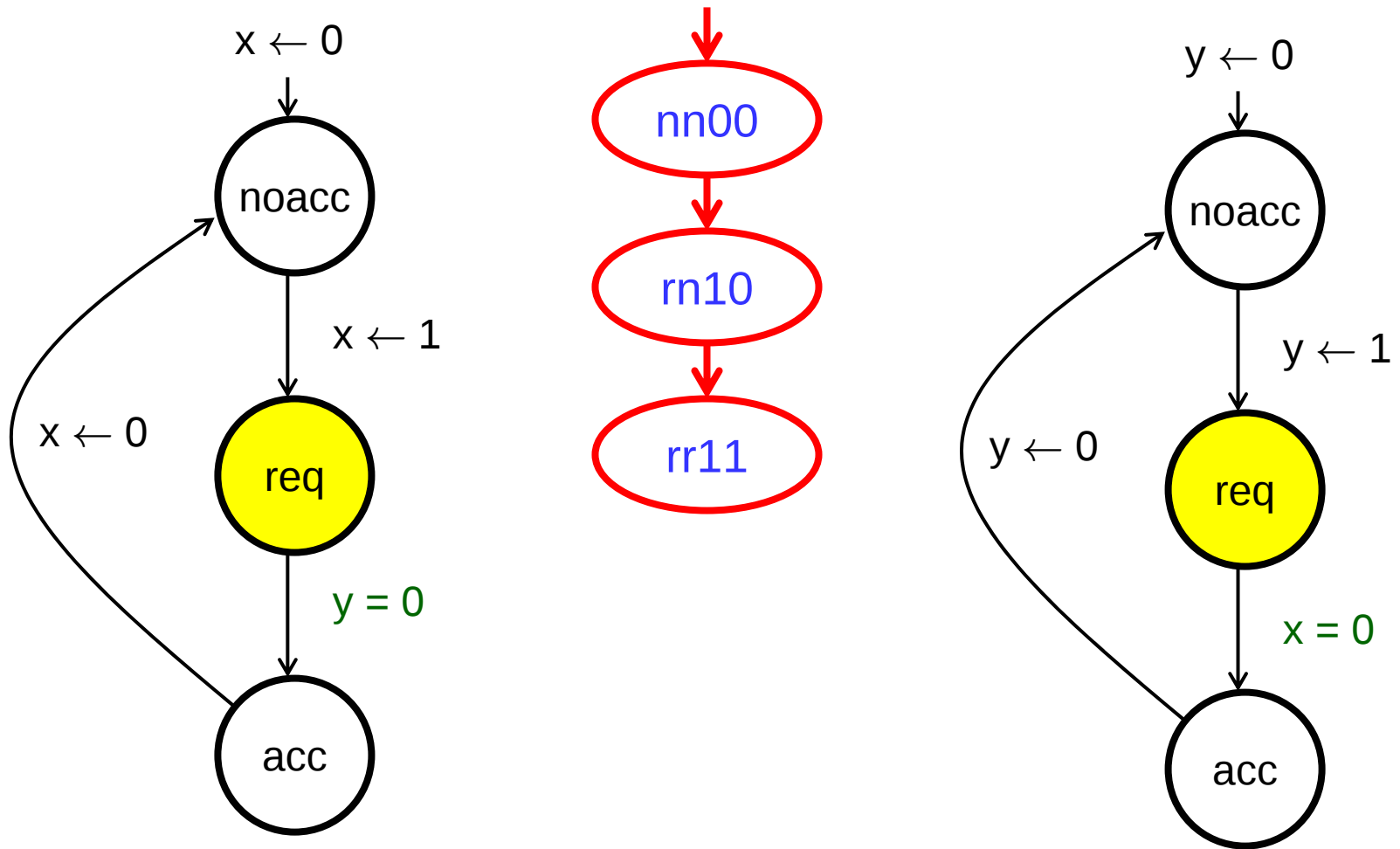
Second Attempt



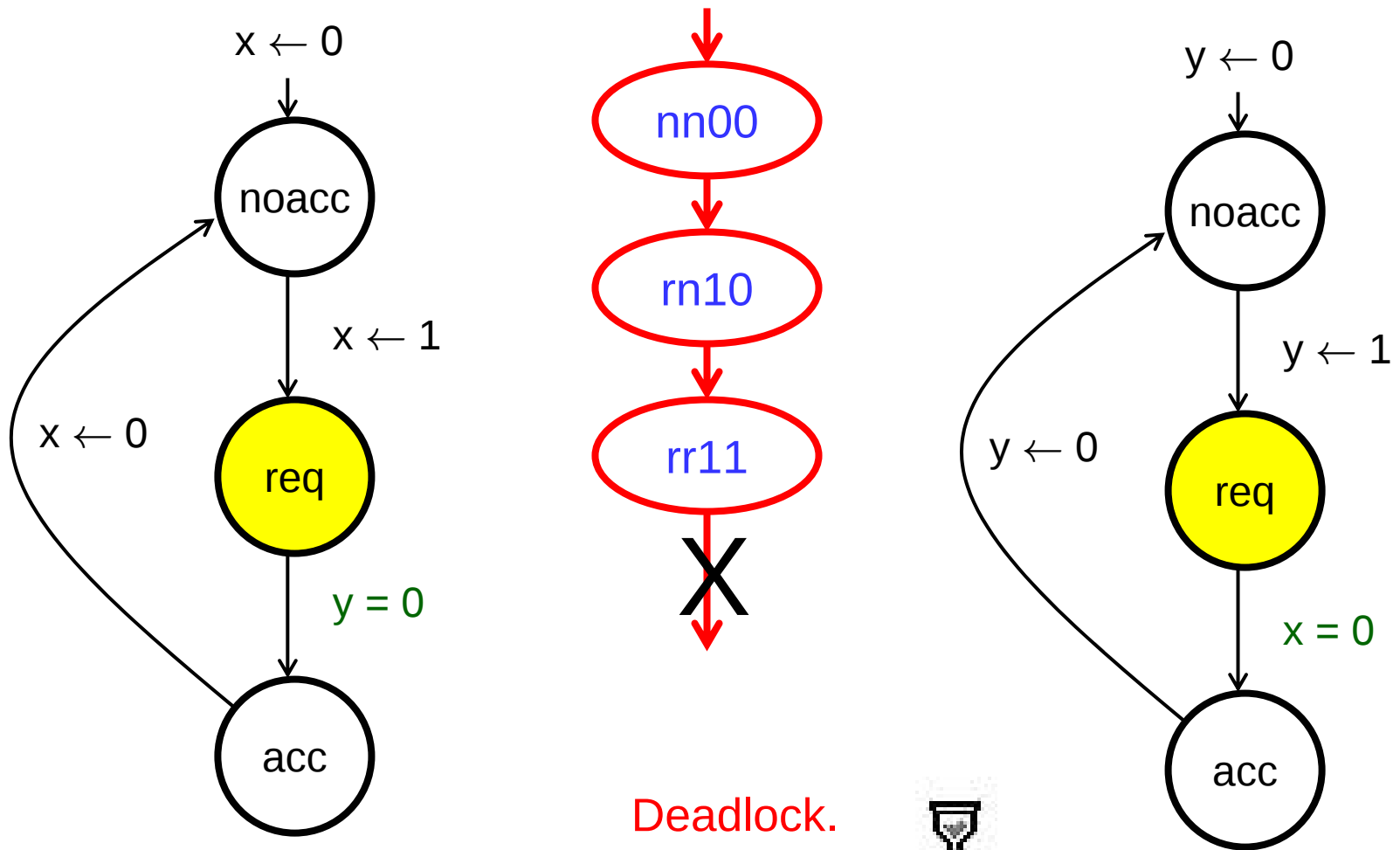
Second Attempt



Second Attempt



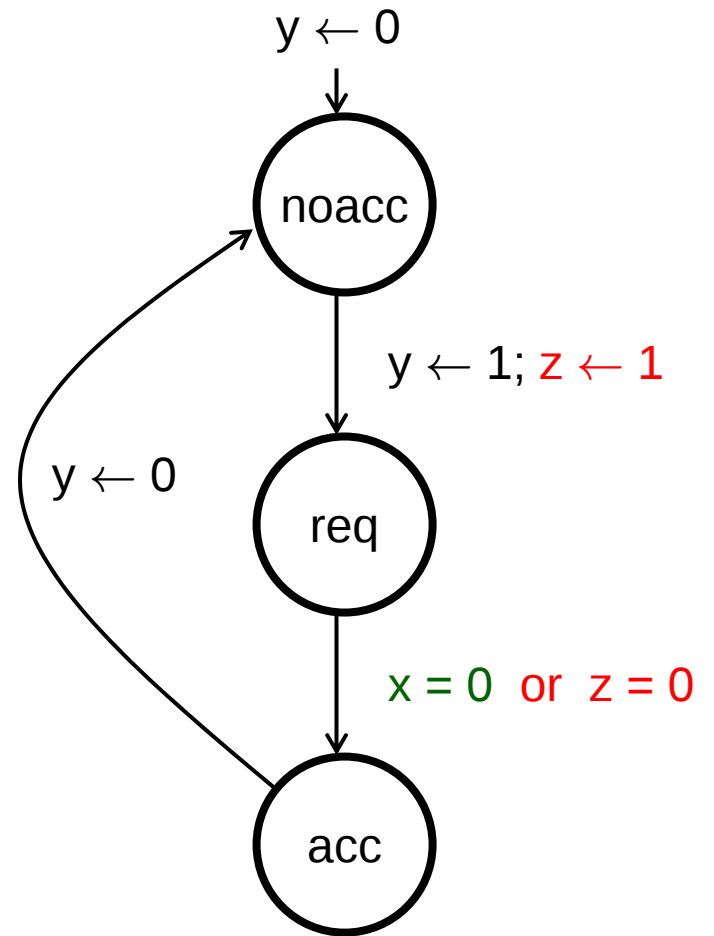
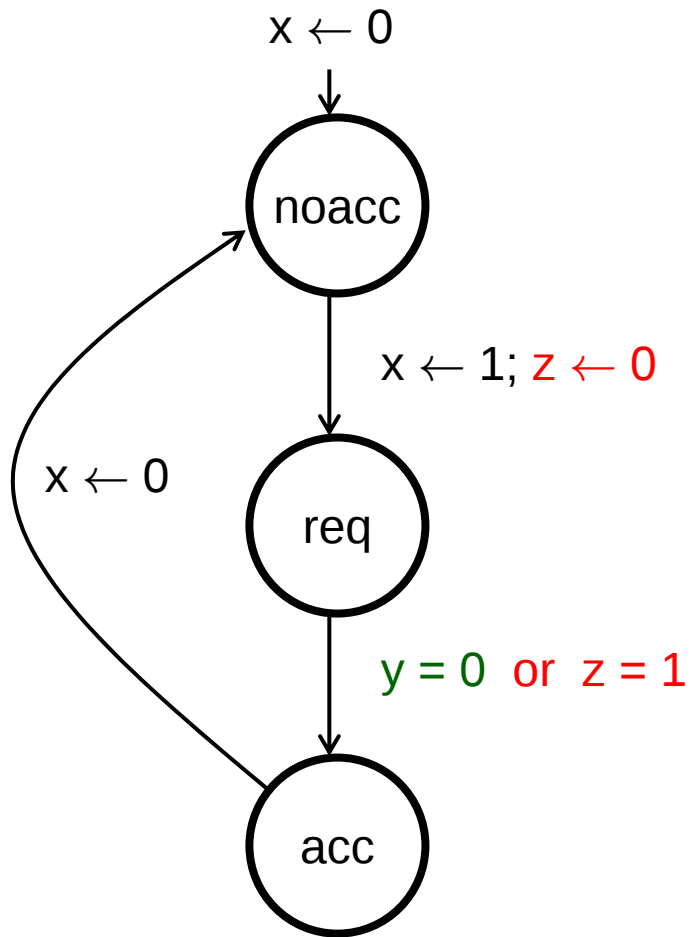
Second Attempt



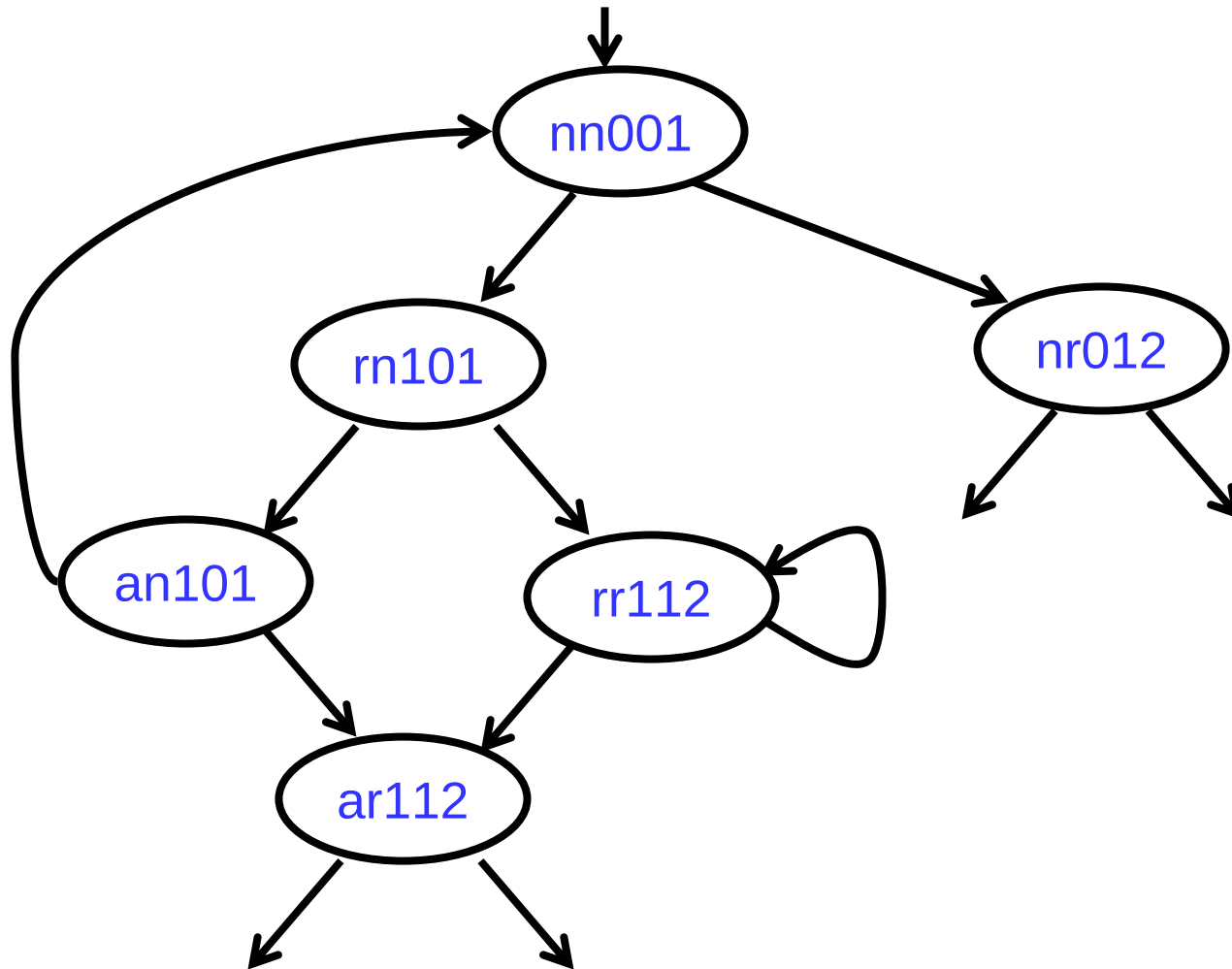
Deadlock.
Violates liveness.



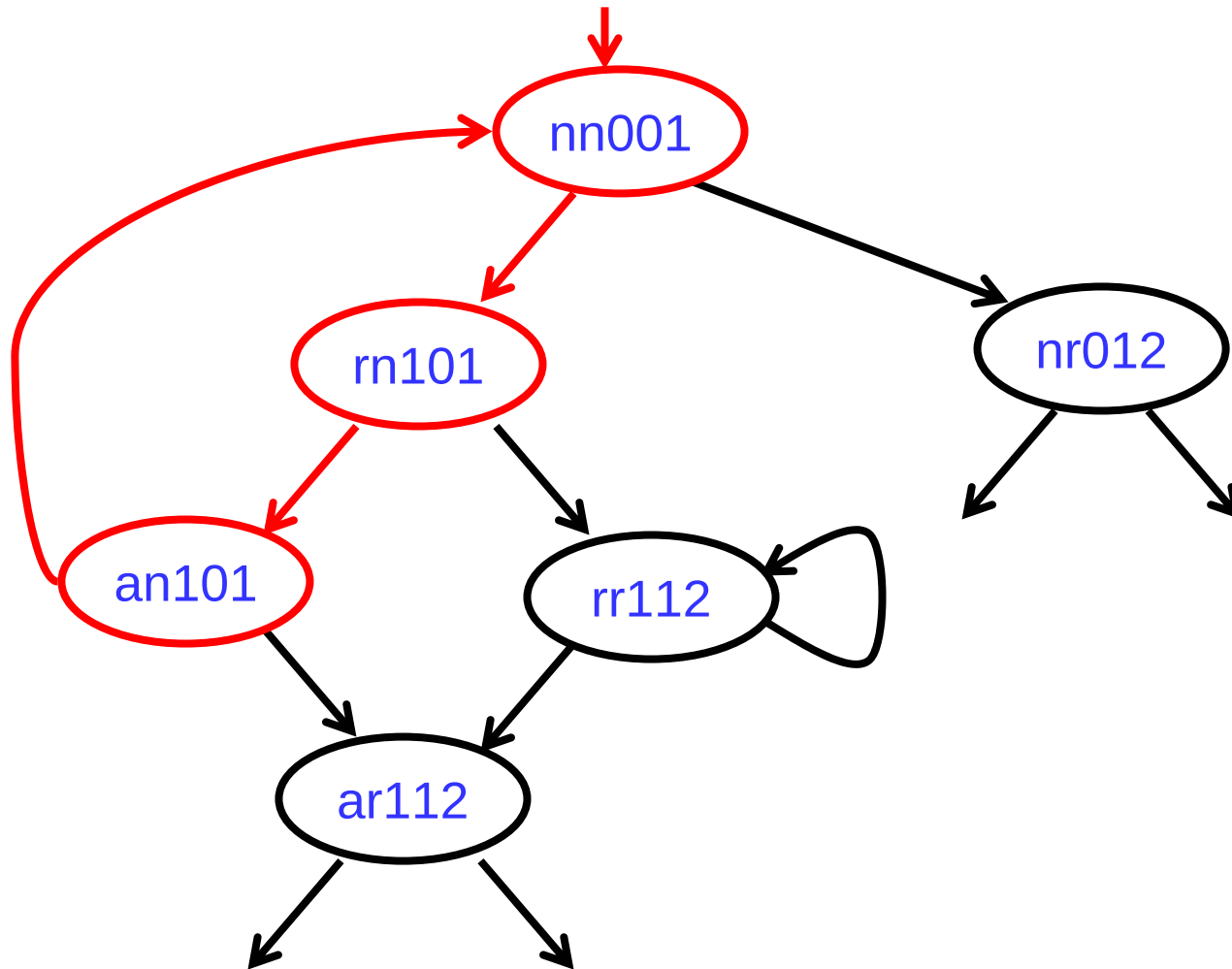
Third Attempt



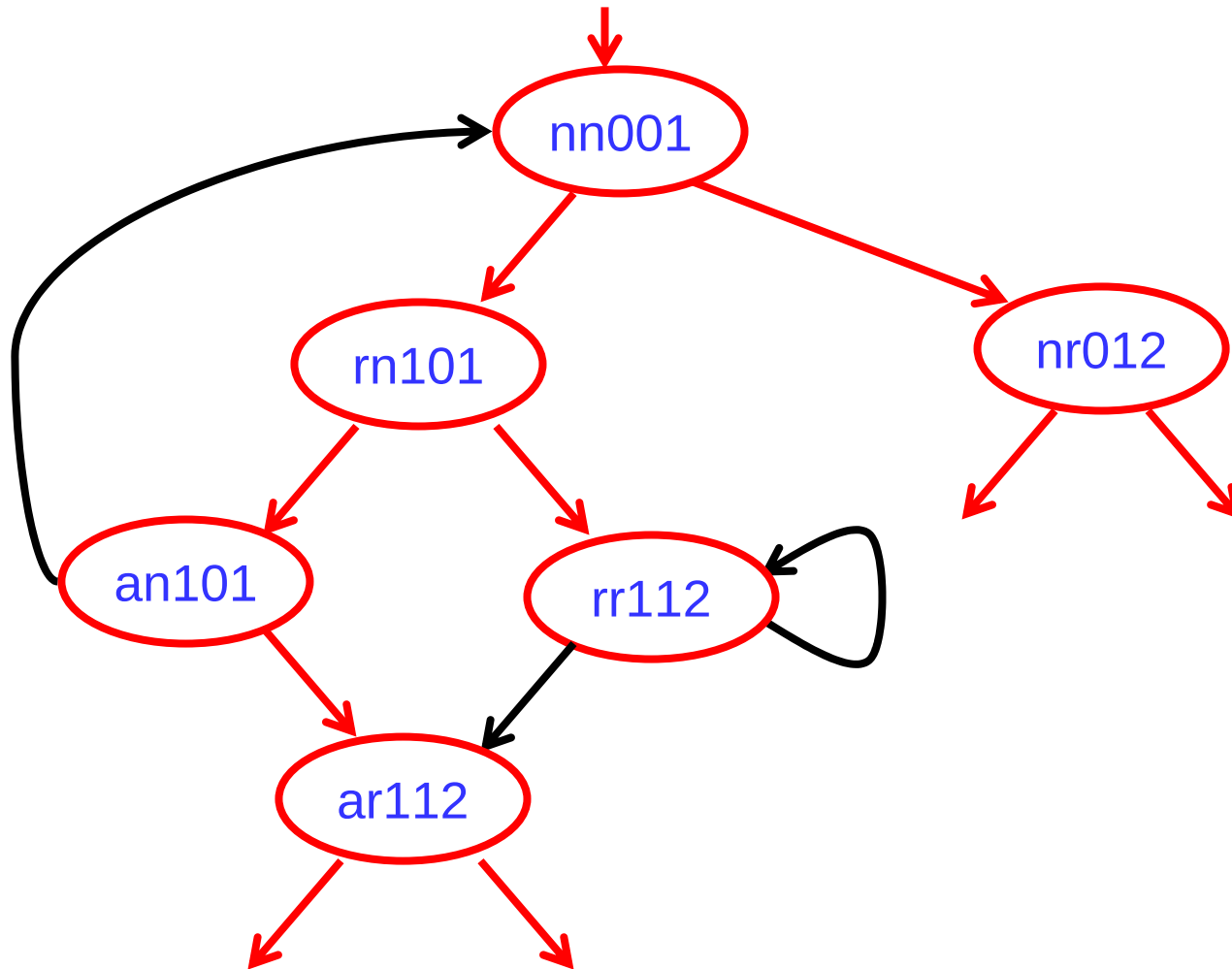
The State Graph



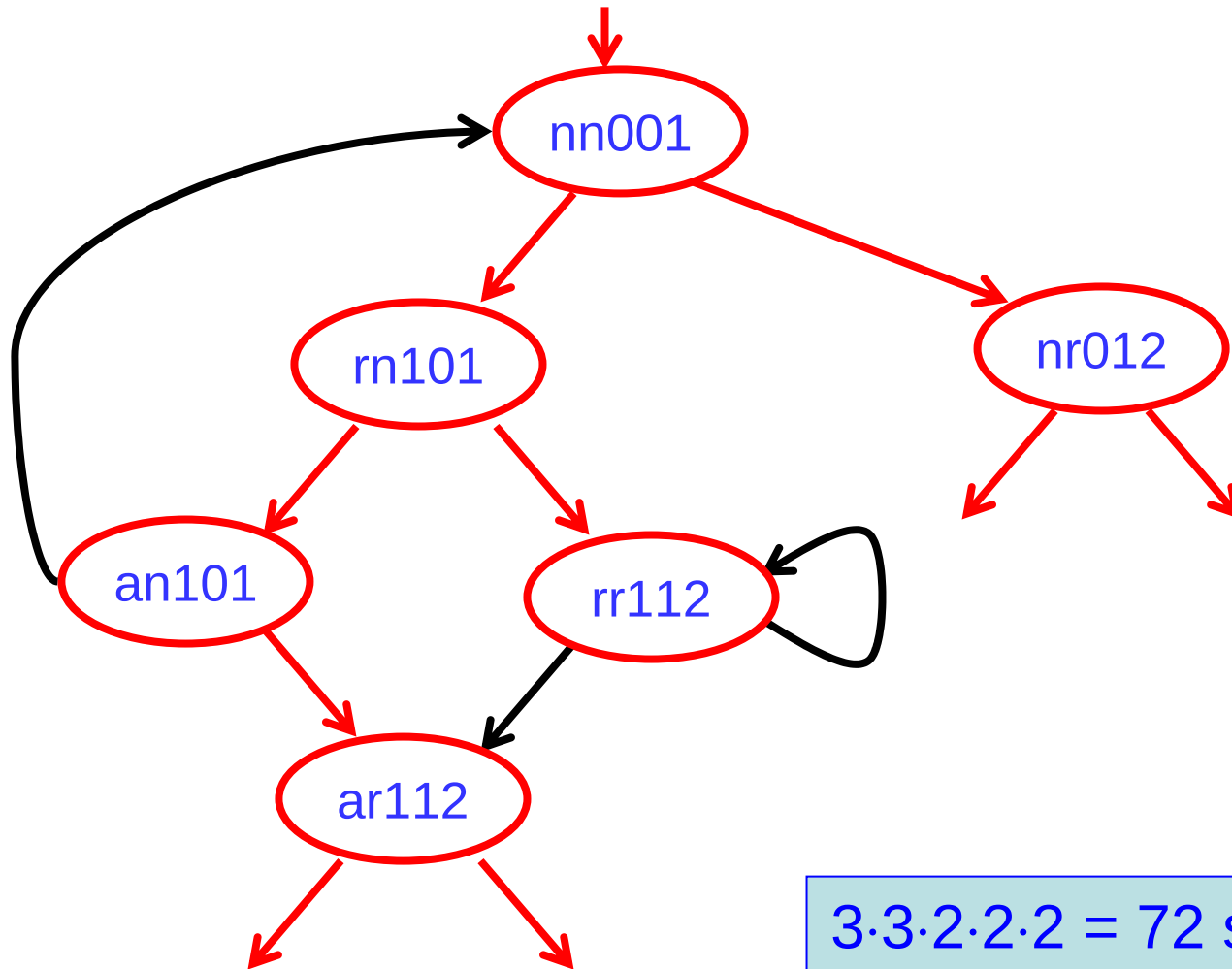
Testing / Simulation: Explore one path at a time.



Model Checking: Explore the whole graph.



Model Checking: Explore the whole graph.



Two Examples

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(due to interaction between two programs)

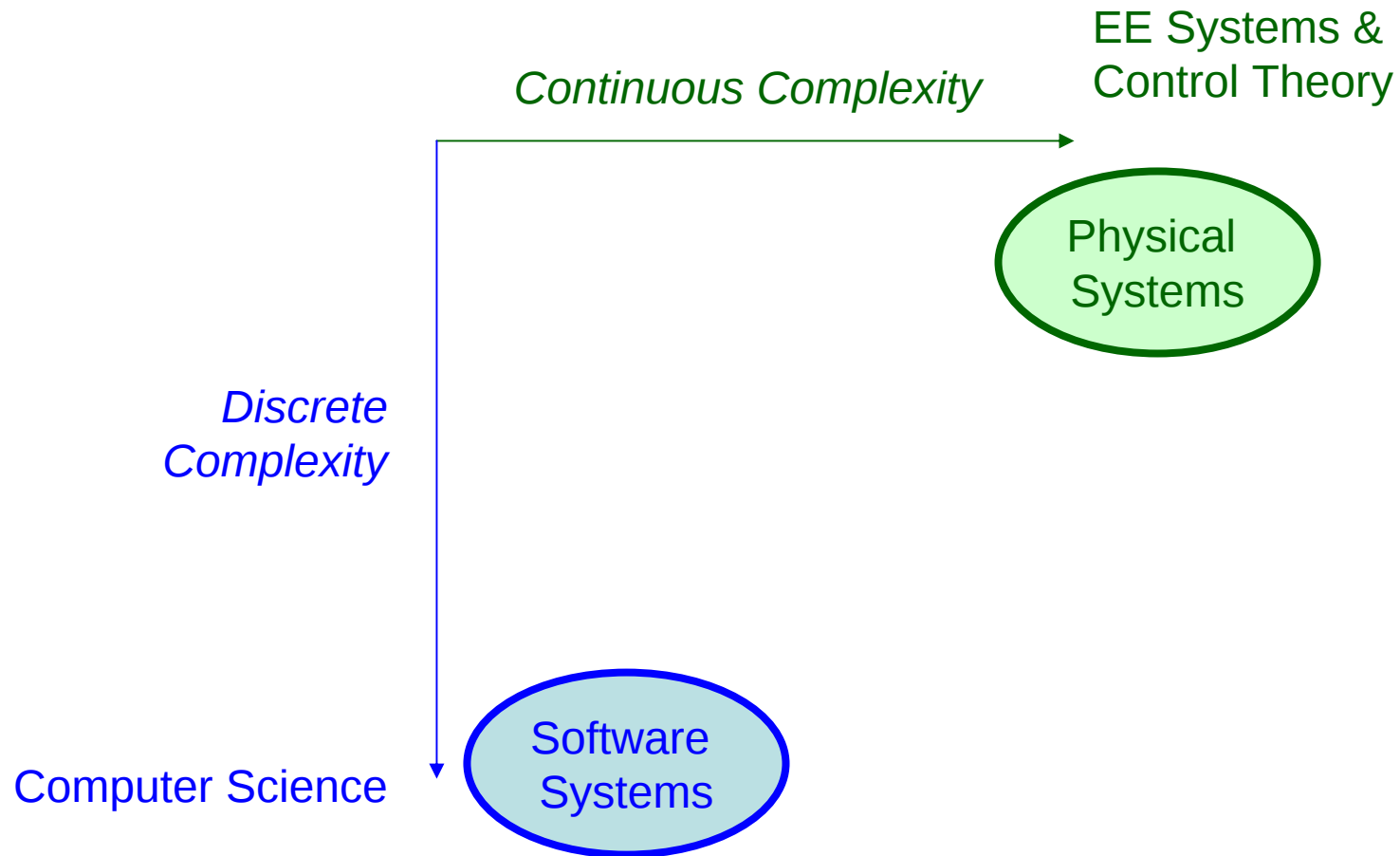
Model:	finite automata
Algorithm:	state graph exploration

2 Embedded Bugs

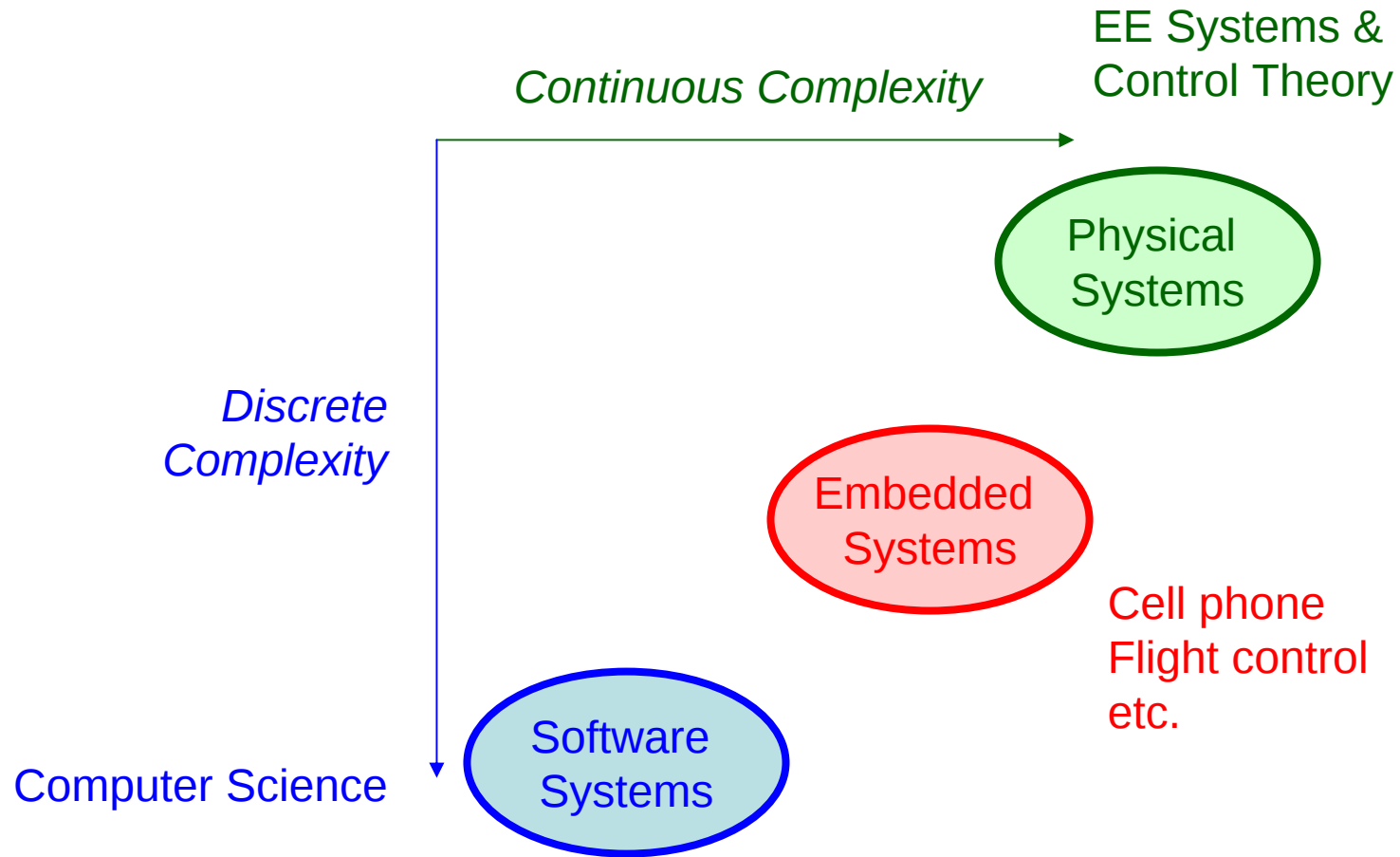
(due to interaction between a program and the physical world)

Model:	hybrid automata
Algorithm:	polyhedral state exploration

The Two Cultures



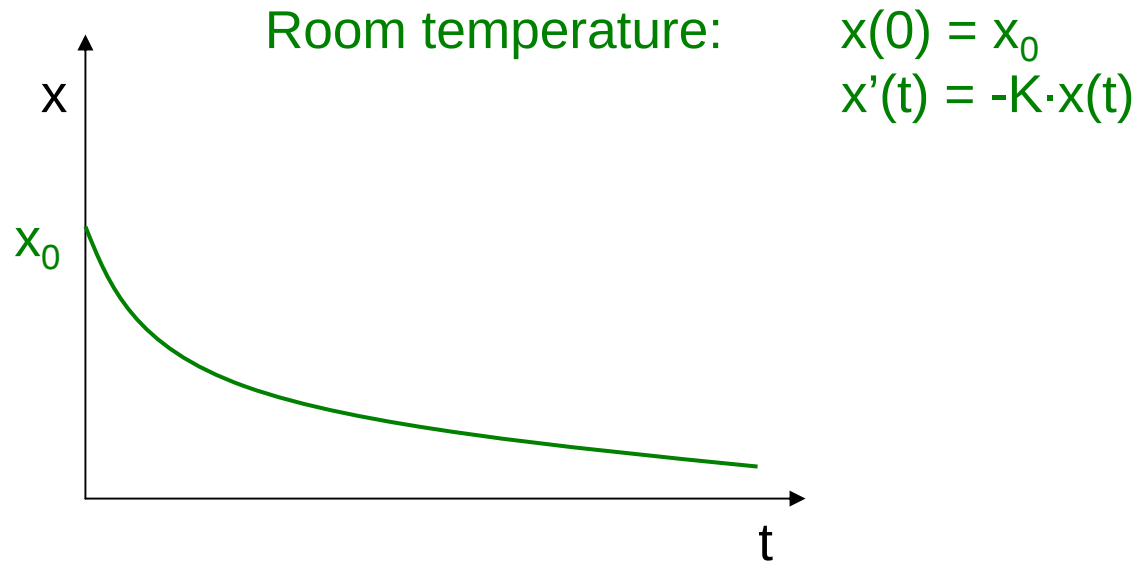
The Two Cultures



Continuous Dynamical System

State space: $\mathbb{R}^n$

Dynamics: initial condition + differential equations

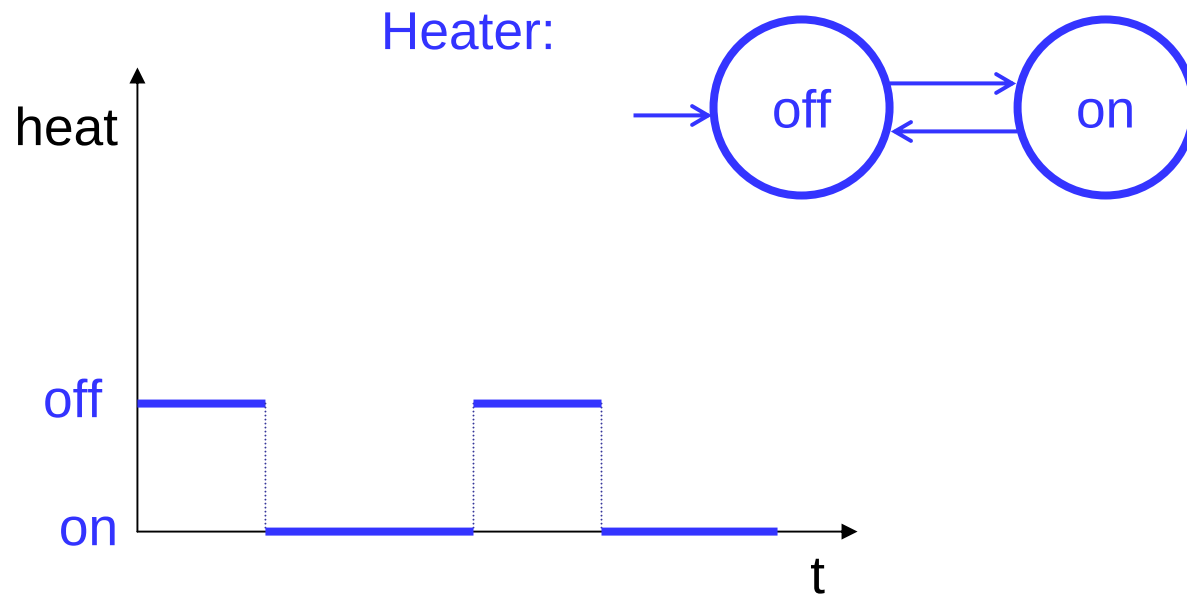


Analytic complexity.

Discrete Software System

State space: $\mathbb{B}^m$

Dynamics: initial condition + state transitions

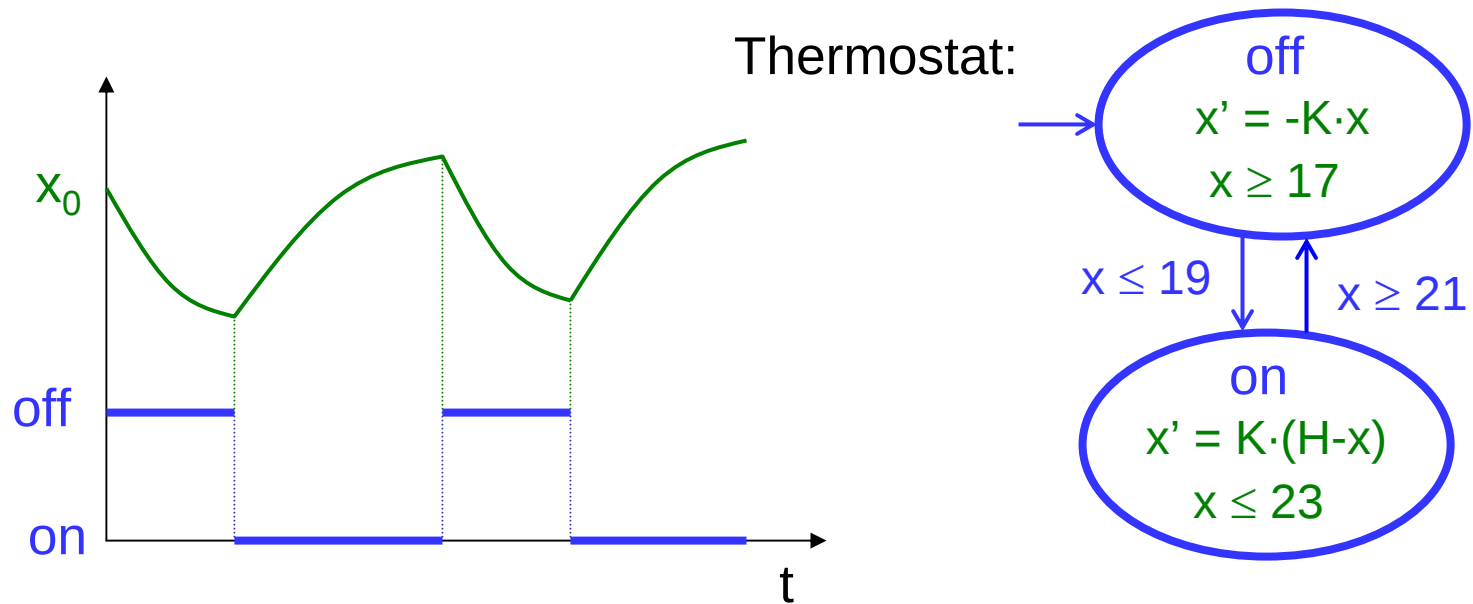


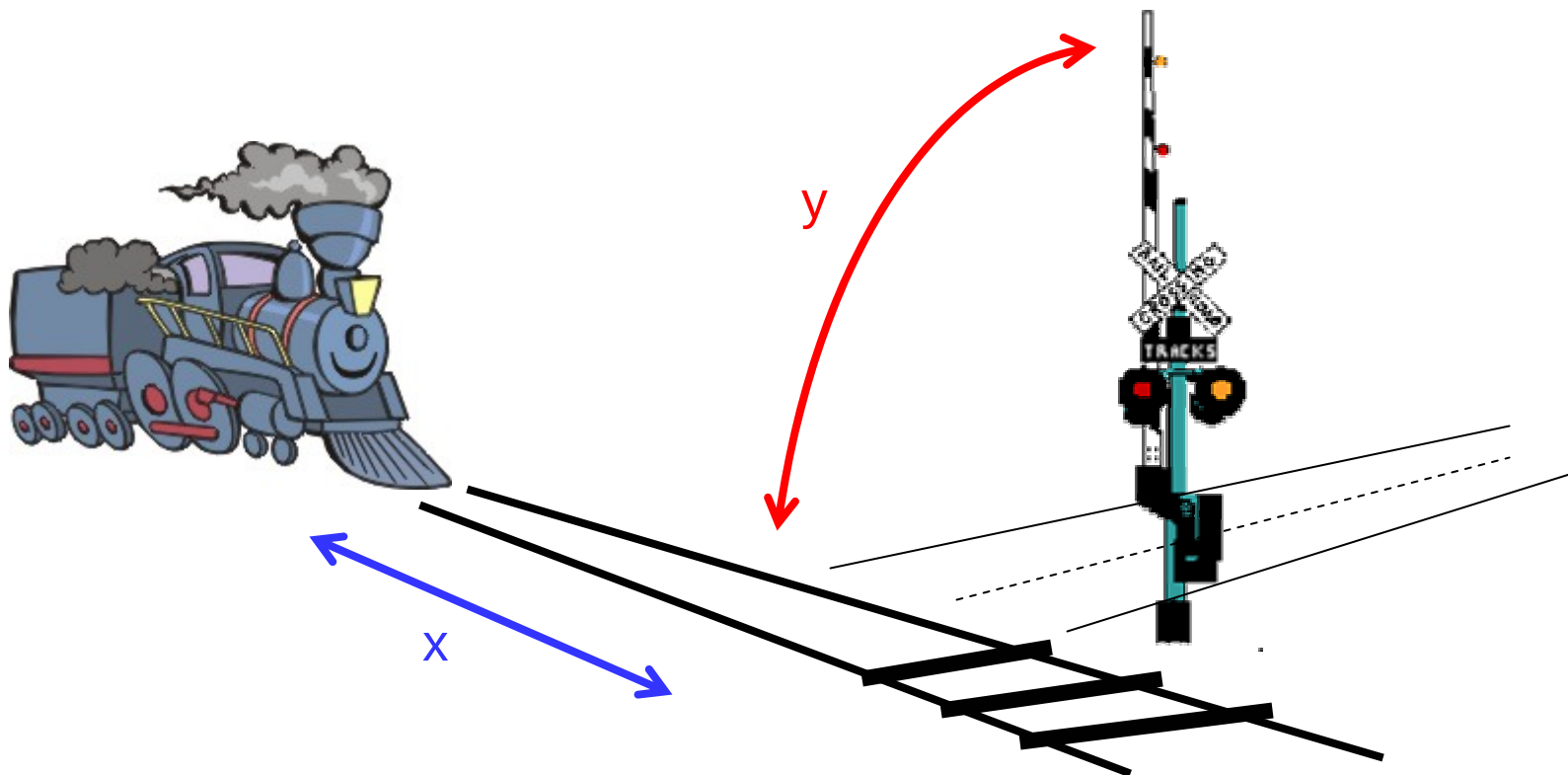
Combinatorial complexity.

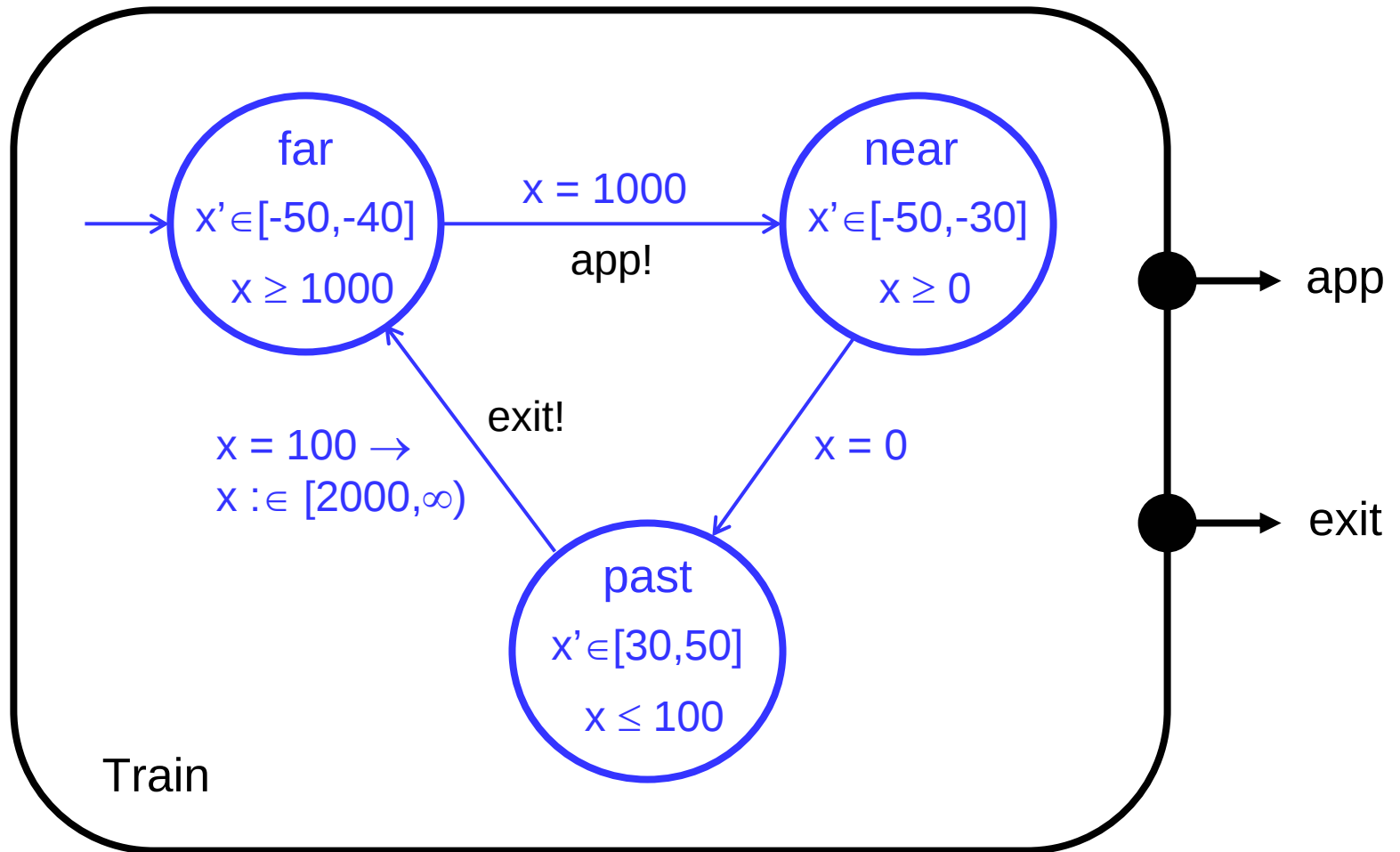
Hybrid Automaton

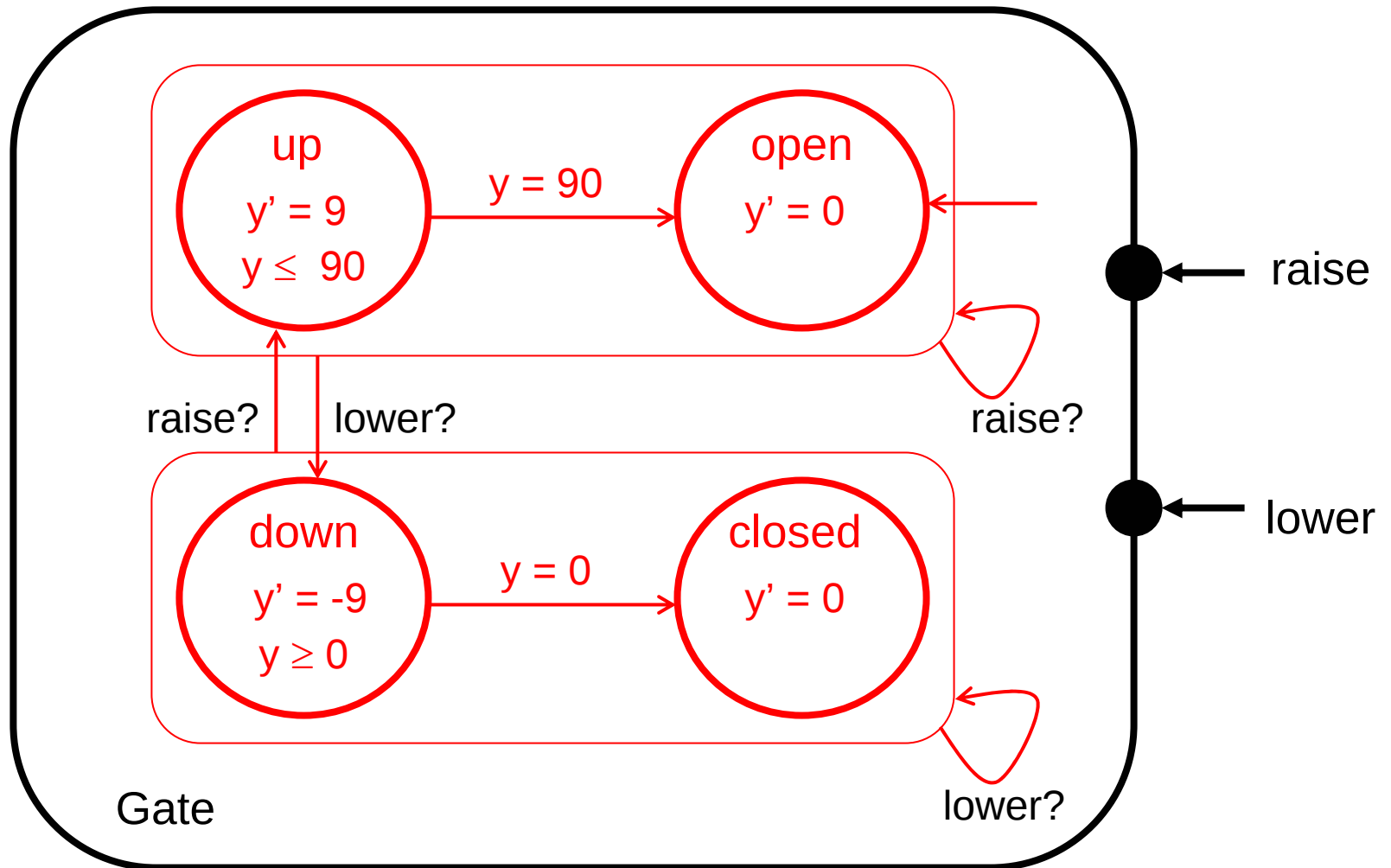
State space: $\mathbb{B}^m \times \mathbb{R}^n$

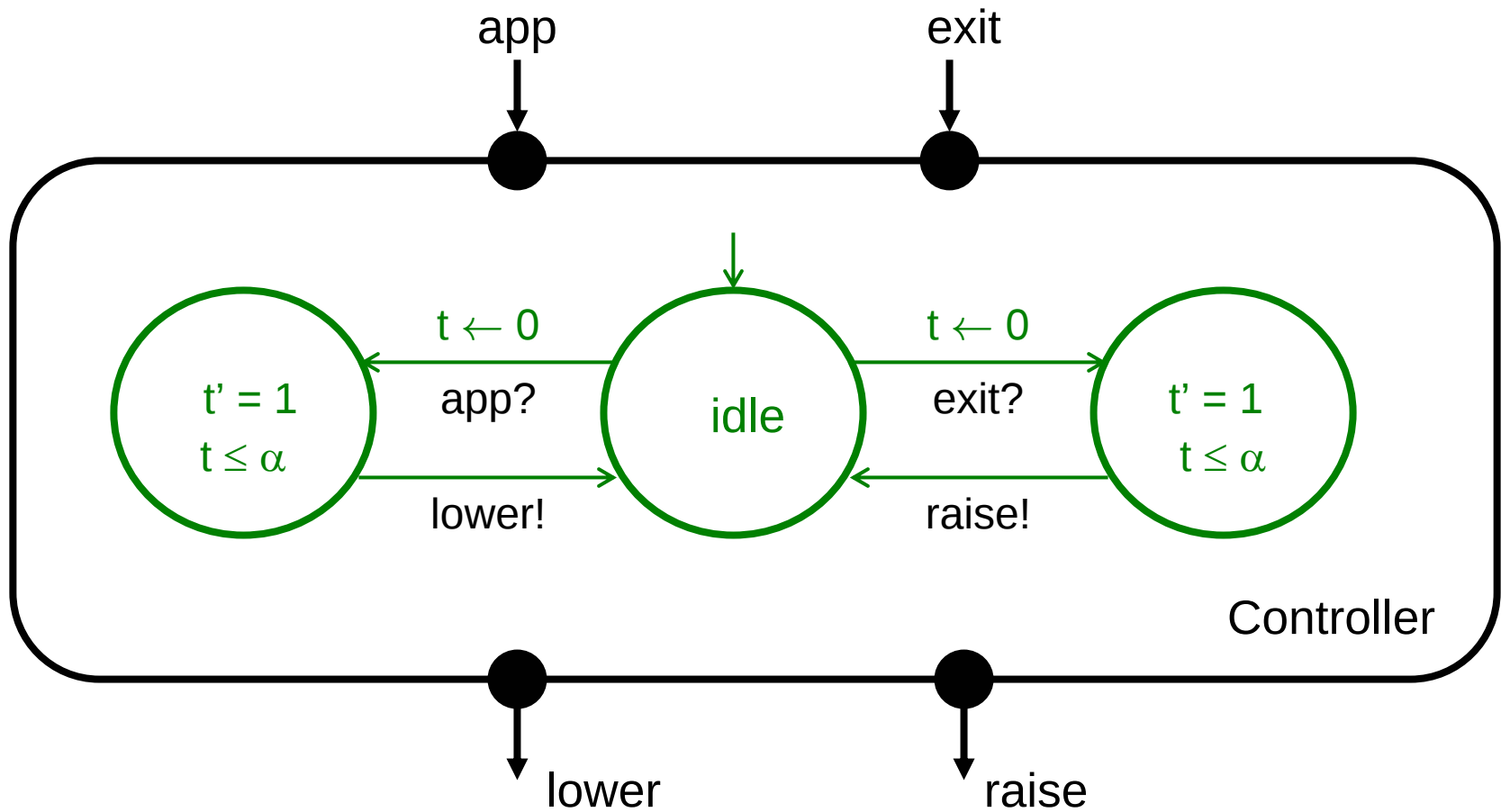
Dynamics: initial condition + state transitions
+ differential equations











α ... response time of the controller

Temporal Logic

Safety: $\forall \square (x \leq 10 \Rightarrow \text{Gate} = \text{closed})$



“on all trajectories, always”

Temporal Logic

Safety: $\forall \square (x \leq 10 \Rightarrow \text{Gate} = \text{closed})$

Liveness: $\forall \square (\text{Gate} = \text{closed} \Rightarrow \forall \diamond (\text{Gate} = \text{open}))$

“on all trajectories, eventually”

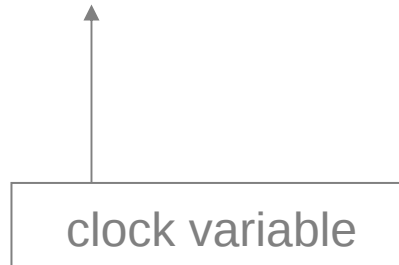


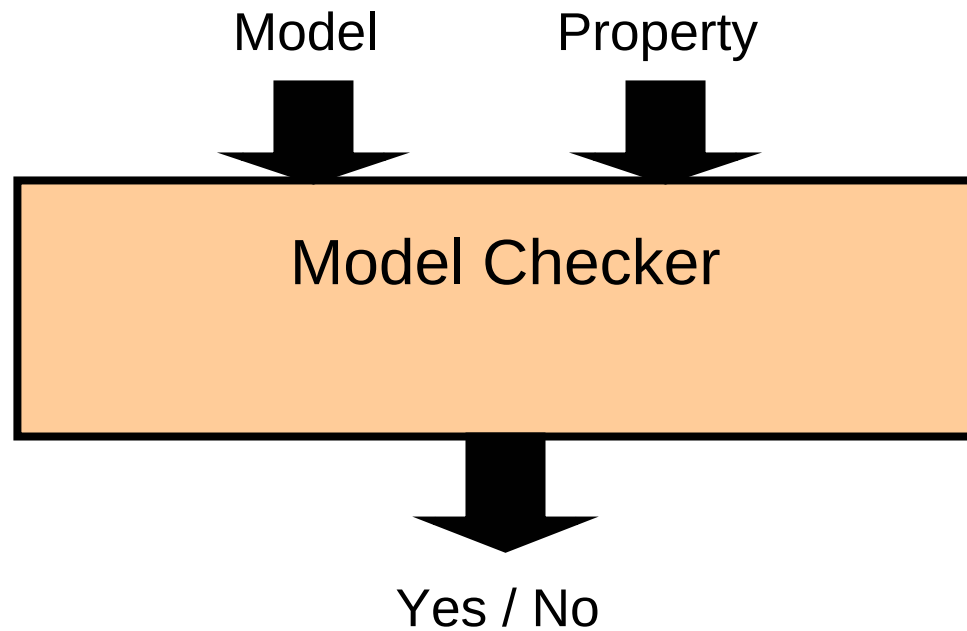
Temporal Logic

Safety: $\forall \Box (x \leq 10 \Rightarrow \text{Gate} = \text{closed})$

Liveness: $\forall \Box (\text{Gate} = \text{closed} \Rightarrow \forall \Diamond (\text{Gate} = \text{open}))$

Real time: $\forall \Box z \leftarrow 0. (z' = 1 \Rightarrow \forall \Diamond (\text{Gate} = \text{open} \wedge z \leq 60))$





Collection of
polyhedral
hybrid automata

Safety or
liveness or
real time

Model

Property

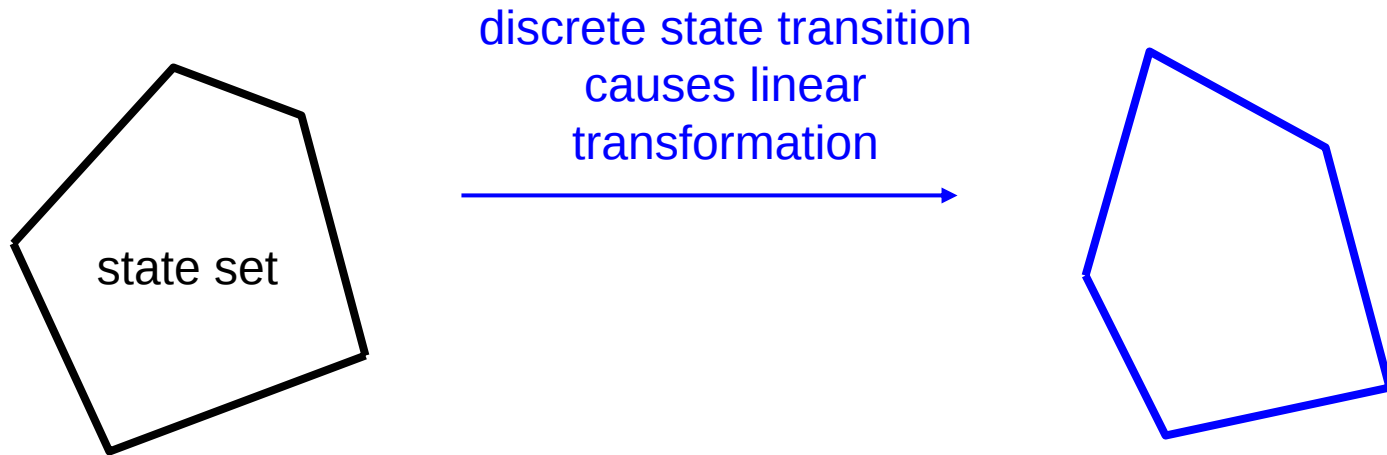
Model Checker

HyTech

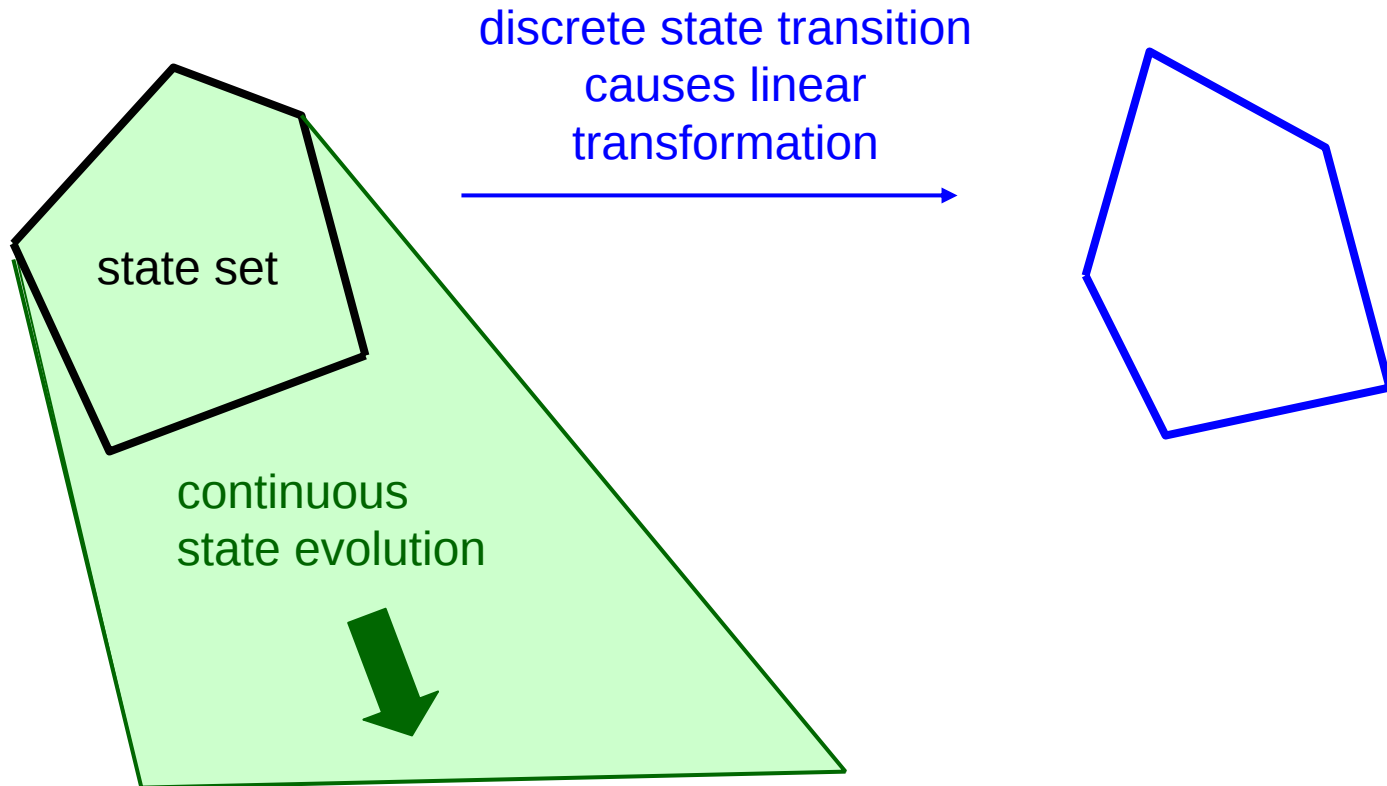
Condition under which the
model satisfies the property,
or error trajectory.

Example: "For which values of α is the controller safe?"

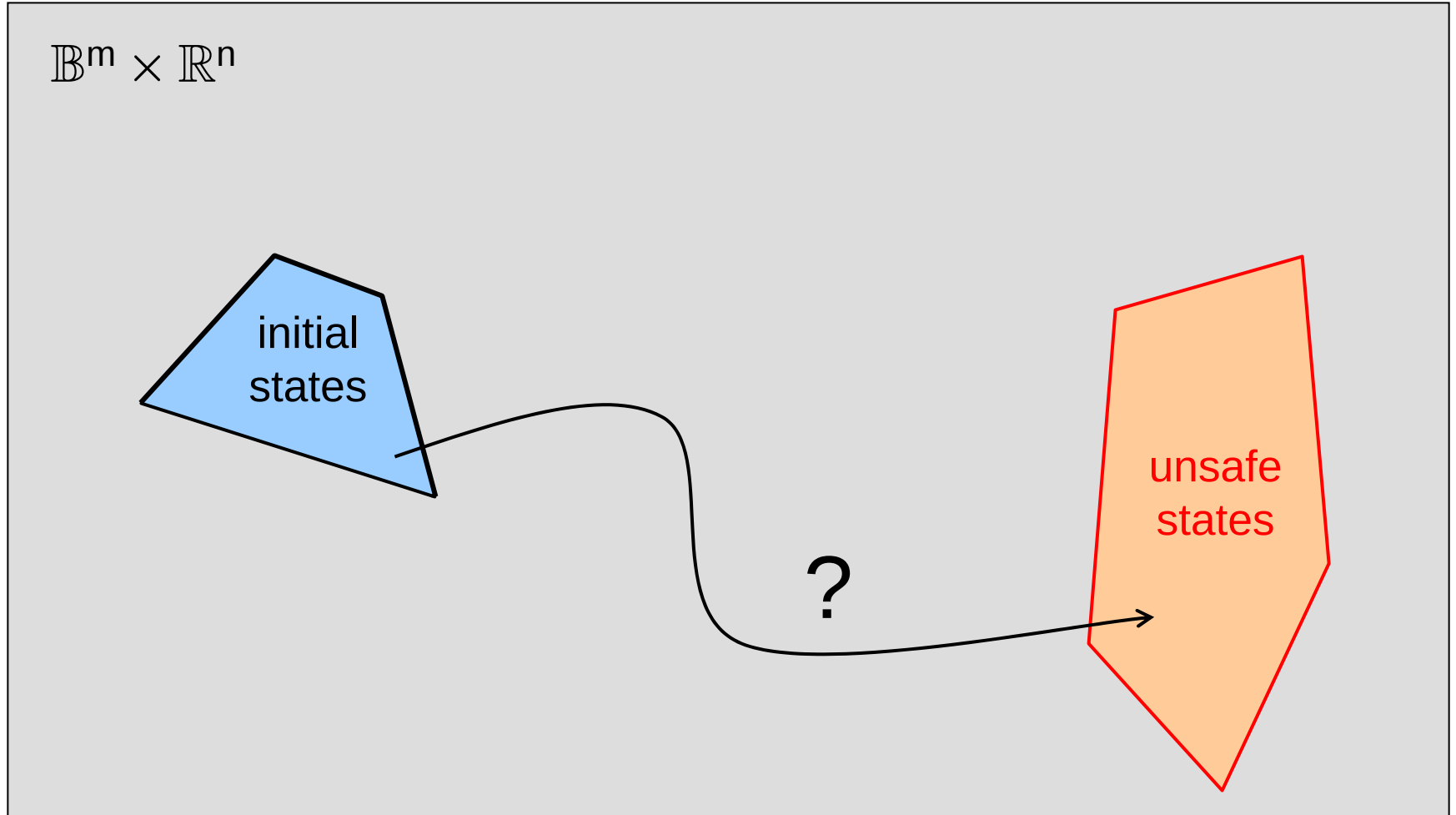
Each state change of a polyhedral hybrid automaton transforms a polyhedral set into a polyhedral set.



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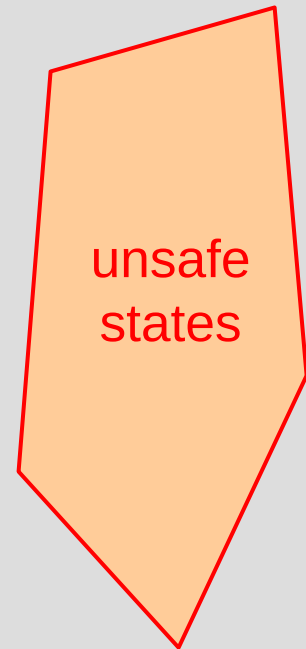
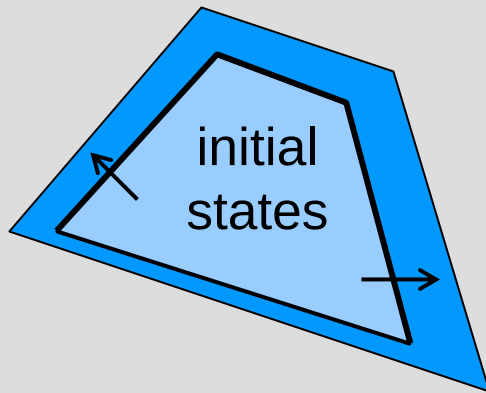


Model Checking for Safety



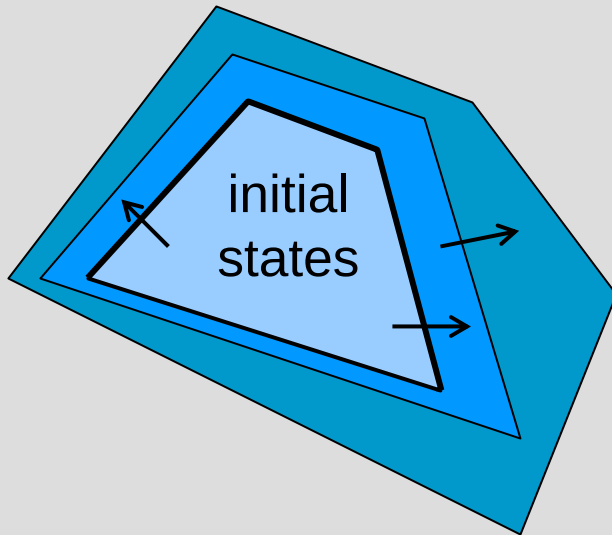
Model Checking for Safety

$\mathbb{B}^m \times \mathbb{R}^n$



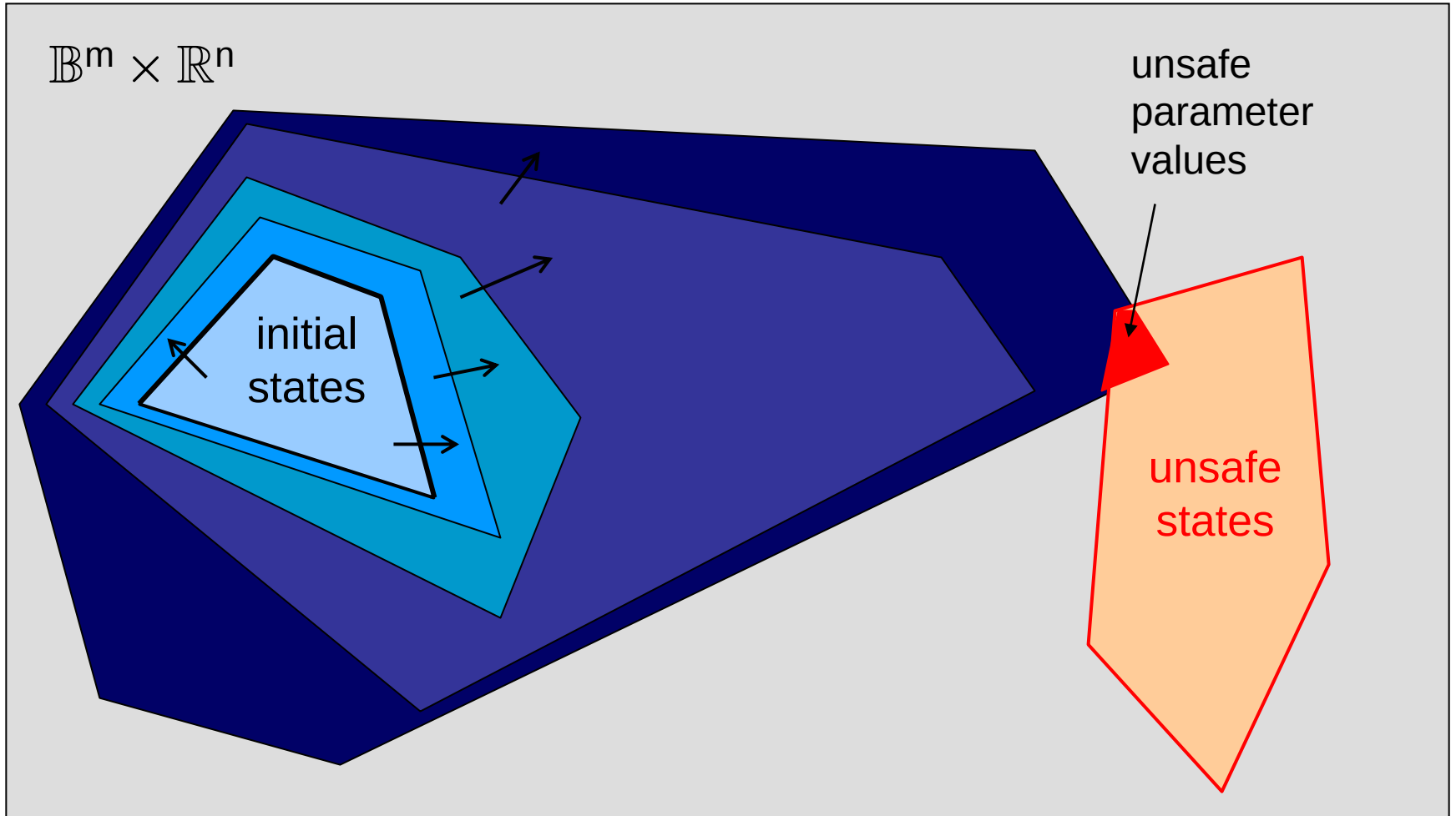
Model Checking for Safety

$\mathbb{B}^m \times \mathbb{R}^n$



unsafe
states

Model Checking for Safety



HyTech on Train + Gate + Controller



hytech-out.cgi.html

Applications of HyTech

- automotive engine control [Wong-Toi et al.]
- chemical plant control [Preussig et al.]
- flight control [Honeywell; Rockwell-Collins]
- air traffic control [Tomlin et al.]
- robot control [Corbett et al.]

Still a long way to go ...



Uptime: 123 years



Indeed, it will get worse before it gets better.



2004



2006



2007

Despite all the differences,
there are things we can learn from systems engineering:

Engineering

Theories of estimation
Theories of robustness

Computer Science

Theories of correctness

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there are things we can learn from systems engineering:

Engineering

Theories of estimation
Theories of robustness

Goal: build reliable systems.

Computer Science

Theories of correctness

*Temptation: programs are
mathematical objects; hence
we want to prove them correct.*

The MTC Mission Statement

Develop models and algorithms that let us **quantify** how the effort spent during **design** relates to the **quality** of the software product.

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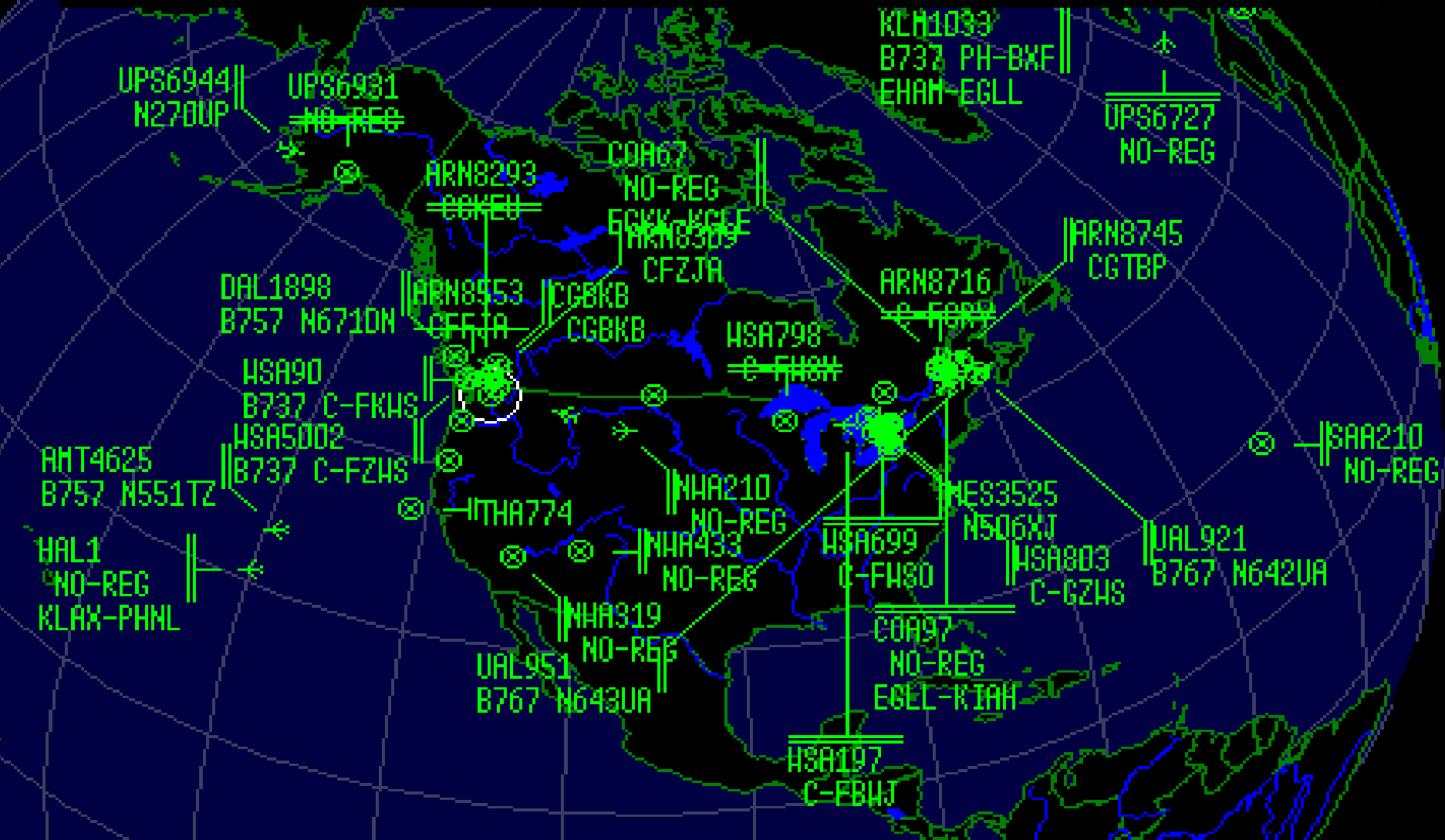
Not only programming, but especially system integration.



Not only functionality and performance, but also robustness (usability, fault tolerance, security).

September 14, 2004

Without warning, at about 5 p.m. PDT, air traffic controllers lost contact with about 400 airplanes they were tracking over the southwestern US. A backup system that was supposed to take over in such an event crashed within a minute after it was turned on.



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Inside the control system is a countdown timer that ticks off time in milliseconds. It starts out at the highest possible number that the system's server can handle: 2^{32} . When the counter reaches 0, the system shuts down.

Counting down from 2^{32} to 0 in milliseconds takes 50 days. The FAA procedure of having a technician reboot the system every 30 days resets the timer almost three weeks before it runs out of digits.

[IEEE Spectrum]



Thank you for your attention.



BC 350