Kinetic and Hyperbolic Equations with Applications to Engineering Processes

Axel-Stefan Häck, M.Sc.

IGPM — RWTH Aachen University

Talk in "Research Modelling Seminar"





Axel-Stefan Häck, M.Sc. (RWTH Aachen)



From Newtonian Mechanics to Boltzmann and Euler Equations



Modeling Steel Rolling Processes by fluid-like Differential Equations



Coupling Conditions by high-order Schemes



Model Hierarchy: General

• We are interested in Agent or Particle based dynamics.

- As an intermediate model we establish a Kinetic Model of such a process.
- Finally, we go over to a *Fluid Dynamics* model to describe the macroscopic behavior by rescaling the kinetic model.





Model Hierarchy: General

- We are interested in Agent or Particle based dynamics.
- As an intermediate model we establish a *Kinetic Model* of such a process.
- Finally, we go over to a *Fluid Dynamics* model to describe the macroscopic behavior by rescaling the kinetic model.





Model Hierarchy: General

- We are interested in Agent or Particle based dynamics.
- As an intermediate model we establish a *Kinetic Model* of such a process.
- Finally, we go over to a *Fluid Dynamics* model to describe the macroscopic behavior by rescaling the kinetic model.



- Newtonian Dynamic: free float and Elastic Collision of Hard Spheres of N(∈ N) atoms.
- Boltzmann equation as an mesoscopic kinetic model (featuring a mean-field).
- Introducing *Moments* and taking a *Hydrodynamic Limit* to gain a fluid dynamics model e.g. the *Euler Equations of Gas Dynamics*



- Newtonian Dynamic: free float and Elastic Collision of Hard Spheres of N(∈ N) atoms.
- Boltzmann equation as an mesoscopic kinetic model (featuring a mean-field).
- Introducing *Moments* and taking a *Hydrodynamic Limit* to gain a fluid dynamics model e.g. the *Euler Equations of Gas Dynamics*



- Newtonian Dynamic: free float and Elastic Collision of Hard Spheres of N(∈ N) atoms.
- Boltzmann equation as an mesoscopic kinetic model (featuring a mean-field).
- Introducing *Moments* and taking a *Hydrodynamic Limit* to gain a fluid dynamics model e.g. the *Euler Equations of Gas Dynamics*



- Newtonian Dynamic: free float and Elastic Collision of Hard Spheres of N(∈ N) atoms.
- Boltzmann equation as an mesoscopic kinetic model (featuring a mean-field).
- Introducing *Moments* and taking a *Hydrodynamic Limit* to gain a fluid dynamics model e.g. the *Euler Equations of Gas Dynamics*



Gas Dynamics: Pros and Cons of Model Level

- Newtonian dynamic is **physically accurate** but **expansive to compute** (*N* extremely large).
- Boltzmann equation can be discretized by less DoF (DoF<< N) but has a seven dimensional input (in 3D: position+velocity+time)!
- Euler equations describe larger space/time-scales with four dimensional input but lose description of microscopic fluctuations as well as velocity information.



Gas Dynamics: Pros and Cons of Model Level

- Newtonian dynamic is **physically accurate** but **expansive to compute** (*N* extremely large).
- Boltzmann equation can be discretized by less DoF (DoF<< N) but has a seven dimensional input (in 3D: position+velocity+time)!
- Euler equations describe larger space/time-scales with four dimensional input but lose description of microscopic fluctuations as well as velocity information.



Gas Dynamics: Pros and Cons of Model Level

- Newtonian dynamic is **physically accurate** but **expansive to compute** (*N* extremely large).
- Boltzmann equation can be discretized by less DoF (DoF<< N) but has a seven dimensional input (in 3D: position+velocity+time)!
- Euler equations describe larger space/time-scales with four dimensional input but lose description of microscopic fluctuations as well as velocity information.



Modeling Steel Rolling Processes by fluid-like Differential Equations



We model a single workpiece in a roll mill.

- The model considers the temperature **T** and thickness **g** of the workpiece and their evolution over time.
- We postulate a stochastic "transition" probability of the workpiece to either undergo a deformation process or not (transport of it or change of milling rolls).





- We model a single workpiece in a roll mill.
- The model considers the temperature **T** and thickness **g** of the workpiece and their evolution over time.
- We postulate a stochastic "transition" probability of the workpiece to either undergo a deformation process or not (transport of it or change of milling rolls).





- We model a single workpiece in a roll mill.
- The model considers the temperature **T** and thickness **g** of the workpiece and their evolution over time.
- We postulate a stochastic "transition" probability of the workpiece to either undergo a deformation process or not (transport of it or change of milling rolls).





• Let τ be a random processing time. We choose

$$P(\tau = s) = \Phi(s).$$

• In case of an rolling event the thickness undergoes the deformation

$$\mathbf{g}(t+\tau) = \mathbf{g}(t) - F(\mathbf{T}(t), \mathbf{g}(t), \tau).$$

Independent of the event (transport of rolling) we assume a temperature flux

$$\mathbf{T}(t+\tau) = \mathbf{T}(t) - \tau \ c(\mathbf{T}(t)).$$

• Let τ be a random processing time. We choose

$$P(\tau = s) = \Phi(s).$$

• In case of an rolling event the thickness undergoes the deformation

$$\mathbf{g}(t+\tau) = \mathbf{g}(t) - F(\mathbf{T}(t), \mathbf{g}(t), \tau).$$

Independent of the event (transport of rolling) we assume a temperature flux

$$\mathbf{T}(t+\tau) = \mathbf{T}(t) - \tau \ \mathbf{c}(\mathbf{T}(t)).$$

• Let τ be a random processing time. We choose

$$P(\tau = s) = \Phi(s).$$

• In case of an rolling event the thickness undergoes the deformation

$$\mathbf{g}(t+\tau) = \mathbf{g}(t) - F(\mathbf{T}(t), \mathbf{g}(t), \tau).$$

Independent of the event (transport of rolling) we assume a temperature flux

$$\mathbf{T}(t+\tau) = \mathbf{T}(t) - \tau \ c(\mathbf{T}(t)).$$



· We rescale the probability via

$$\omega(au) = rac{\Phi(au)}{\int_{ au}^{\infty} \Phi(s) ds}$$

and consider a small time-step $\Delta t > 0$. [M. Herty, C. Ringhofer, 2001].

• With probability $\omega(\tau(t))\Delta t$ we have (rolling):

$$\begin{aligned} \tau(t + \Delta t) &= 0, \\ \mathbf{g}(t + \Delta t) &= \mathbf{g}(t) - F(\mathbf{T}(t), \mathbf{g}(t), \tau), \\ \mathbf{T}(t + \Delta t) &= \mathbf{T}(t) - \Delta t c(\mathbf{T}(t)), \end{aligned}$$

• And with probability $1 - \omega(\tau(t))\Delta t$ (no rolling):

$$\tau(t + \Delta t) = \tau(t) + \Delta t,$$

$$\mathbf{g}(t + \Delta t) = \mathbf{g}(t),$$

$$\mathbf{T}(t + \Delta t) = \mathbf{T}(t) - \Delta t c(\mathbf{T}(t))$$

· We rescale the probability via

$$\omega(au) = rac{\Phi(au)}{\int_{ au}^{\infty} \Phi(s) ds}$$

and consider a small time-step $\Delta t > 0$. [M. Herty, C. Ringhofer, 2001].

• With probability $\omega(\tau(t))\Delta t$ we have (rolling):

$$\begin{aligned} \tau(t + \Delta t) &= 0, \\ \mathbf{g}(t + \Delta t) &= \mathbf{g}(t) - F(\mathbf{T}(t), \mathbf{g}(t), \tau), \\ \mathbf{T}(t + \Delta t) &= \mathbf{T}(t) - \Delta t c(\mathbf{T}(t)), \end{aligned}$$

• And with probability $1 - \omega(\tau(t))\Delta t$ (no rolling):

$$\tau(t + \Delta t) = \tau(t) + \Delta t,$$

$$\mathbf{g}(t + \Delta t) = \mathbf{g}(t),$$

$$\mathbf{T}(t + \Delta t) = \mathbf{T}(t) - \Delta tc(\mathbf{T}(t))$$

igpm _ ____

· We rescale the probability via

$$\omega(au) = rac{\Phi(au)}{\int_{ au}^{\infty} \Phi(s) ds}$$

and consider a small time-step $\Delta t > 0$. [M. Herty, C. Ringhofer, 2001].

• With probability $\omega(\tau(t))\Delta t$ we have (rolling):

$$\begin{aligned} \tau(t + \Delta t) &= 0, \\ \mathbf{g}(t + \Delta t) &= \mathbf{g}(t) - \mathcal{F}(\mathbf{T}(t), \mathbf{g}(t), \tau), \\ \mathbf{T}(t + \Delta t) &= \mathbf{T}(t) - \Delta t \mathbf{c}(\mathbf{T}(t)), \end{aligned}$$

• And with probability $1 - \omega(\tau(t))\Delta t$ (no rolling):

$$\tau(t + \Delta t) = \tau(t) + \Delta t,$$

$$\mathbf{g}(t + \Delta t) = \mathbf{g}(t),$$

$$\mathbf{T}(t + \Delta t) = \mathbf{T}(t) - \Delta t c(\mathbf{T}(t))$$

Transition Probability

 As the transition from state X = (τ, g, T) to state X' = (τ', g', T') in a time step Δt we have:

$$P(X, X') = (1 - \omega(\tau')\Delta t) \cdot \delta(\tau - (\tau' + \Delta t)) \cdot \delta(\mathbf{g} - \mathbf{g}') \cdot \delta(\mathbf{T} - (\mathbf{T}' - \Delta tc(\mathbf{T}'))) + \omega(\tau')\Delta t \cdot \delta(\tau) \cdot \delta(\mathbf{g} - (\mathbf{g}' - F(\mathbf{T}', \mathbf{g}', \tau')) \cdot \delta(\mathbf{T} - (\mathbf{T}' - \Delta tc(\mathbf{T}'))).$$

 Hence, the probability f(t, X) (kinetic model) to be in state X at time t evolves according to

$$f(t+\Delta t,X)=\int P(X,X')f(t,X')dX.$$



Transition Probability

 As the transition from state X = (τ, g, T) to state X' = (τ', g', T') in a time step Δt we have:

$$P(X, X') = (1 - \omega(\tau')\Delta t) \cdot \delta(\tau - (\tau' + \Delta t)) \cdot \delta(\mathbf{g} - \mathbf{g}') \cdot \delta(\mathbf{T} - (\mathbf{T}' - \Delta tc(\mathbf{T}'))) + \omega(\tau')\Delta t \cdot \delta(\tau) \cdot \delta(\mathbf{g} - (\mathbf{g}' - F(\mathbf{T}', \mathbf{g}', \tau')) \cdot \delta(\mathbf{T} - (\mathbf{T}' - \Delta tc(\mathbf{T}'))).$$

• Hence, the probability f(t, X) (kinetic model) to be in state X at time t evolves according to

$$f(t+\Delta t,X)=\int P(X,X')f(t,X')dX.$$



- Scaling frequency ω by $\hat{\omega} = \frac{\omega}{\Delta t}$,
- Taylor expansion w.r.t. Δt and considering resulting first-order dynamics (see Boltzmann limit),
- Scaling τ by $\frac{\tau}{\varepsilon}$ and take $\varepsilon \to 0$ (see hydrodynamic limit).



- Scaling frequency ω by $\hat{\omega} = \frac{\omega}{\Delta t}$,
- Taylor expansion w.r.t. Δt and considering resulting first-order dynamics (see Boltzmann limit),
- Scaling τ by $\frac{\tau}{\varepsilon}$ and take $\varepsilon \to 0$ (see hydrodynamic limit).



- Scaling frequency ω by $\hat{\omega} = \frac{\omega}{\Delta t}$,
- Taylor expansion w.r.t. Δt and considering resulting first-order dynamics (see Boltzmann limit),
- Scaling τ by $\frac{\tau}{\varepsilon}$ and take $\varepsilon \to 0$ (see hydrodynamic limit).



- Scaling frequency ω by $\hat{\omega} = \frac{\omega}{\Delta t}$,
- Taylor expansion w.r.t. Δ*t* and considering resulting first-order dynamics (see Boltzmann limit),
- Scaling τ by $\frac{\tau}{\varepsilon}$ and take $\varepsilon \to 0$ (see hydrodynamic limit).

Fluid-like PDE

The resulting PDE reads

$$f_t(t,\mathbf{g},\mathbf{T}) = \hat{\omega}(0) \left[\partial_{\mathbf{g}}(F_{\tau}(\mathbf{T},\mathbf{g},0)f(t,\mathbf{g},\mathbf{T})) + c(\mathbf{T})f_{\mathbf{T}}(t,\mathbf{g},\mathbf{T}) \right] + f(t,\mathbf{g},\mathbf{T})(1 + \hat{\omega}(0))(c(\mathbf{T}) - 1).$$



Simulations



1100 1200 1300 1400 1500 1600 Temperature in K



Interpretation of Results

- As desired, the resulting dynamics recovers a reduction in thickness and temperature of the initial workpieces,
- Some realistic properties of the deformation: hotter particles deform quicker.



Interpretation of Results

- As desired, the resulting dynamics recovers a reduction in thickness and temperature of the initial workpieces,
- Some realistic properties of the deformation: hotter particles deform quicker.



Potential Applications

- A credible model would offer the opportunity to predict stochastic quantities of a rolling process e.g. expectation value and variance of thickness,
- This would enable the possibility to control the production precess (choice of applied force),
- Desirable optimizations: Production time, minimizing variance (to name a few).

Potential Applications

- A credible model would offer the opportunity to predict stochastic quantities of a rolling process e.g. expectation value and variance of thickness,
- This would enable the possibility to control the production precess (choice of applied force),
- Desirable optimizations: Production time, minimizing variance (to name a few).

Potential Applications

- A credible model would offer the opportunity to predict stochastic quantities of a rolling process e.g. expectation value and variance of thickness,
- This would enable the possibility to control the production precess (choice of applied force),
- Desirable optimizations: Production time, minimizing variance (to name a few).

Remaining Modeling Steps

To gain a credible model it remains:

- Model $\omega(\cdot)$ after experimental data,
- Implement a higher-order approximation to the temperature flux $c(\cdot)$,
- Discriminate between temperature flux into air and into milling roll,
- Introduce uncertainties! on each step (in the particle dynamics) according to experimental data.
- Model $\omega(\cdot)$ after experimental data,
- Implement a higher-order approximation to the temperature flux $c(\cdot)$,
- Discriminate between temperature flux into air and into milling roll,
- Introduce uncertainties! on each step (in the particle dynamics) according to experimental data.

- Model $\omega(\cdot)$ after experimental data,
- Implement a higher-order approximation to the temperature flux $c(\cdot)$,
- Discriminate between temperature flux into air and into milling roll,
- Introduce uncertainties! on each step (in the particle dynamics) according to experimental data.

- Model $\omega(\cdot)$ after experimental data,
- Implement a higher-order approximation to the temperature flux $c(\cdot)$,
- Discriminate between temperature flux into air and into milling roll,
- Introduce uncertainties! on each step (in the particle dynamics) according to experimental data.



- Model $\omega(\cdot)$ after experimental data,
- Implement a higher-order approximation to the temperature flux $c(\cdot)$,
- Discriminate between temperature flux into air and into milling roll,
- Introduce uncertainties! on each step (in the particle dynamics) according to experimental data.



Coupling Conditions by high-order Schemes



• We consider a model of flow on graphs.

- A single vertex with n adjacent arcs (which we extend to infinity).
- All arcs are parameterized by [0,∞), such that the junction is located at x = 0 (for all arcs).
- We assume the flux f(·) ∈ C⁴(ℝ², ℝ²) and the u_j(t, x) : ℝ⁺₀ × ℝ⁺₀ to be the conserved states on the arcs j = 1,..., n





- We consider a model of flow on graphs.
- A single vertex with *n* adjacent arcs (which we extend to infinity).
- All arcs are parameterized by [0,∞), such that the junction is located at x = 0 (for all arcs).
- We assume the flux $f(\cdot) \in \mathscr{C}^4(\mathbb{R}^2, \mathbb{R}^2)$ and the $u_j(t, x) : \mathbb{R}^+_0 \times \mathbb{R}^+_0$ to be the conserved states on the arcs j = 1, ..., n





- We consider a model of flow on graphs.
- A single vertex with n adjacent arcs (which we extend to infinity).
- All arcs are parameterized by [0,∞), such that the junction is located at x = 0 (for all arcs).
- We assume the flux $f(\cdot) \in \mathscr{C}^4(\mathbb{R}^2, \mathbb{R}^2)$ and the $u_j(t, x) : \mathbb{R}^+_0 \times \mathbb{R}^+_0$ to be the conserved states on the arcs j = 1, ..., n





- We consider a model of flow on graphs.
- A single vertex with n adjacent arcs (which we extend to infinity).
- All arcs are parameterized by [0,∞), such that the junction is located at x = 0 (for all arcs).
- We assume the flux $f(\cdot) \in \mathscr{C}^4(\mathbb{R}^2, \mathbb{R}^2)$ and the $u_j(t, x) : \mathbb{R}^+_0 \times \mathbb{R}^+_0$ to be the conserved states on the arcs j = 1, ..., n



Problem Setting

$$\begin{aligned} \partial_t u_j + \partial_x f(u_j) &= 0, \ t \ge 0, x \ge 0, \\ u_j(0, x) &= u_{j,o}(x), \ x \ge 0, \\ \Psi(u_1(t, 0+), \dots, u_n(t, 0+)) &= 0, \ t \ge 0, \end{aligned} \tag{PDE}$$

where $\Psi : \mathbb{R}^{2n} \to \mathbb{R}^n$ is the (possibly nonlinear!) coupling condition. (PDE) are assumed to be strictly hyperbolic.

(Existence and uniqueness of solution in [R. M. Colombo, M. Herty, and V. Sachers, 2008].)

igpm

Let Ψ fulfill the transversality condition

$$det\left[D_1\Psi(\hat{u})r_2(\hat{u}_1),\ldots,D_n\Psi(\hat{u})r_2(\hat{u}_n)\right]\neq 0, \tag{TC}$$

- $D_j \Psi(\hat{u}) = \frac{\partial}{\partial u_j} \Psi(\hat{u}),$
- $\hat{u} \in \mathbb{R}^{2n}$ is a steady state solution to (PDE) (and $\Psi(\hat{u}) = 0$),
- Df(û_j) has a strictly negative λ¹(û_j) and a strictly positive eigenvalue λ²(û_j) with linearly independent (right) eigenvectors r₁(û_j) and r₂(û_j),
- Corresponding characteristic fields to be either genuine nonlinear or linearly degenerate.

Let Ψ fulfill the transversality condition

$$\det\left[D_1\Psi(\hat{u})r_2(\hat{u}_1),\ldots,D_n\Psi(\hat{u})r_2(\hat{u}_n)\right]\neq 0,\tag{TC}$$

- $D_j \Psi(\hat{u}) = \frac{\partial}{\partial u_j} \Psi(\hat{u}),$
- $\hat{u} \in \mathbb{R}^{2n}$ is a steady state solution to (PDE) (and $\Psi(\hat{u}) = 0$),
- Df(û_j) has a strictly negative λ¹(û_j) and a strictly positive eigenvalue λ²(û_j) with linearly independent (right) eigenvectors r₁(û_j) and r₂(û_j),
- Corresponding characteristic fields to be either genuine nonlinear or linearly degenerate.

Let Ψ fulfill the transversality condition

$$\det\left[D_1\Psi(\hat{u})r_2(\hat{u}_1),\ldots,D_n\Psi(\hat{u})r_2(\hat{u}_n)\right]\neq 0,\tag{TC}$$

- $D_j \Psi(\hat{u}) = \frac{\partial}{\partial u_j} \Psi(\hat{u}),$
- $\hat{u} \in \mathbb{R}^{2n}$ is a steady state solution to (PDE) (and $\Psi(\hat{u}) = 0$),
- Df(û_j) has a strictly negative λ¹(û_j) and a strictly positive eigenvalue λ²(û_j) with linearly independent (right) eigenvectors r₁(û_j) and r₂(û_j),
- Corresponding characteristic fields to be either genuine nonlinear or linearly degenerate.



Let Ψ fulfill the transversality condition

$$\det\left[D_1\Psi(\hat{u})r_2(\hat{u}_1),\ldots,D_n\Psi(\hat{u})r_2(\hat{u}_n)\right]\neq 0,\tag{TC}$$

- $D_j \Psi(\hat{u}) = \frac{\partial}{\partial u_j} \Psi(\hat{u}),$
- $\hat{u} \in \mathbb{R}^{2n}$ is a steady state solution to (PDE) (and $\Psi(\hat{u}) = 0$),
- Df(û_j) has a strictly negative λ¹(û_j) and a strictly positive eigenvalue λ²(û_j) with linearly independent (right) eigenvectors r₁(û_j) and r₂(û_j),
- Corresponding characteristic fields to be either genuine nonlinear or linearly degenerate.

Let Ψ fulfill the transversality condition

$$\det\left[D_1\Psi(\hat{u})r_2(\hat{u}_1),\ldots,D_n\Psi(\hat{u})r_2(\hat{u}_n)\right]\neq 0,\tag{TC}$$

where

- $D_j \Psi(\hat{u}) = \frac{\partial}{\partial u_j} \Psi(\hat{u}),$
- $\hat{u} \in \mathbb{R}^{2n}$ is a steady state solution to (PDE) (and $\Psi(\hat{u}) = 0$),
- Df(û_j) has a strictly negative λ¹(û_j) and a strictly positive eigenvalue λ²(û_j) with linearly independent (right) eigenvectors r₁(û_j) and r₂(û_j),
- Corresponding characteristic fields to be either genuine nonlinear or linearly degenerate.

igpm

Finite Volume

 The discretization for each u_i (seperately) is done by a finite volume method, where the cell average U^m_{i,i} of u_j in cell i at time t^m is given by

$$U_{j,i}^{m} := \frac{1}{\Delta x} \int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} u_{j}(x, t^{m}) dx,$$

• Its evolution over Δt follows

$$U_{j,i}^{m+1} = U_{j,i}^{m} - \frac{1}{\Delta x} \left((\mathscr{F}_{j})_{i+\frac{1}{2}} - (\mathscr{F}_{j})_{i-\frac{1}{2}} \right).$$
(FVM)



Finite Volume

 The discretization for each u_i (seperately) is done by a finite volume method, where the cell average U^m_{i,i} of u_j in cell i at time t^m is given by

$$U_{j,i}^{m} := \frac{1}{\Delta x} \int_{x_{i-\frac{1}{2}}}^{x_{i+\frac{1}{2}}} u_{j}(x, t^{m}) dx,$$

• Its evolution over Δt follows

$$U_{j,i}^{m+1} = U_{j,i}^{m} - \frac{1}{\Delta x} \left((\mathscr{F}_{j})_{i+\frac{1}{2}} - (\mathscr{F}_{j})_{i-\frac{1}{2}} \right).$$
(FVM)



· The flux across the cell interfaces is given by

$$(\mathscr{F}_{j})_{i+\frac{1}{2}} = \int_{t^{m}}^{t^{m+1}} f\left(u_{j}\left(x_{i+\frac{1}{2}},s\right)\right) ds.$$

- We will use a second order approximation!
- By (CC) we get boundary conditions for (PDE) at x = 0!
- The cell average at the first cell *i* = 0 at time *t^m* is given by the states *u^m_{j,0}*,
 j = 1,...,*n*. We assume them to be sufficiently close to *û_i* such that (TC) holds.

· The flux across the cell interfaces is given by

$$(\mathscr{F}_{j})_{i+\frac{1}{2}} = \int_{t^{m}}^{t^{m+1}} f\left(u_{j}\left(x_{i+\frac{1}{2}},s\right)\right) ds.$$

- We will use a second order approximation!
- By (CC) we get boundary conditions for (PDE) at x = 0!
- The cell average at the first cell i = 0 at time t^m is given by the states $u_{j,0}^m$, j = 1, ..., n. We assume them to be sufficiently close to \hat{u}_j such that (TC) holds.

· The flux across the cell interfaces is given by

$$(\mathscr{F}_{j})_{i+\frac{1}{2}} = \int_{t^{m}}^{t^{m+1}} f\left(u_{j}\left(x_{i+\frac{1}{2}},s\right)\right) ds.$$

- We will use a second order approximation!
- By (CC) we get boundary conditions for (PDE) at x = 0!
- The cell average at the first cell *i* = 0 at time *t^m* is given by the states *u^m_{j,0}*,
 j = 1,...,*n*. We assume them to be sufficiently close to *û_i* such that (TC) holds.

· The flux across the cell interfaces is given by

$$(\mathscr{F}_{j})_{i+\frac{1}{2}} = \int_{t^{m}}^{t^{m+1}} f\left(u_{j}\left(x_{i+\frac{1}{2}},s\right)\right) ds.$$

- We will use a second order approximation!
- By (CC) we get boundary conditions for (PDE) at x = 0!
- The cell average at the first cell i = 0 at time t^m is given by the states $u_{j,0}^m$, j = 1, ..., n. We assume them to be sufficiently close to \hat{u}_i such that (TC) holds.

iapm/____

Characteristic Splitting

- Let $s \to \mathscr{L}_{\kappa}(u_o, s)$ the κ -th Lax curve through the state u_o for $\kappa = 1, 2$.
- We find (s_1^*, \ldots, s_n^*) (e.g. using *Newton's method*) to solve

$$\Psi\left(\mathscr{L}_{2}(U_{1,0}^{m},s_{1}),\ldots,\mathscr{L}_{2}(U_{n,0}^{m},s_{n})\right)\stackrel{!}{=}0$$

which exists and is unique due to (TC). (This is zero order data only!)



Characteristic Splitting

- Let $s \to \mathscr{L}_{\kappa}(u_o, s)$ the κ -th Lax curve through the state u_o for $\kappa = 1, 2$.
- We find (s_1^*, \ldots, s_n^*) (e.g. using *Newton's method*) to solve

$$\Psi\left(\mathscr{L}_{2}(U_{1,0}^{m}, \boldsymbol{s}_{1}), \ldots, \mathscr{L}_{2}(U_{n,0}^{m}, \boldsymbol{s}_{n})\right) \stackrel{!}{=} 0$$

which exists and is unique due to (TC). (This is zero order data only!)



Extend numerical Scheme to Boundary Values (in the Vertex).



Step 0: First order data at x=0

We can now calculate the boundary cell value $U_{j,0}^{m+1}$ at time t^{m+1} by (FVM) for i = 0 by using

$$U_{j,-1}^m := \mathscr{L}_2\left(U_{j,0}^m, \boldsymbol{s}_j^*\right). \tag{GC}$$

(Hence, we obtain a first-order approximation to the coupling condition as well as to the solution u_j .)

Step 1: Reconstruction

• Given the cell averages $U_{j,i}^m$ we reconstruct a p.w. linear function $u_j(x, t_m)$ and each cell $\left[x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}\right]$.

(This is standard: MUSCL scheme.)

• In the first cell i = 0 the slope reconstruction will utilize the data gained in (GC) to calculate $\sigma_{j,0}$.

We obtain a p.w. linear reconstruction

$$U_{j}(x,t^{m}) = \sigma_{j,i}(x-x_{i}) + U_{j,i}^{m}, \qquad x_{i-\frac{1}{2}} \le x \le x_{i+\frac{1}{2}}, \ i = 0, \dots,$$
(1)

where $\sigma_{i,i}$ is the vector of slopes.

 This way we get distinct values at each interface (in the spatial domain, as well as at the vertex) which we will denote by the values at x_{i+1}∓.

iapm/____

Step 1: Reconstruction

• Given the cell averages $U_{j,i}^m$ we reconstruct a p.w. linear function $u_j(x, t_m)$ and each cell $\left[x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}\right]$.

(This is standard: MUSCL scheme.)

• In the first cell *i* = 0 the slope reconstruction will utilize the data gained in (GC) to calculate $\sigma_{j,0}$.

We obtain a p.w. linear reconstruction

$$U_{j}(x,t^{m}) = \sigma_{j,i}(x-x_{i}) + U_{j,i}^{m}, \qquad x_{i-\frac{1}{2}} \le x \le x_{i+\frac{1}{2}}, \ i = 0, \dots,$$
(1)

where $\sigma_{i,i}$ is the vector of slopes.

 This way we get distinct values at each interface (in the spatial domain, as well as at the vertex) which we will denote by the values at x_{i+1}∓.

igpm _____

Step 1: Reconstruction

• Given the cell averages $U_{j,i}^m$ we reconstruct a p.w. linear function $u_j(x, t_m)$ and each cell $\left[x_{i-\frac{1}{2}}, x_{i+\frac{1}{2}}\right]$.

(This is standard: MUSCL scheme.)

• In the first cell *i* = 0 the slope reconstruction will utilize the data gained in (GC) to calculate $\sigma_{j,0}$.

We obtain a p.w. linear reconstruction

$$U_{j}(x,t^{m}) = \sigma_{j,i}(x-x_{i}) + U_{j,i}^{m}, \qquad x_{i-\frac{1}{2}} \le x \le x_{i+\frac{1}{2}}, \ i = 0, \dots,$$
(1)

where $\sigma_{i,i}$ is the vector of slopes.

 This way we get distinct values at each interface (in the spatial domain, as well as at the vertex) which we will denote by the values at x_{i+1}⁺⁺⁺.

igpm _

Step 2: Reconstruction at boundary

Reconstruct for each arc *j* a piecewise linear function v_j(t) for t^m ≤ t ≤ t^{m+1} such that

$$\frac{d}{dt}\Psi(v_1(t),\ldots,v_n(t))|_{t=t^m}=0.$$

Let the solution be $(\dot{v}_1, \dots, \dot{v}_j)$. (Solution exists due to (TC).)

• First order data of $v_i(t)$ already gained by (GC).



Step 2: Reconstruction at boundary

Reconstruct for each arc *j* a piecewise linear function v_j(t) for t^m ≤ t ≤ t^{m+1} such that

$$\frac{d}{dt}\Psi(v_1(t),\ldots,v_n(t))|_{t=t^m}=0.$$

Let the solution be $(\dot{v}_1, \dots, \dot{v}_j)$. (Solution exists due to (TC).)

• First order data of $v_i(t)$ already gained by (GC).

Step 3: Second order flow

Using the *Midpoint rule* for the flux (at the interfaces), Taylor expansion (on f^{\pm}) and the p.w. linear reconstruction of u_i we get:

$$U_{j,i-}^{m} := U_{j,i}^{m} + \sigma_{j,i} \frac{\Delta x}{2}, \ U_{j,i+}^{m} := U_{j,i+1}^{m} - \sigma_{j,i+1} \frac{\Delta x}{2},$$
$$\frac{1}{\Delta x} (\mathscr{F}_{j})_{i+\frac{1}{2}} \approx \frac{\Delta t}{\Delta x} \left[f^{+} \left(U_{j,i-}^{m} - \frac{\Delta t}{2} Df(U_{j,i-}^{m}) \sigma_{j,i} \right) + f^{-} \left(U_{j,i+}^{m} - \frac{\Delta t}{2} Df(U_{j,i+}^{m}) \sigma_{j,i+1} \right) \right],$$

where the flux is splitted as

$$f(u) = f^{+}(u) + f^{-}(u) := \frac{1}{2}(f(u) + au) + \frac{1}{2}(f(u) - au),$$

with $a = \lambda_{max}$. [A. Kurganov, E. Tadmor, 2000].

igpm/____

Step 4: Second order flow at boundary

- We need to evaluate the flux at the boundary (ℱ_j)_{-1/2}. By (GC) and Step 2 of the algorithm the characteristic speed of information is non-negative.
- Using the midpoint rule:

$$\begin{aligned} (\mathscr{F}_j)_{-\frac{1}{2}} &= \int_{t^m}^{t^{m+1}} f\left(u_j\left(x_{-\frac{1}{2}},s\right)\right) ds \\ &\approx \int_{t^m}^{t^{m+1}} f(v_j(s)) ds = \Delta t f\left(v_j\left(t^{m+\frac{1}{2}}\right)\right) + \mathscr{O}\left((\Delta t)^3\right). \end{aligned}$$

Therefore, the boundary flux is given by

$$\frac{1}{\Delta x}(\mathscr{F}_j)_{-\frac{1}{2}} \approx \frac{\Delta t}{\Delta x} f\left(v_j + \frac{\Delta t}{2}\dot{v}_j\right). \tag{BF}$$



Step 4: Second order flow at boundary

- We need to evaluate the flux at the boundary (ℱ_j)_{-1/2}. By (GC) and Step 2 of the algorithm the characteristic speed of information is non-negative.
- Using the midpoint rule:

$$(\mathscr{F}_{j})_{-\frac{1}{2}} = \int_{t^{m}}^{t^{m+1}} f\left(u_{j}\left(x_{-\frac{1}{2}},s\right)\right) ds$$
$$\approx \int_{t^{m}}^{t^{m+1}} f(v_{j}(s)) ds = \Delta t f\left(v_{j}\left(t^{m+\frac{1}{2}}\right)\right) + \mathscr{O}\left((\Delta t)^{3}\right).$$

Therefore, the boundary flux is given by

$$\frac{1}{\Delta x}(\mathscr{F}_j)_{-\frac{1}{2}} \approx \frac{\Delta t}{\Delta x} f\left(v_j + \frac{\Delta t}{2}\dot{v}_j\right). \tag{BF}$$

Step 4: Second order flow at boundary

- We need to evaluate the flux at the boundary (ℱ_j)_{-1/2}. By (GC) and Step 2 of the algorithm the characteristic speed of information is non-negative.
- Using the midpoint rule:

$$(\mathscr{F}_{j})_{-\frac{1}{2}} = \int_{t^{m}}^{t^{m+1}} f\left(u_{j}\left(x_{-\frac{1}{2}},s\right)\right) ds$$
$$\approx \int_{t^{m}}^{t^{m+1}} f(v_{j}(s)) ds = \Delta t f\left(v_{j}\left(t^{m+\frac{1}{2}}\right)\right) + \mathscr{O}\left((\Delta t)^{3}\right).$$

Therefore, the boundary flux is given by

$$\frac{1}{\Delta x}(\mathscr{F}_j)_{-\frac{1}{2}} \approx \frac{\Delta t}{\Delta x} f\left(v_j + \frac{\Delta t}{2}\dot{v}_j\right). \tag{BF}$$

Step 5: Update

Evolve the dynamics according to equation (FVM) for i = 1, ..., to obtain the new cell averages at time t^{m+1} and proceed with STEP 1.



Calculate Step 2

Using the p.w. linear reconstruction

$$u_{j}\left(x_{-\frac{1}{2}},t^{m}\right) = U_{j,0}^{m} - \frac{\Delta x}{2}\sigma_{j,0}$$

to get second order accurate boundary values.

We determine the vector s = (s₁,...,s_n) ∈ ℝⁿ by solving the possibly nonlinear equation:

$$\Psi\left(\mathscr{L}_2\left(U_{1,0}^m-\frac{\Delta x}{2}\sigma_{1,0},s_1\right),\ldots,\mathscr{L}_2\left(U_{n,0}^m-\frac{\Delta x}{2}\sigma_{n,0},s_n\right)\right)=0.$$

• Since we want Ψ to hold for $t > t^m$ we solve:

$$0 = \frac{d}{dt}\Psi(u_1(t, 0+), \dots, u_n(t, 0+))$$

= $\sum_{k=1}^n D_{u_k}\Psi(u_1(t, 0+), \dots, u_n(t, 0+))\partial_t u_k(t, 0+).$

iapm/ ...
Calculate Step 2

Using the p.w. linear reconstruction

$$u_{j}\left(x_{-\frac{1}{2}},t^{m}\right) = U_{j,0}^{m} - \frac{\Delta x}{2}\sigma_{j,0}$$

to get second order accurate boundary values.

We determine the vector s = (s₁,...,s_n) ∈ ℝⁿ by solving the possibly nonlinear equation:

$$\Psi\left(\mathscr{L}_{2}\left(U_{1,0}^{m}-\frac{\Delta x}{2}\sigma_{1,0},s_{1}\right),\ldots,\mathscr{L}_{2}\left(U_{n,0}^{m}-\frac{\Delta x}{2}\sigma_{n,0},s_{n}\right)\right)=0.$$

• Since we want Ψ to hold for $t > t^m$ we solve:

$$0 = \frac{d}{dt} \Psi(u_1(t, 0+), \dots, u_n(t, 0+))$$

= $\sum_{k=1}^n D_{u_k} \Psi(u_1(t, 0+), \dots, u_n(t, 0+)) \partial_t u_k(t, 0+).$

iapm/

Calculate Step 2

Using the p.w. linear reconstruction

$$u_{j}\left(x_{-\frac{1}{2}},t^{m}\right) = U_{j,0}^{m} - \frac{\Delta x}{2}\sigma_{j,0}$$

to get second order accurate boundary values.

We determine the vector s = (s₁,...,s_n) ∈ ℝⁿ by solving the possibly nonlinear equation:

$$\Psi\left(\mathscr{L}_{2}\left(U_{1,0}^{m}-\frac{\Delta x}{2}\sigma_{1,0},s_{1}\right),\ldots,\mathscr{L}_{2}\left(U_{n,0}^{m}-\frac{\Delta x}{2}\sigma_{n,0},s_{n}\right)\right)=0.$$

Since we want Ψ to hold for t > t^m we solve:

$$0 = \frac{d}{dt}\Psi(u_1(t, 0+), \dots, u_n(t, 0+))$$

= $\sum_{k=1}^n D_{u_k}\Psi(u_1(t, 0+), \dots, u_n(t, 0+))\partial_t u_k(t, 0+).$

iapm/____

Lemma: Second order CC

Lemma:

Consider a single node with *n* connected arcs and let t^m be some positive time. Let $\Psi \in C^2(\mathbb{R}^{2n};\mathbb{R}^n)$ and let $\hat{u}_j := U_{i,0}^m - \frac{\Delta x}{2}$ be such that condition (TC) holds true.

Then, for $v_j(t)$ as in the the previous construction, the coupling condition is satisfied up to second order in time

$$\Psi(\mathbf{v}_1(t),\ldots,\mathbf{v}_n(t))=\mathscr{O}\left((t-t^m)^2\right).$$





Application: Gas Dynamics



• We will connect two arcs j = 1, 2.

• We consider isothermal Euler equations, where the conservation law reads:

$$\partial_t \begin{pmatrix} \rho_j \\ q_j \end{pmatrix} + \partial_x \begin{pmatrix} q_j \\ a^2 \rho_j + \frac{q_j^2}{\rho_j} \end{pmatrix} = 0, \ a > 0 \ \left(U = \begin{pmatrix} \rho \\ q \end{pmatrix} \right)$$

- $\Psi^1(U_1(t,0+), U_2(t,0+)) = q_1(t,0+) + q_2(t,0+)$ and • $\Psi^2(U_1(t,0+), U_2(t,0+)) = \left(-\frac{2}{2} e_1(t,0+) + \frac{q_2^2(t,0+)}{2} \right) + \left(-\frac{2}{2} e_2(t,0+) + \frac{q_2^2(t,0+)}{2} \right)$
- $\Psi^2(U_1(t,0+),U_2(t,0+)) = \left(a^2\rho_2(t,0+) + \frac{q_2^2(t,0+)}{\rho_2(t,0+)}\right) + \left(a^2\rho_1(t,0+) + \frac{q_1^2(t,0+)}{\rho_1(t,0+)}\right).$

- We will connect two arcs j = 1, 2.
- We consider isothermal Euler equations, where the conservation law reads:

$$\partial_t \begin{pmatrix} \rho_j \\ q_j \end{pmatrix} + \partial_x \begin{pmatrix} q_j \\ a^2 \rho_j + \frac{q_j^2}{\rho_j} \end{pmatrix} = 0, \ a > 0 \ \left(U = \begin{pmatrix} \rho \\ q \end{pmatrix} \right).$$

• $\Psi^1(U_1(t,0+), U_2(t,0+)) = q_1(t,0+) + q_2(t,0+)$ and • $\Psi^2(U_1(t,0+), U_2(t,0+)) = \left(a^2\rho_2(t,0+) + \frac{q_2^2(t,0+)}{\rho_2(t,0+)}\right) + \left(a^2\rho_1(t,0+) + \frac{q_1^2(t,0+)}{\rho_1(t,0+)}\right).$

- We will connect two arcs j = 1, 2.
- We consider isothermal Euler equations, where the conservation law reads:

$$\partial_t \begin{pmatrix} \rho_j \\ q_j \end{pmatrix} + \partial_x \begin{pmatrix} q_j \\ a^2 \rho_j + \frac{q_j^2}{\rho_j} \end{pmatrix} = 0, \ a > 0 \ \left(U = \begin{pmatrix} \rho \\ q \end{pmatrix} \right).$$

- $\Psi^1(U_1(t,0+),U_2(t,0+)) = q_1(t,0+) + q_2(t,0+)$ and
- $\Psi^2(U_1(t,0+),U_2(t,0+)) = \left(a^2\rho_2(t,0+) + \frac{q_2^2(t,0+)}{\rho_2(t,0+)}\right) + \left(a^2\rho_1(t,0+) + \frac{q_1^2(t,0+)}{\rho_1(t,0+)}\right).$

- We will connect two arcs j = 1, 2.
- We consider isothermal Euler equations, where the conservation law reads:

$$\partial_t \begin{pmatrix} \rho_j \\ q_j \end{pmatrix} + \partial_x \begin{pmatrix} q_j \\ a^2 \rho_j + \frac{q_j^2}{\rho_j} \end{pmatrix} = 0, \ a > 0 \ \left(U = \begin{pmatrix} \rho \\ q \end{pmatrix} \right).$$

- $\Psi^1(U_1(t,0+),U_2(t,0+)) = q_1(t,0+) + q_2(t,0+)$ and
- $\Psi^2(U_1(t,0+),U_2(t,0+)) = \left(a^2\rho_2(t,0+) + \frac{q_2^2(t,0+)}{\rho_2(t,0+)}\right) + \left(a^2\rho_1(t,0+) + \frac{q_1^2(t,0+)}{\rho_1(t,0+)}\right).$

- For subsonical states U_j we have $\lambda_i^1 < 0$ and $\lambda_i^2 > 0$.
- For small $t t^m$ we use the decomposition $U_j(t^m, 0+) = v_j^1(t)r_j^1(v(t^m)) + v_j^2(t)r_j^2(v(t^m)) = R_j \begin{pmatrix} v_j^1(t) \\ v_j^2(t) \end{pmatrix} = R_j V_j(t).$
- $v_j^i(t) = v_j^i + (t t^m)\dot{v}_j^i$. We know v_j^i from (GC) and \dot{v}_j^1 .
- $\dot{v}_j^1 = -\lambda_1 \partial_x \left(R^{-1} U_j(t^m, 0+) \right)^1 = -\lambda_1 \left(R^{-1} \begin{pmatrix} \sigma_{j,0}^1 \\ \sigma_{j,0}^2 \end{pmatrix} \right)^1$.



- For subsonical states U_j we have λ¹_j < 0 and λ²_j > 0.
- For small $t t^m$ we use the decomposition $U_j(t^m, 0+) = v_j^1(t)r_j^1(v(t^m)) + v_j^2(t)r_j^2(v(t^m)) = R_j \begin{pmatrix} v_j^1(t) \\ v_j^2(t) \end{pmatrix} = R_j V_j(t).$ • $v_j^i(t) = v_j^i + (t - t^m)\dot{v}_j^i$. We know v_j^i from (GC) and \dot{v}_j^1 .
- $\dot{v}_j^1 = -\lambda_1 \partial_x \left(R^{-1} U_j(t^m, 0+) \right)^1 = -\lambda_1 \left(R^{-1} \begin{pmatrix} \sigma_{j,0}^1 \\ \sigma_{j,0}^2 \end{pmatrix} \right)^{\prime}$.

- For subsonical states U_j we have λ¹_j < 0 and λ²_j > 0.
- For small $t t^m$ we use the decomposition $U_j(t^m, 0+) = v_j^1(t)r_j^1(v(t^m)) + v_j^2(t)r_j^2(v(t^m)) = R_j \begin{pmatrix} v_j^1(t) \\ v_j^2(t) \end{pmatrix} = R_j V_j(t).$
- $v_j^i(t) = v_j^i + (t t^m)\dot{v}_j^i$. We know v_j^i from (GC) and \dot{v}_j^1 .
- $\dot{v}_j^1 = -\lambda_1 \partial_x \left(R^{-1} U_j(t^m, 0+) \right)^1 = -\lambda_1 \left(R^{-1} \begin{pmatrix} \sigma_{j,0}^1 \\ \sigma_{j,0}^2 \end{pmatrix} \right)^{'}$.



- For subsonical states U_j we have λ¹_j < 0 and λ²_j > 0.
- For small $t t^m$ we use the decomposition $U_j(t^m, 0+) = v_j^1(t)r_j^1(v(t^m)) + v_j^2(t)r_j^2(v(t^m)) = R_j\begin{pmatrix}v_j^1(t)\\v_j^2(t)\end{pmatrix} = R_jV_j(t).$ • $v_j^i(t) = v_j^i + (t - t^m)\dot{v}_j^i$. We know v_j^i from (GC) and \dot{v}_j^1 .

•
$$\dot{v}_j^1 = -\lambda_1 \partial_x \left(R^{-1} U_j(t^m, 0+) \right)^1 = -\lambda_1 \left(R^{-1} \begin{pmatrix} \sigma_{j,0}^1 \\ \sigma_{j,0}^2 \end{pmatrix} \right)^1$$
.

Linearize of Influx: \dot{v}_i^2

Linearize Ψ:

$$0 = \frac{d}{dt} \Psi(U_1(t^m, 0+), U_2(t, 0+))$$

= $\frac{d}{dt} \Psi(V_1(t), V_2(t)) |_{t=t^m}$
= $-\sum_{j=1}^2 D_{V_j} \Psi(V_1(t), V_2(t)) Df(V_j) \begin{pmatrix} \dot{v}_j^1 \\ \dot{v}_j^2 \end{pmatrix}.$

• $\Rightarrow \dot{v}_j^2 \Rightarrow V_j(t)$ which we will use to calculate the fluxes at x = 0.



Linearize of Influx: \dot{v}_i^2

Linearize Ψ:

$$0 = \frac{d}{dt} \Psi(U_1(t^m, 0+), U_2(t, 0+))$$

= $\frac{d}{dt} \Psi(V_1(t), V_2(t)) |_{t=t^m}$
= $-\sum_{j=1}^2 D_{V_j} \Psi(V_1(t), V_2(t)) Df(V_j) \begin{pmatrix} \dot{v}_j^1 \\ \dot{v}_j^2 \end{pmatrix}.$

• $\Rightarrow \dot{v}_i^2 \Rightarrow V_i(t)$ which we will use to calculate the fluxes at x = 0.



Plot Periodic vs. Coupled

• Initial data: $\rho(x)_0 = 0.1 \cos(x) + 1$, $q(x)_0 = 0.05 \cos(x) + 2$, final time T = 0.3.

• Plot of solutions U_p (periodic) and U_c (coupled).



Plot Periodic vs. Coupled

- Initial data: $\rho(x)_0 = 0.1 \cos(x) + 1$, $q(x)_0 = 0.05 \cos(x) + 2$, final time T = 0.3.
- Plot of solutions U_p (periodic) and U_c (coupled).



Table of Error

N _k	$L^1 \rho$	$L^1 q$	Rate ρ	Rate q
2 ⁵	8.8259	7.1826	/	/
2 ⁶	10.4556	8.6067	1.6297	1.4242
27	12.1436	10.3566	1.6880	1.7499
2 ⁸	13.8907	12.1301	1.7471	1.7735
2 ⁹	15.6996	13.9506	1.8089	1.8205
2 ¹⁰	17.5927	15.8745	1.8931	1.9239
2 ¹¹	19.5538	17.8503	1.9611	1.9758
212	21.5445	19.8373	1.9907	1.9870

Table: L^1 convergence of the periodic boundary to the nodal coupled method.



Y-Junction: Setup

• Consider n = 3 (arcs); spatial domain $x \in [0, 2]$,

- Neumann boundary conditions (outflowing) at *x* = 2,
- Coupling conditions: Conservation of mass and conservation of flow (as in the previous example),
- The initial data:
 For the first arc, *j* = 1, we se

$$\rho_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 + 1 & x \in [0,1) \\ \frac{3}{2} & x \in [1,2] \end{cases} \text{ and } q_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 & x \in [0,1) \\ \frac{1}{2} & x \in [1,2] \end{cases}.$$

For the second and the third arcs, j = 2, 3, we set

 $q_j(x,0) \equiv 0$ and $\rho_j(x,0) \equiv 1$.

• We have: $\Psi(U_1(x,0), U_2(x,0), U_3(x,0)) = (0,0,0)^{\top}$.

Axel-Stefan Häck, M.Sc. (RWTH Aachen)

iapm/ ...

Y-Junction: Setup

- Consider n = 3 (arcs); spatial domain $x \in [0, 2]$,
- Neumann boundary conditions (outflowing) at *x* = 2,
- Coupling conditions: Conservation of mass and conservation of flow (as in the previous example),
- The initial data: For the first arc, *j* = 1, we set

$$\rho_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 + 1 & x \in [0,1) \\ \frac{3}{2} & x \in [1,2] \end{cases} \text{ and } q_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 & x \in [0,1) \\ \frac{1}{2} & x \in [1,2] \end{cases}.$$

For the second and the third arcs, j = 2, 3, we set

 $q_j(x,0) \equiv 0$ and $\rho_j(x,0) \equiv 1$.

• We have: $\Psi(U_1(x,0), U_2(x,0), U_3(x,0)) = (0,0,0)^{\top}$.

iapm/ ...

Y-Junction: Setup

- Consider n = 3 (arcs); spatial domain $x \in [0, 2]$,
- Neumann boundary conditions (outflowing) at *x* = 2,
- Coupling conditions: Conservation of mass and conservation of flow (as in the previous example),
- The initial data:
 For the first arc, j = 1, we set

$$\rho_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 + 1 & x \in [0,1) \\ \frac{3}{2} & x \in [1,2] \end{cases} \text{ and } q_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 & x \in [0,1) \\ \frac{1}{2} & x \in [1,2] \end{cases}.$$

For the second and the third arcs, j = 2, 3, we set

 $q_j(x,0) \equiv 0$ and $\rho_j(x,0) \equiv 1$.

• We have: $\Psi(U_1(x,0), U_2(x,0), U_3(x,0)) = (0,0,0)^{\top}$.

iapm/____

Y-Junction: Setup

- Consider n = 3 (arcs); spatial domain $x \in [0, 2]$,
- Neumann boundary conditions (outflowing) at *x* = 2,
- Coupling conditions: Conservation of mass and conservation of flow (as in the previous example),
- The initial data:
 - For the first arc, j = 1, we set

$$\rho_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 + 1 & x \in [0,1) \\ \frac{3}{2} & x \in [1,2] \end{cases} \text{ and } q_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 & x \in [0,1) \\ \frac{1}{2} & x \in [1,2] \end{cases}.$$

For the second and the third arcs, j = 2, 3, we set

$$q_j(x,0) \equiv 0$$
 and $\rho_j(x,0) \equiv 1$.

• We have: $\Psi(U_1(x,0), U_2(x,0), U_3(x,0)) = (0,0,0)^\top$.

iapm/____

Y-Junction: Setup

- Consider n = 3 (arcs); spatial domain $x \in [0, 2]$,
- Neumann boundary conditions (outflowing) at *x* = 2,
- Coupling conditions: Conservation of mass and conservation of flow (as in the previous example),
- The initial data:
 - For the first arc, j = 1, we set

$$\rho_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 + 1 & x \in [0,1) \\ \frac{3}{2} & x \in [1,2] \end{cases} \text{ and } q_1(x,0) = \begin{cases} -x^3 + \frac{3}{2}x^2 & x \in [0,1) \\ \frac{1}{2} & x \in [1,2] \end{cases}.$$

For the second and the third arcs, j = 2, 3, we set

$$q_j(x,0)\equiv 0$$
 and $ho_j(x,0)\equiv 1$.

• We have: $\Psi(U_1(x,0), U_2(x,0), U_3(x,0)) = (0,0,0)^\top$.

igpm _____

Y-Junction: Plots ρ



Figure: Evolution of the density ρ . Arcs: $\diamond j = 1, \circ j = 2, \times j = 3$.

Axel-Stefan Häck, M.Sc. (RWTH Aachen)

iapm

Y-Junction: Plots q



Figure: Evolution of the flow *q*. Arcs: $\diamond j = 1$, $\circ j = 2$, $\times j = 3$.

igpm,



Thank you!

Literature:

Steel rolling:

- M. Bambach, A.-S. Häck, and M. Herty. *Modeling steel rolling processes by fluid-like differential equations. Applied mathematical modelling.*
- A.-S. Häck and M. Herty. *Hot Rolling Multipass Simulation*, pages 286–293. In "Integrative Production Technology Theory and Applications".

Coupling:

• M.K. Banda, A.-S. Häck, and M. Herty. *Numerical discretization of coupling conditions by high-order schemes*. Journal of Scientific Computing.

igpm _