

Lectures on
DIFFERENTIAL GEOMETRY AND TOPOLOGY

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Lecture XII

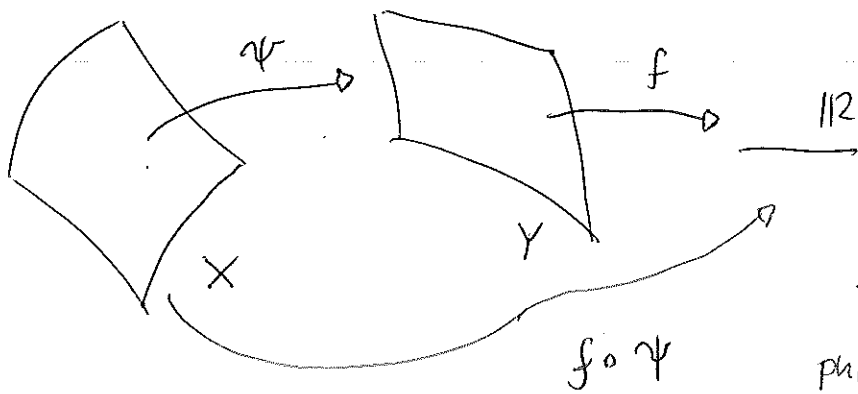
* Smooth maps between manifolds

- Smooth maps between manifolds p. 1
- differential p. 2
- Example p. 6
- Tangent & cotangent bundles p. 8

Let X, Y be differentiable manifolds of dimension n and m respectively

- Tensor bundles p. 12
- Riemannian metrics p. 13
- Behaviour under smooth maps p. 14

* A map $\psi: X \rightarrow Y$ is said to be smooth if, whenever $f \in C^\infty(Y, \mathbb{R})$ (smooth function on Y), then $f \circ \psi \in C^\infty(X, \mathbb{R})$



"smooth is who smooth does"

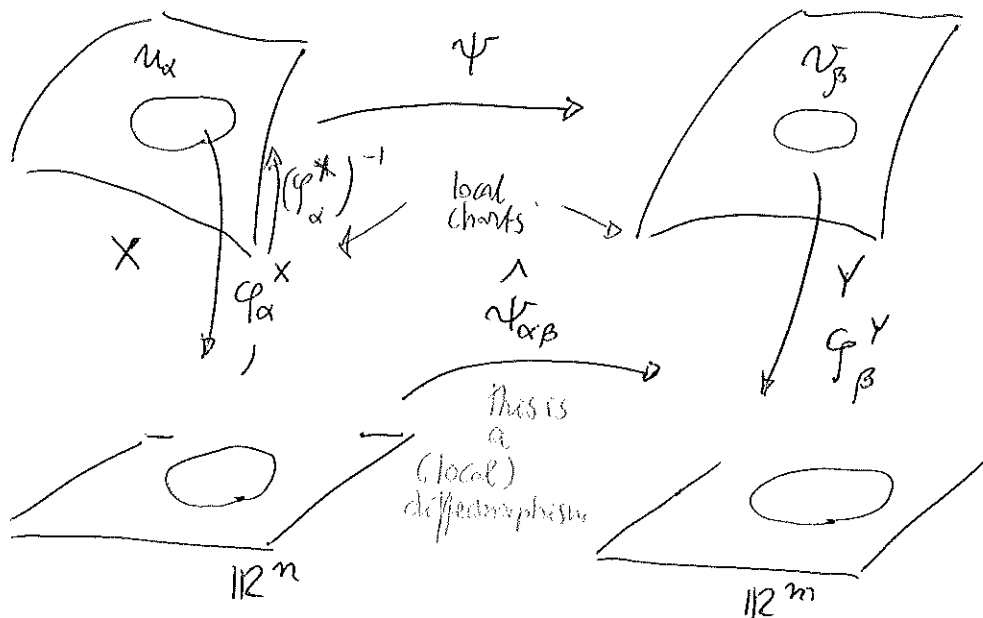
$f \circ \psi =: \psi^* f$
 pull-back of f via ψ

"knowing functions on X one knows X "

Def. $\psi: X \rightarrow Y$ is said to be a (smooth) diffeomorphism

- if
- ψ is bijective (and smooth)
 - ψ^{-1} is smooth

Locally, $\psi: X \rightarrow Y$ induces smooth maps from \mathbb{R}^n to \mathbb{R}^m (upon applying the definition to local coordinate functions)



$$\hat{\psi}_{\alpha\beta} = \varphi_{\beta}^Y \circ \psi \circ (\varphi_{\alpha}^X)^{-1}$$

if ψ
 is smooth,
 and $f \in C^0(Y, \mathbb{R})$,
 then $f \circ \psi = \psi^* f$
 $\in C^0(X, \mathbb{R})$
 by definition

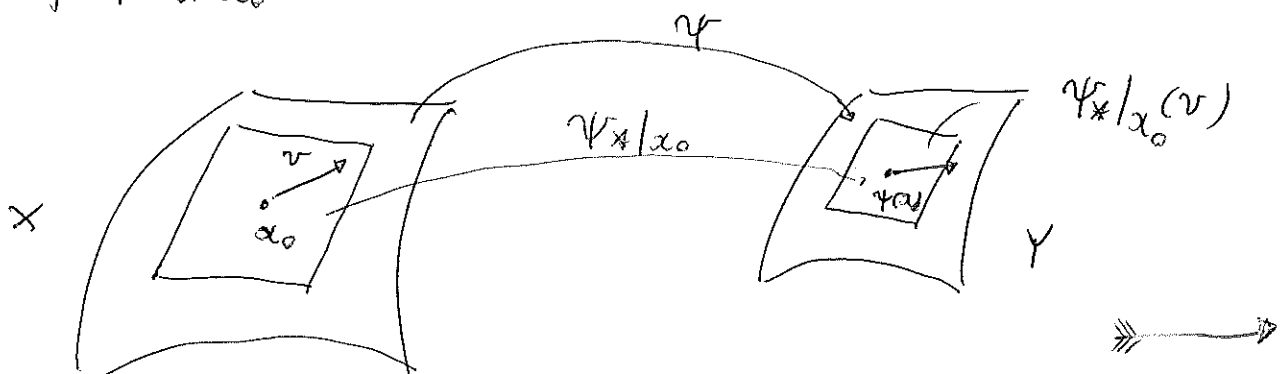
* Differential of a smooth map.

Let $\psi: X \rightarrow Y$ Smooth
 and $\alpha_0 \in X$. One can define

$$d\psi|_{\alpha_0} \equiv \psi_*|_{\alpha_0} : T_{\alpha_0} X \longrightarrow T_{\psi(\alpha_0)} Y$$

differential
 (push-forward)
 of ψ at α_0

$$\begin{array}{ccc} \downarrow & & \\ v & \longmapsto & \psi_*|_{\alpha_0}(v) \end{array}$$



Let us provide some details

$$\psi: X \rightarrow Y$$

φ : coordinate system $(x^1 \dots x^n)$ around $x_0 \in X$
local chart

τ : $= (y^1 \dots y^m)$ around $y_0 \in Y$

Compute:

$$(\psi_* |_{x_0})(v)(g) = v(g \circ \psi) = \sum_{i=1}^n a^i \frac{\partial}{\partial x^i} (g \circ \psi)$$

$$= \sum_{i=1}^n a^i \frac{\partial}{\partial r^i} (g \circ \tau^{-1} \circ \tau \circ \psi \circ \varphi^{-1}) \Big|_{\varphi(x_0)}$$

chain rule

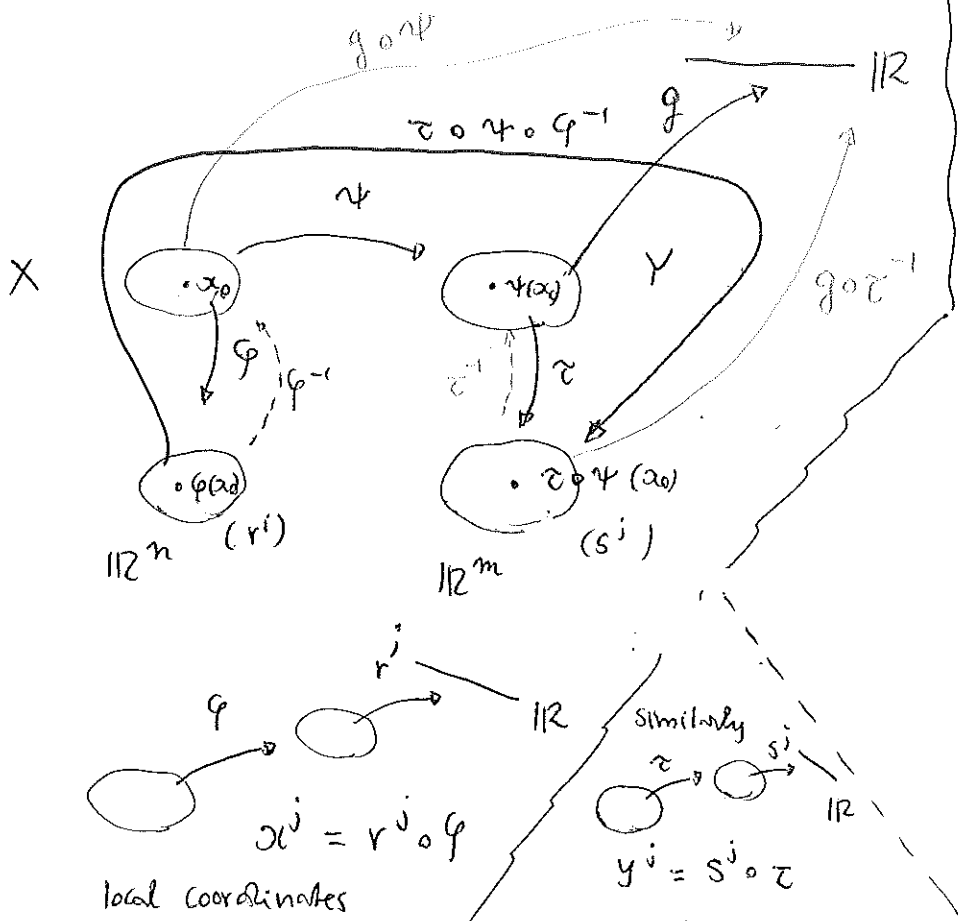
$$= \sum_{i=1}^n a^i \sum_{j=1}^m \frac{\partial}{\partial s^j} (g \circ \tau^{-1}) \Big|_{\tau \circ \psi(x_0)} \cdot \frac{\partial}{\partial r^i} (\tau \circ \psi \circ \varphi^{-1}) \Big|_{\varphi(x_0)}$$

coordinate maps on \mathbb{R}^m

$$= \sum_{i=1}^n \sum_{j=1}^m a^i \frac{\partial g}{\partial y^j} \cdot \frac{\partial}{\partial x^i} (y_j \circ \psi)$$

$$= \left[\sum_{j=1}^m v(y_j \circ \psi) \frac{\partial}{\partial y^j} \right] (g)$$

this is indeed a tangent vector at $\psi(x_0)$

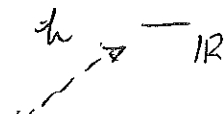


We find, in particular

$$\psi_* \Big|_{\alpha_0} : T_{\alpha_0} X \longrightarrow T_{\psi(\alpha_0)} Y$$

$$\frac{\partial}{\partial x^i} \longmapsto \sum_{j=1}^m \underbrace{\frac{\partial}{\partial y^j} (\psi_j \circ \psi)}_{(\psi_* \Big|_{\alpha})_{ji}} \frac{\partial}{\partial y^j}$$

$\leftarrow J^T$

Let us also check that if $X \xrightarrow{\psi} Y \xrightarrow{\Phi} Z$ 

then $d(\Phi \circ \psi) = d\Phi \circ d\psi$ generalized chain rule
 \leftarrow as homomorphisms
 no matrix product.

$$\boxed{(\Phi \circ \psi)_* = \Phi_* \circ \psi_*}$$

associativity of \circ

$$\left[(\Phi \circ \psi)_* (v) \right] (h) \stackrel{\text{def}}{=} \mathcal{V} (h \circ (\Phi \circ \psi)) = \mathcal{V} ((h \circ \Phi) \circ \psi)$$

$$= \psi_* (v) (h \circ \Phi) = \Phi_* (\psi_* (v)) (h)$$

$$= \left[(\Phi_* \circ \psi_*) (v) \right] (h) \quad \square$$

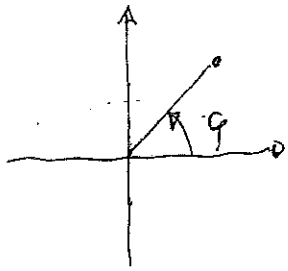
* Example. Let $M = \mathbb{R}^2 - \{(a, 0) \mid a \geq 0\}$

$$\psi: \begin{matrix} M \subset \mathbb{R}^2 \\ (p, \varphi) \end{matrix} \longmapsto (x, y) \in \mathbb{R}^2 \quad \psi: \begin{cases} x = p \cos \varphi \\ y = p \sin \varphi \end{cases}$$

$p > 0$
 $\varphi \in (0, 2\pi)$

$$d\psi: \begin{cases} dx = dp \cos \varphi - p \sin \varphi d\varphi \\ dy = dp \sin \varphi + p \cos \varphi d\varphi \end{cases}$$

|||
 ψ_*



$$\begin{pmatrix} \cos \varphi & -p \sin \varphi \\ \sin \varphi & p \cos \varphi \end{pmatrix}$$

$$\frac{\partial}{\partial p} \mapsto \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

$$\frac{\partial}{\partial \varphi} \mapsto \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

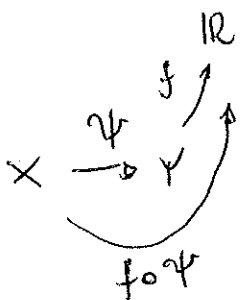
$$\psi_* \left(\frac{\partial}{\partial p} \right) = \cos \varphi \frac{\partial}{\partial x} + \sin \varphi \frac{\partial}{\partial y} = \frac{x}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial x} + \frac{y}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial y}$$

$$\psi_* \left(\frac{\partial}{\partial \varphi} \right) = -p \sin \varphi \frac{\partial}{\partial x} + p \cos \varphi \frac{\partial}{\partial y} = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}$$

This is of course in agreement with the general definition

$$(\psi_* X)(f) = X(f \circ \psi)$$

Take $X = \frac{\partial}{\partial p}$. Compute:



$$\psi_* \left(\frac{\partial}{\partial p} \right) (f) = \frac{\partial}{\partial p} (f \circ \psi) = \frac{\partial f}{\partial x} \frac{\partial x}{\partial p} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial p}$$

"f = f(x, y)" "f = f(p, φ)"

$$= \frac{\partial f}{\partial x} \underbrace{\cos \varphi}_{\frac{x}{\sqrt{x^2 + y^2}}} + \frac{\partial f}{\partial y} \underbrace{\sin \varphi}_{\frac{y}{\sqrt{x^2 + y^2}}} \Rightarrow \boxed{\psi_* \left(\frac{\partial}{\partial p} \right) = \frac{x}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial x} + \frac{y}{\sqrt{x^2 + y^2}} \frac{\partial}{\partial y}} \quad \checkmark$$

"remove f"

Similarly:

$$\psi_* \left(\frac{\partial}{\partial p} \right) (f) = \frac{\partial}{\partial p} (f \circ \psi) = \frac{\partial f}{\partial x} \frac{\partial x}{\partial p} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial p}$$

$$= \frac{\partial f}{\partial x} \underbrace{(-p \sin \varphi)}_{-y} + \frac{\partial f}{\partial y} \underbrace{(p \cos \varphi)}_{x} \Rightarrow \boxed{\psi_* \left(\frac{\partial}{\partial p} \right) = -y \frac{\partial}{\partial x} + x \frac{\partial}{\partial y}}$$

Let us examine this "classical" computation as well (useful in general)

$$\frac{\partial f}{\partial p} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial p} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial p}$$

$$\frac{\partial f}{\partial q} = \frac{\partial f}{\partial x} \frac{\partial x}{\partial q} + \frac{\partial f}{\partial y} \frac{\partial y}{\partial q}$$

$$\begin{pmatrix} \frac{\partial x}{\partial p} & \frac{\partial y}{\partial p} \\ \frac{\partial x}{\partial q} & \frac{\partial y}{\partial q} \end{pmatrix} = J^t$$

that is:
(remove f)

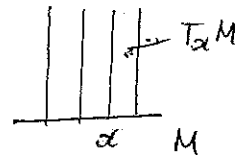
$$\begin{pmatrix} \frac{\partial}{\partial p} \\ \frac{\partial}{\partial q} \end{pmatrix} = \begin{pmatrix} \cos \varphi & \sin \varphi \\ -p \sin \varphi & p \cos \varphi \end{pmatrix} \begin{pmatrix} \frac{\partial}{\partial x} \\ \frac{\partial}{\partial y} \end{pmatrix}$$

$$\begin{cases} \frac{\partial}{\partial p} = \frac{x}{r} \frac{\partial}{\partial x} + \frac{y}{r} \frac{\partial}{\partial y} \\ \frac{\partial}{\partial q} = \underbrace{-p \sin \varphi}_{-y} \frac{\partial}{\partial x} + \underbrace{p \cos \varphi}_{x} \frac{\partial}{\partial y} \end{cases}$$

$\frac{\partial}{\partial p}$ and $\frac{\partial}{\partial q}$ are viewed, concretely, as linear combinations of $\frac{\partial}{\partial x}$ and $\frac{\partial}{\partial y}$ but

* The tangent bundle TM

Let M be a (smooth) manifold



Let

$$TM = \bigsqcup_{\alpha \in M} T_{\alpha} M$$

* tangent bundle of M

disjoint union

$\alpha \in M$

* tangent space at α

* Cotangent bundle of M

$$T^*M = \bigsqcup_{\alpha \in M} T_{\alpha}^* M$$

$= (T_{\alpha} M)^*$ dual of $T_{\alpha} M$

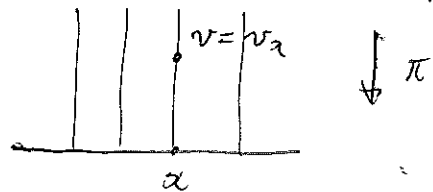
\equiv cotangent space at α

* TM and T^*M are naturally endowed with a manifold structure. Let us focus on TM (T^*M is treated similarly)

Let $\mathcal{A} = \{(\mathcal{U}_{\alpha}, \varphi_{\alpha})\}_{\alpha \in \mathcal{R}}$ be an atlas for M
Some index set

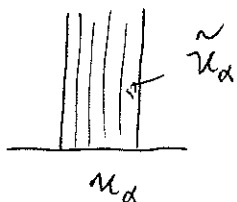
Let $\pi: TM \rightarrow M$ be the natural projection map.

$$v \equiv v_{\alpha} \mapsto \alpha$$



any $v \in TM$ belongs to one and only one $T_{\alpha} M$ for $\alpha \in M$

Let $\tilde{\mathcal{U}}_{\alpha} = \pi^{-1}(\mathcal{U}_{\alpha}) \cong \mathcal{U}_{\alpha} \times \mathbb{R}^n$
 may give us to



Set

$$\tilde{\varphi}_{\alpha}: \left(\alpha, \sum_{i=1}^n b^i \frac{\partial}{\partial x^i} \right) \mapsto (\alpha^i, b^j)$$

\cap
 $T_{\alpha} M$

\cong
 \mathbb{R}^n
 local coordinates

$\tilde{\mathcal{A}} = \{(\tilde{\mathcal{U}}_{\alpha}, \tilde{\varphi}_{\alpha})\}_{\alpha \in \mathcal{R}}$ becomes an atlas

for TM

* TM can be topologized according to the second definition; it is clear that it has a countable basis and is Hausdorff if M is such.

The transition functions are readily obtained via the following computation (bridged notation, together with Einstein's convention)

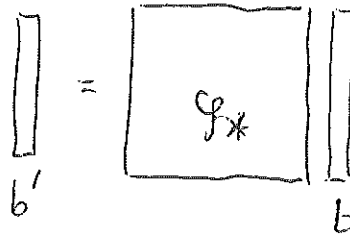
$$b^i \frac{\partial f}{\partial x^i} = b^i \frac{\partial f}{\partial y^j} \frac{\partial y^j}{\partial x^i}$$

↑
insert argument

$y = y(x)$
coordinate change
 $y = y(x)$

$$= \underbrace{\left(b^i \frac{\partial y^j}{\partial x^i} \right)}_{(b'^j)} \frac{\partial f}{\partial y^j} \quad (b^i) \mapsto (b'^i)$$

$$b'^i = b^{ik} \frac{\partial y^i}{\partial x^k} = \frac{\partial y^i}{\partial x^k} b^{ik}$$

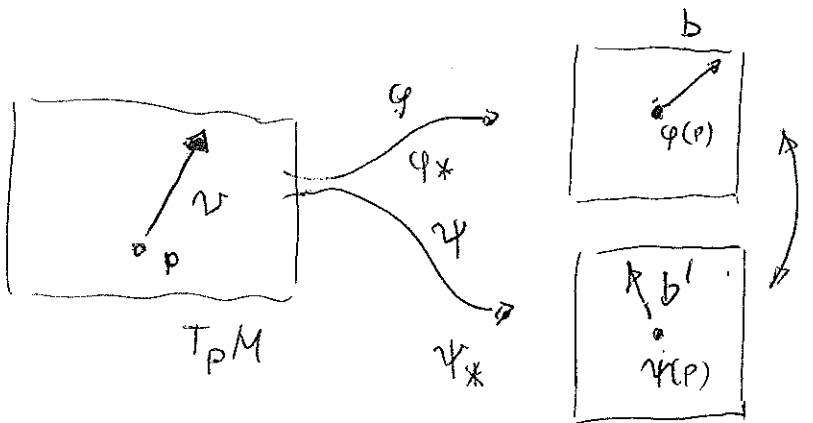


↖
just a re-labeling

this is fully consistent with the interpretation of the b's as velocity vectors of curves

transition maps:

$$(x, b) \mapsto (y, b')$$



↖
★ The same object is viewed in different coordinate systems

* The cotangent bundle

A similar treatment can be devised for the cotangent bundle T^*M . Charts (given an atlas for M):

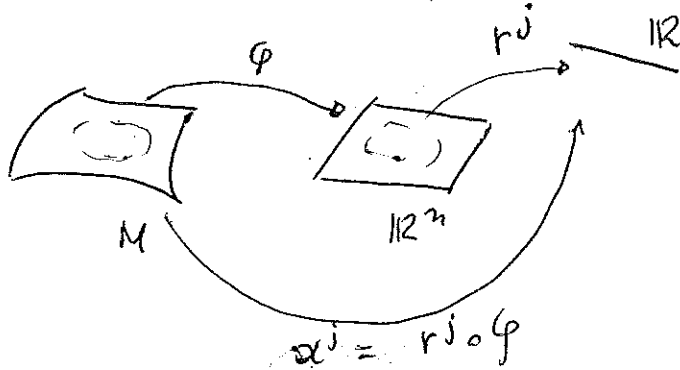
$$\tilde{\varphi}_\alpha : (\alpha, \sum_{i=1}^n b_i d\alpha^i) \longmapsto (\alpha^i, b^i)$$

$$\uparrow \\ T_\alpha^* M$$

notice:

$d\alpha^i$ is the differential

of the j th-coordinate function α^j



in accordance with the general definition

$$\varphi : X \rightarrow Y$$

Remark:

Cotangent spaces are fundamental in mechanics, being examples of phase spaces (symplectic manifolds), i.e. receptacles of positions and momenta of point particles.

$$d\varphi|_{*\alpha} : T_\alpha X \rightarrow T_{\varphi(\alpha)} Y$$

|||
duals of velocities

remember that identification with dual space is not canonical



Again work out the transition functions

$$b_i dx^i = \overbrace{b'_j}^{b'_j} \frac{\partial x^i}{\partial y^j} dy^j$$

$$b \longmapsto b'$$

$$(b_i) \longmapsto (b'_k \frac{\partial x^k}{\partial y^i}) = (\frac{\partial x^k}{\partial y^i} b_k) \equiv (b'_i)$$

↑
relabeling

* again notice the different behaviours

(contravariance vs covariance)

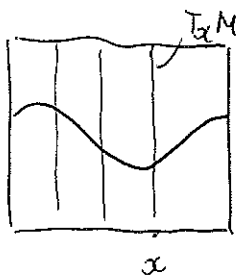
transition maps

$$(x, b) \longmapsto (y, b')$$

↑
covector

* vector fields (notation: $\mathcal{X}(M)$) are the smooth sections on M of TM , i.e. given $\pi: TM \rightarrow M$

(canonical projection; it is a smooth map), $X: M \rightarrow TM$ (smooth) such that $\pi \circ X = \text{id}_M$, i.e. $X(x) \in T_x M$



$X \in \mathcal{X}(M)$

$\forall x \in M$

* differential 1-forms (notation: $\Delta^1(M)$) \cong smooth sections of T^*M ; $\omega: M \rightarrow T^*M$

with $\pi \circ \omega = \text{id}_M$ ($\pi: T^*M \rightarrow M$ canonical projection)


* Tensor bundles

One can similarly define tensor bundles, whose sections are tensor fields

$$\pi: T^{(p,q)}(M) \rightarrow M$$

$T^{(p,q)}(M) \ni (\alpha, t_{\ J}^{\ I} \frac{\partial}{\partial x^I} \otimes dx^J)$
 \downarrow local chart
 $(\alpha, t_{\ J}^{\ I})$
 \mathbb{R} components

$T_{\alpha}^* M \otimes \dots \otimes T_{\alpha}^* M \otimes T_{\alpha} M \otimes \dots \otimes T_{\alpha} M$
 $\underbrace{\hspace{10em}}_q \quad \underbrace{\hspace{10em}}_p$



 tensor field notation: $\gamma^{(p,q)}(M)$

* transition maps:

$$y = y(\alpha)$$

$$t_{\ j_1 \dots j_q}^{i_1 \dots i_p} \frac{\partial}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial}{\partial x^{i_p}} dx^{j_1} \otimes \dots \otimes dx^{j_q}$$

\parallel

$\frac{\partial f}{\partial x^{i_1}} = \frac{\partial f}{\partial y^{l_1}} \frac{\partial y^{l_1}}{\partial x^{i_1}}$ (Einstein etc...)

$dx^{j_1} = \frac{\partial x^{j_1}}{\partial y^{l_1}} dy^{l_1}$ (etc)

$$t_{\ j_1 \dots j_q}^{i_1 \dots i_p} \frac{\partial y^{l_1}}{\partial x^{i_1}} \otimes \dots \otimes \frac{\partial y^{l_p}}{\partial x^{i_p}} \frac{\partial x^{j_1}}{\partial y^{h_1}} \otimes \dots \otimes \frac{\partial x^{j_q}}{\partial y^{h_q}} \frac{\partial}{\partial y^{l_1}} \otimes \dots \otimes \frac{\partial}{\partial y^{l_p}} dy^{h_1} \otimes \dots \otimes dy^{h_q}$$

$t_{\ h_1 \dots h_q}^{l_1 \dots l_p}$

Concisely:

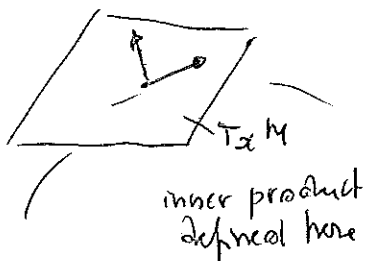
$$t_{\ J}^{\ I} \frac{\partial}{\partial x^I} \otimes dx^J = t_{\ H}^{\ L} \frac{\partial y^L}{\partial x^I} \frac{\partial x^J}{\partial y^H} \frac{\partial}{\partial y^L} \otimes dy^H$$

$t_{\ H}^{\ L}$

$$t_{\ H}^{\ L} = t_{\ J}^{\ I} \frac{\partial y^L}{\partial x^I} \frac{\partial x^J}{\partial y^H}$$

Sum over I and J

★ Example: A Riemannian metric on M is a smoothly varying family of inner products on $T_\alpha M$, $\alpha \in M$; it is a symmetric, positive definite (at each point) element of $\mathcal{L}^{(0,2)}(M)$



locally:

$$\alpha \mapsto g_{ij} dx^i dx^j$$

$$dx^i dx^j = \frac{1}{2} (dx^i \otimes dx^j + dx^j \otimes dx^i)$$

★ symmetric tensor product

Let us check its transformation law:

$$g_{ij} dx^i dx^j = g_{ij} \frac{\partial x^i}{\partial y^k} dy^k \frac{\partial x^j}{\partial y^l} dy^l$$

↑
as a function of α

$$= g_{ij} \frac{\partial x^i}{\partial y^k} \frac{\partial x^j}{\partial y^l} dy^k dy^l$$

as a function of y

$$\equiv g'_{kl} dy^k dy^l$$

$dx^i dx^j = \frac{1}{2} (dx^i \otimes dx^j - dx^j \otimes dx^i)$

★ antisymmetric tensor product

 $dx^i dx^j = dx^i dy^j + dx^j dy^i$

$$g'_{kl} = g_{ij} \frac{\partial x^i}{\partial y^k} \frac{\partial x^j}{\partial y^l}$$

(this is a function of y)

Once one gets used to this kind of computations they are easily performed automatically.

