Chapter 4: Network Layer

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- 4.2 Virtual circuit and datagram networks
- 4.3 What's inside a router
- 4.4 IP: Internet Protocol
  - Datagram format
  - IPv4 addressing
  - ICMP
  - IPv6
- 4.5 Routing algorithms
  - Link state
  - Distance Vector
  - Hierarchical routing
- 4.6 Routing in the Internet
  - RIP
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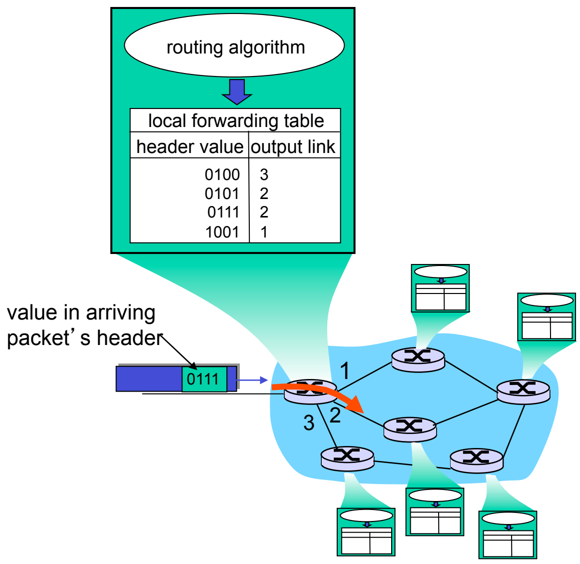
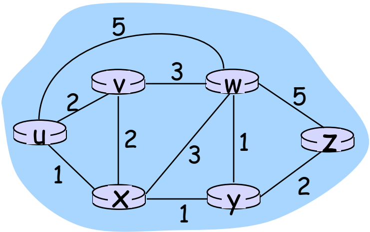
- 4.7 Broadcast and multicast routing

Interplay between routing, forwarding



Graph abstraction



Graph: G = (N,E)

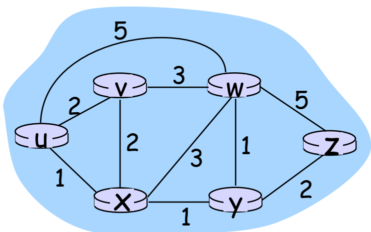
N = set of routers = { u, v, w, x, y, z }

E = set of links ={ (u,v), (u,x), (v,x), (v,w), (x,w), (x,y), (w,y), (w,z), (y,z) }

Remark: Graph abstraction is useful in other network contexts

Example: P2P, where N is set of peers and E is set of TCP connections

Graph abstraction: costs



- $c(x,x')$ = cost of link (x,x')
  - e.g., $c(w,z) = 5$
- cost could always be 1, or inversely related to bandwidth, or inversely related to congestion

Cost of path $(x_1, x_2, x_3,\ldots, x_p) = c(x_1,x_2) + c(x_2,x_3) + \ldots + c(x_{p-1},x_p)$

Question: What's the least-cost path between u and z ?

Routing algorithm: algorithm that finds least-cost path

Routing Algorithm classification

Global or decentralized information?

Global:
- all routers have complete topology, link cost info
- "link state" algorithms

Decentralized:
- router knows physically-connected neighbors, link costs to neighbors
- iterative process of computation, exchange of info with neighbors
- "distance vector" algorithms

Static or dynamic?

Static:
- routes change slowly over time

Dynamic:
- routes change more quickly
  - periodic update
  - in response to link cost changes

Chapter 4: Network Layer

A Link-State Routing Algorithm

Dijkstra's algorithm

- net topology, link costs known to all nodes
  - accomplished via "link state broadcast"
  - all nodes have same info
- computes least cost paths from one node ('source") to all other nodes
  - gives forwarding table for that node
- iterative: after k iterations, know least cost path to k dest.'s

Notation:

- c(x,y): link cost from node x to y; = ∞ if not direct neighbors
- D(v): current value of cost of path from source to dest. v
- p(v): predecessor node along path from source to v
- N': set of nodes whose least cost path definitively known

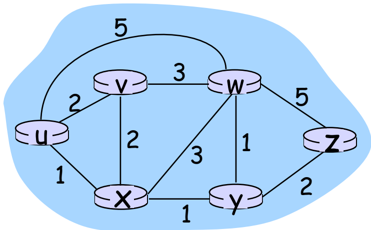
Dijsktra's Algorithm

```
Initialization:
  N' = {u}
  for all nodes v
    if v adjacent to u
        then D(v) = c(u,v)
    else D(v) = ∞

 Loop
   find w not in N' such that D(w) is a minimum
    add w to N'
    update D(v) for all v adjacent to w and not in N' :
       D(v) = min( D(v), D(w) + c(w,v) )
    /* new cost to v is either old cost to v or known
     shortest path cost to w plus cost from w to v */
  until all nodes in N'
```

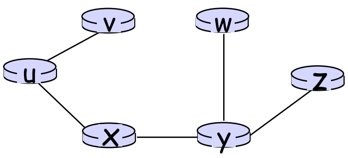
Dijkstra's algorithm: example

Step	N'	D(v),p(v)	D(w),p(w)	D(x),p(x)	D(y),p(y)	D(z),p(z)
0	u	2,u	5,u	1,u	∞	∞
1	ux	2,u	4,x		2,x	∞
2	uxy	2,u	3,y			4,y
3	uxyv		3,y			4,y
4	uxyvw					4,y
5	uxyvwz					



Dijkstra's algorithm: example (2)

Resulting shortest-path tree from u:



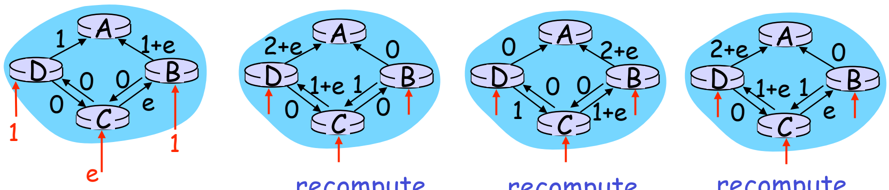
Resulting forwarding table in u:

destination	link
v	(u,v)
x	(u,x)
y	(u,x)
w	(u,x)
z	(u,x)

Dijkstra's algorithm, discussion

Algorithm complexity: n nodes
- each iteration: need to check all nodes, w, not in N
- n(n+1)/2 comparisons: $O(n^2)$
- more efficient implementations possible: O(nlogn)

Oscillations possible:
- e.g., link cost = amount of carried traffic



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Distance Vector Algorithm

Bellman-Ford Equation (dynamic programming)

Define

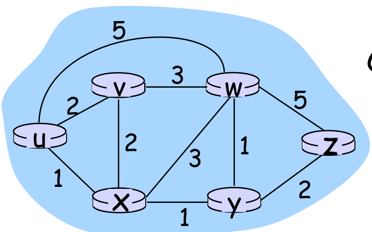
$d_x(y)$:= cost of least-cost path from x to y

Then

$$d_x(y) = \min_v \{c(x,v) + d_v(y)\}$$

where min is taken over all neighbors v of x

Bellman-Ford example



Clearly, $d_v(z) = 5$, $d_x(z) = 3$, $d_w(z) = 3$

B-F equation says:

$$d_u(z) = \min\{ c(u,v) + d_v(z),\ c(u,x) + d_x(z),\ c(u,w) + d_w(z) \}$$
$$= \min\{2 + 5,\ 1 + 3,\ 5 + 3\} = 4$$

Node that achieves minimum is next hop in shortest path ➜ forwarding table

Distance Vector Algorithm

- $D_x(y)$ = estimate of least cost from x to y
- Node x knows cost to each neighbor v: $c(x,v)$
- Node x maintains distance vector $\mathbf{D}_x = [D_x(y): y \in N]$
- Node x also maintains its neighbors' distance vectors
  - For each neighbor v, x maintains $\mathbf{D}_v = [D_v(y): y \in N]$

Distance vector algorithm (4)

Basic idea:

- From time-to-time, each node sends its own distance vector estimate to neighbors
- Asynchronous
- When a node x receives new DV estimate from neighbor, it updates its own DV using B-F equation:

$$D_x(y) \leftarrow \min_v\{c(x,v) + D_v(y)\} \quad \text{for each node } y \in N$$

- Under minor, natural conditions, the estimate $D_x(y)$ *converge to the actual least cost* $d_x(y)$

Distance Vector Algorithm (5)

Iterative, asynchronous: each local iteration caused by:

- local link cost change
- DV update message from neighbor

Distributed:

- each node notifies neighbors *only* when its DV changes
  - neighbors then notify their neighbors if necessary

Each node:

wait for (change in local link cost or msg from neighbor)

↓

recompute estimates

↓

if DV to any dest has changed, *notify* neighbors

$D_x(y) = \min\{c(x,y) + D_y(y), c(x,z) + D_z(y)\}$
$= \min\{2+0 , 7+1\} = 2$

$D_x(z) = \min\{c(x,y) + D_y(z), c(x,z) + D_z(z)\}$
$= \min\{2+1 , 7+0\} = 3$

node x table

from \ cost to	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

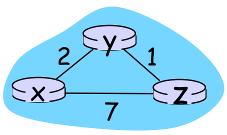
from \ cost to	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

node y table

from \ cost to	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

node z table

from \ cost to	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0



time

$D_x(y) = \min\{c(x,y) + D_y(y), c(x,z) + D_z(y)\}$
$= \min\{2+0 , 7+1\} = 2$

$D_x(z) = \min\{c(x,y) + D_y(z), c(x,z) + D_z(z)\}$
$= \min\{2+1 , 7+0\} = 3$

node x table

cost to

from	x	y	z
x	0	2	7
y	∞	∞	∞
z	∞	∞	∞

cost to

from	x	y	z
x	0	2	3
y	2	0	1
z	7	1	0

cost to

from	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node y table

cost to

from	x	y	z
x	∞	∞	∞
y	2	0	1
z	∞	∞	∞

cost to

from	x	y	z
x	0	2	7
y	2	0	1
z	7	1	0

cost to

from	x	y	z
x	0	2	3
y	2	0	1
z	3	1	0

node z table

cost to

from	x	y	z
x	∞	∞	∞
y	∞	∞	∞
z	7	1	0

cost to

from	x	y	z
x	0	2	7
y	2	0	1
z	3	1	0

cost to

from	x	y	z
x	0	2	3
y	2	0	1
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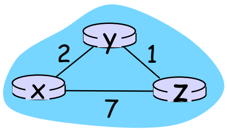
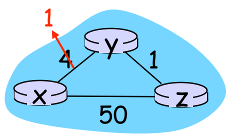
time



Distance Vector: link cost changes

Link cost changes:

- node detects local link cost change
- updates routing info, recalculates distance vector
- if DV changes, notify neighbors



"good news travels fast"

At time t_0, *y* detects the link-cost change, updates its DV, and informs its neighbors.

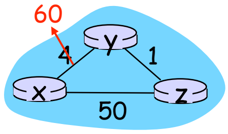
At time t_1, *z* receives the update from *y* and updates its table. It computes a new least cost to *x* and sends its neighbors its DV.

At time t_2, *y* receives *z*'s update and updates its distance table. *y*'s least costs do not change and hence *y* does *not* send any message to *z*.

Distance Vector: link cost changes

Link cost changes:

- good news travels fast
- bad news travels slow - "count to infinity" problem!
- 44 iterations before algorithm stabilizes: see text



Poisoned reverse:

- If Z routes through Y to get to X :
  - Z tells Y its (Z's) distance to X is infinite (so Y won't route to X via Z)
- will this completely solve count to infinity problem?

Comparison of LS and DV algorithms

Message complexity

- LS: with n nodes, E links, O(nE) msgs sent
- DV: exchange between neighbors only
  - convergence time varies

Speed of Convergence

- LS: O(n^2) algorithm requires O(nE) msgs
  - may have oscillations
- DV: convergence time varies
  - may be routing loops
  - count-to-infinity problem

Robustness: what happens if router malfunctions?

LS:

- node can advertise incorrect *link* cost
- each node computes only its *own* table

DV:

- DV node can advertise incorrect *path* cost
- each node's table used by others
  - error propagate thru network

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Hierarchical Routing

Our routing study thus far - idealization
- all routers identical
- network "flat"

… *not* true in practice

scale: with 200 million destinations:
- can't store all dest's in routing tables!
- routing table exchange would swamp links!

administrative autonomy
- internet = network of networks
- each network admin may want to control routing in its own network

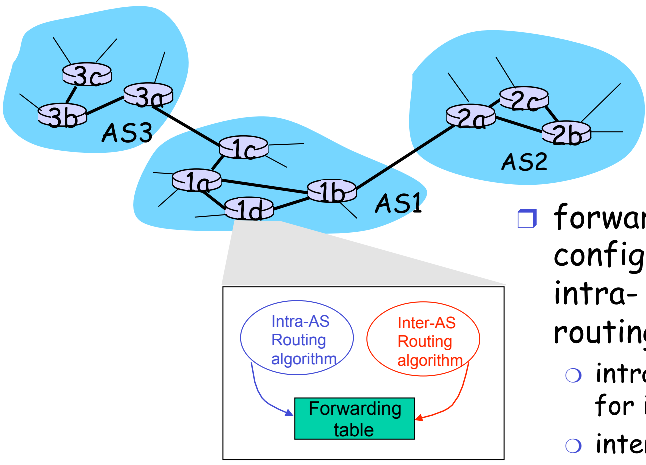
Hierarchical Routing

- aggregate routers into regions, "autonomous systems" (AS)
- routers in same AS run same routing protocol
  - "intra-AS" routing protocol
  - routers in different AS can run different intra-AS routing protocol

Gateway router

- Direct link to router in another AS

Interconnected ASes



- forwarding table configured by both intra- and inter-AS routing algorithm
  - intra-AS sets entries for internal dests
  - inter-AS & intra-As sets entries for external dests

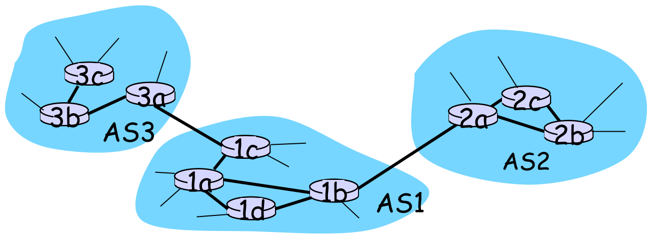
Inter-AS tasks

- suppose router in AS1 receives datagram destined outside of AS1:
  - router should forward packet to gateway router, but which one?

AS1 must:

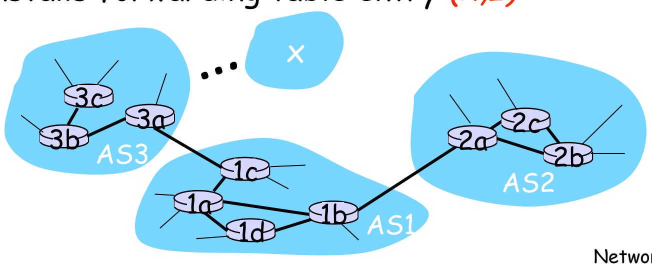
1. learn which dests are reachable through AS2, which through AS3
2. propagate this reachability info to all routers in AS1

Job of inter-AS routing!



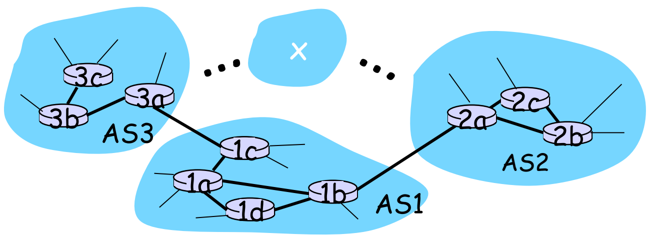
Example: Setting forwarding table in router 1d

- suppose AS1 learns (via inter-AS protocol) that subnet *x* reachable via AS3 (gateway 1c) but not via AS2.
- inter-AS protocol propagates reachability info to all internal routers.
- router 1d determines from intra-AS routing info that its interface *I* is on the least cost path to 1c.
  - installs forwarding table entry *(x,I)*



Example: Choosing among multiple ASes

- now suppose AS1 learns from inter-AS protocol that subnet x is reachable from AS3 *and* from AS2.
- to configure forwarding table, router 1d must determine towards which gateway it should forward packets for dest x.
  - this is also job of inter-AS routing protocol!



Example: Choosing among multiple ASes

- now suppose AS1 learns from inter-AS protocol that subnet x is reachable from AS3 *and* from AS2.
- to configure forwarding table, router 1d must determine towards which gateway it should forward packets for dest x.
  - this is also job of inter-AS routing protocol!
- hot potato routing: send packet towards closest of two routers.