Image Processing for Bioinformatics

AA 2009-2010 Facoltà di Scienze MM, FF e NN Dipartimento di Informatica Università di Verona

General information

- Teacher: Gloria Menegaz
- Assistant: Francesca Pizzorni
- Scheduling
 - Theory
 - Mon. 14.30 to 16.30
 - Wed. 10.30 to 11.30
 - Laboratory
 - Wed. 11.30 to 13.30
 - Tutoring (ricevimento)
 - by appointment (email)
 - Start and end dates
 - March 1°, 2010 Mid May 2010

- Exam
 TBD
- Support
 Slides of the course
 - Books

Contents

Classical IP

- Review of Fourier Transform
- Extension to 2D
- Sampling in 2D
- Quantization
- Edge detection
 - Model-based, region-based
- Filtering
 - denoising, deblurring, image enhancement
- Segmentation techniques
- Basics of pattern recognition
 - Clustering, classification

Advanced Topics

- Color imaging
- Introduction to stochastic processes
- Microarray image analysis

Why do we process images?

- To facilitate their storage and transmission
- To prepare them for display or printing
- To enhance or restore them
- To extract information from them
- To hide information in them

Image types

Optical (CCD)



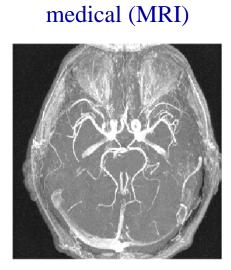


radar (SAR)

underwater

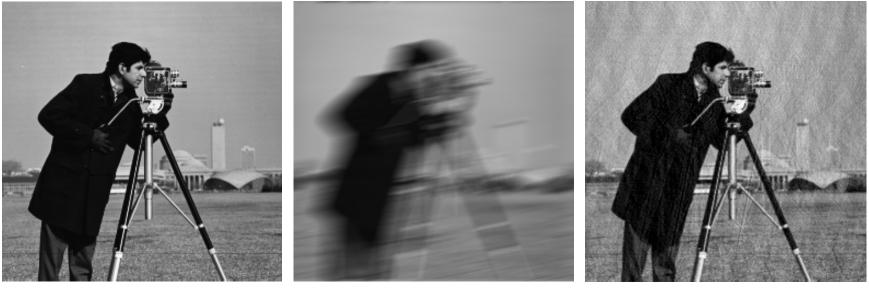






Microarray images 0000 • III III III . . 0 0 10 0 0 000

• Image Restoration

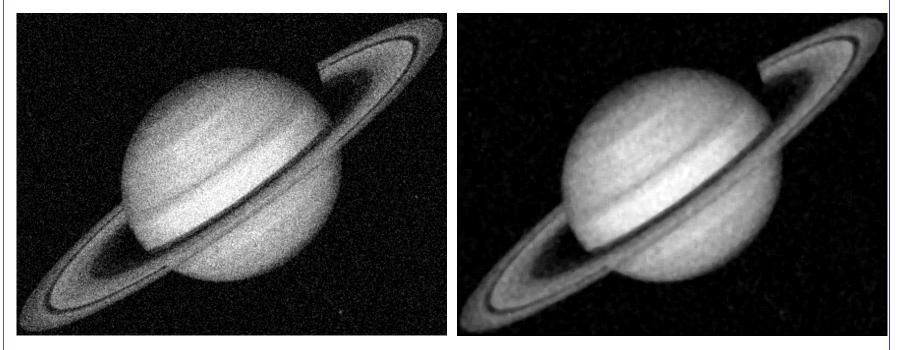


Original image

Blurred

Restored by Wiener filter

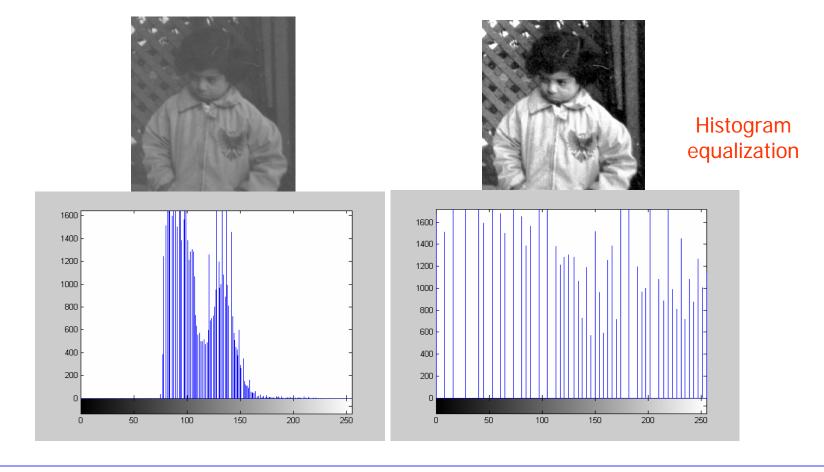
Noise Removal



Noisy image

Denoised by Median filter

• Image Enhancement



Artifact Reduction in Digital Cameras ۲



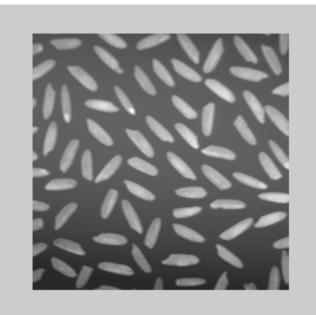
Original scene

Captured by a digital camera Processed to reduce artifacts

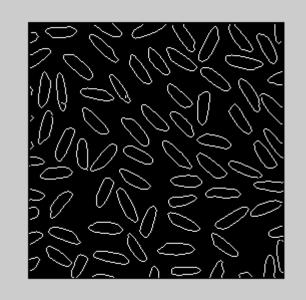
Image Compression



Object Segmentation



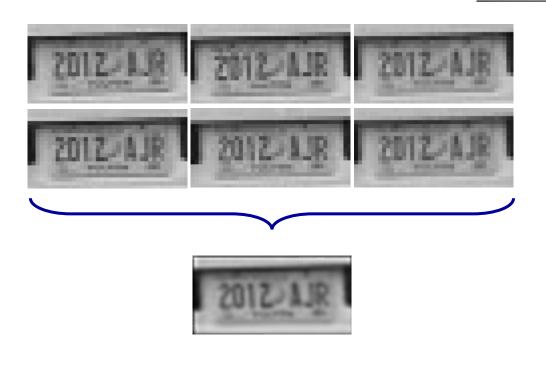
"Rice" image



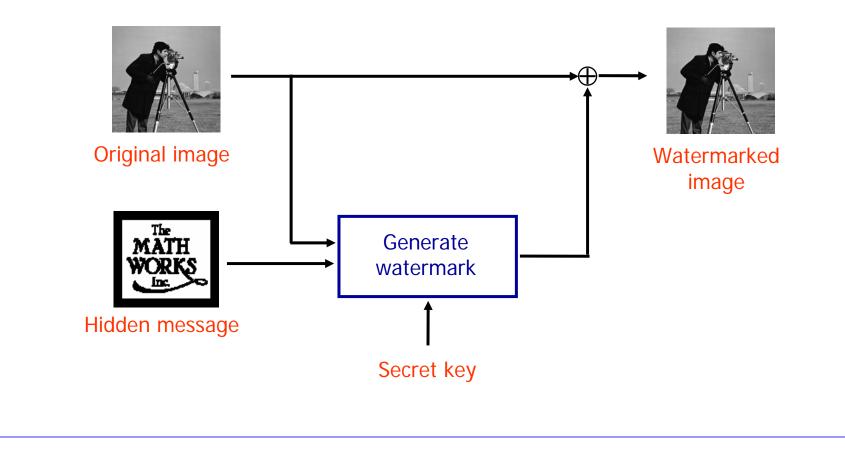
Edges detected using Canny filter

Resolution Enhancement

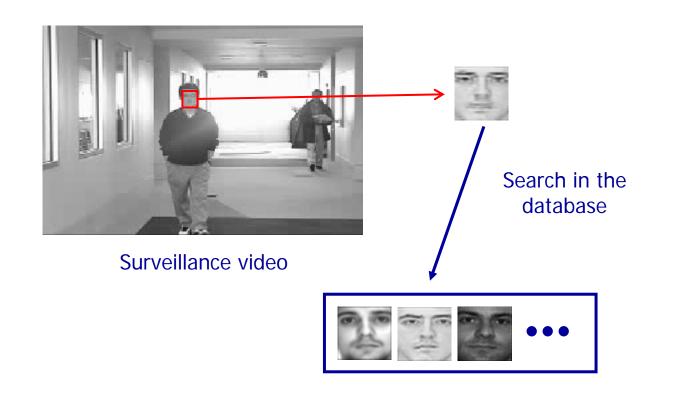




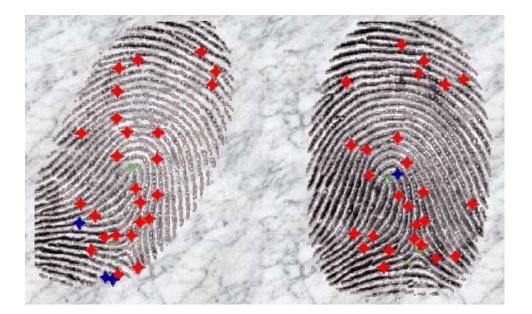
• Watermarking



• Face Recognition

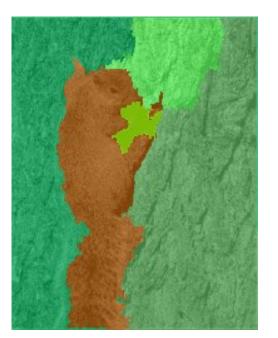


• Fingerprint Matching



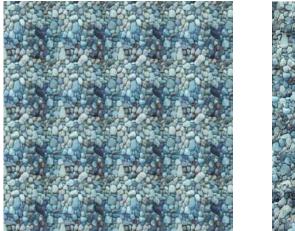
Segmentation





• Texture Analysis and Synthesis





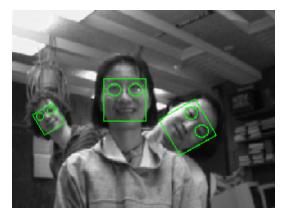
Pattern repeated

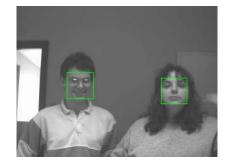


Photo

Computer generated

• Face detection and tracking



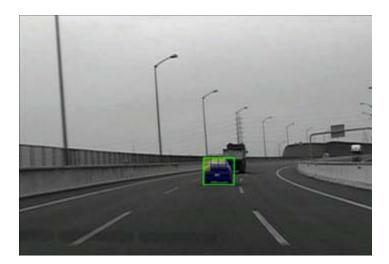


http://vasc.ri.cmu.edu/NNFaceDetector/

• Face Tracking

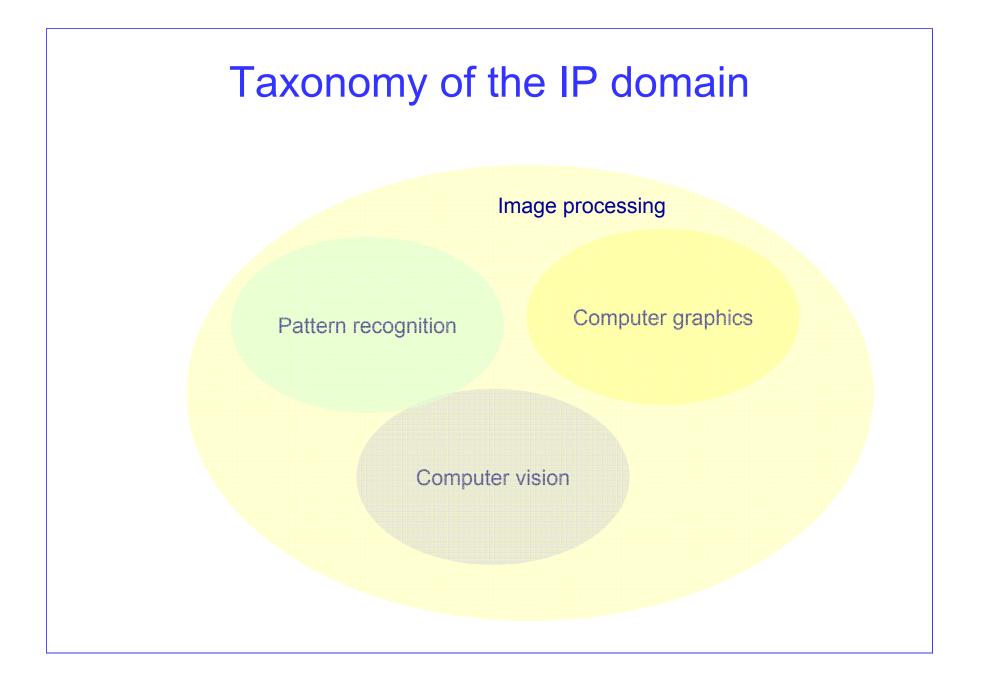


• Object Tracking



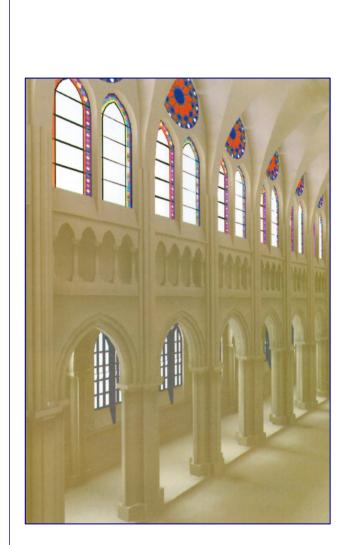
• Visually Guided Surgery





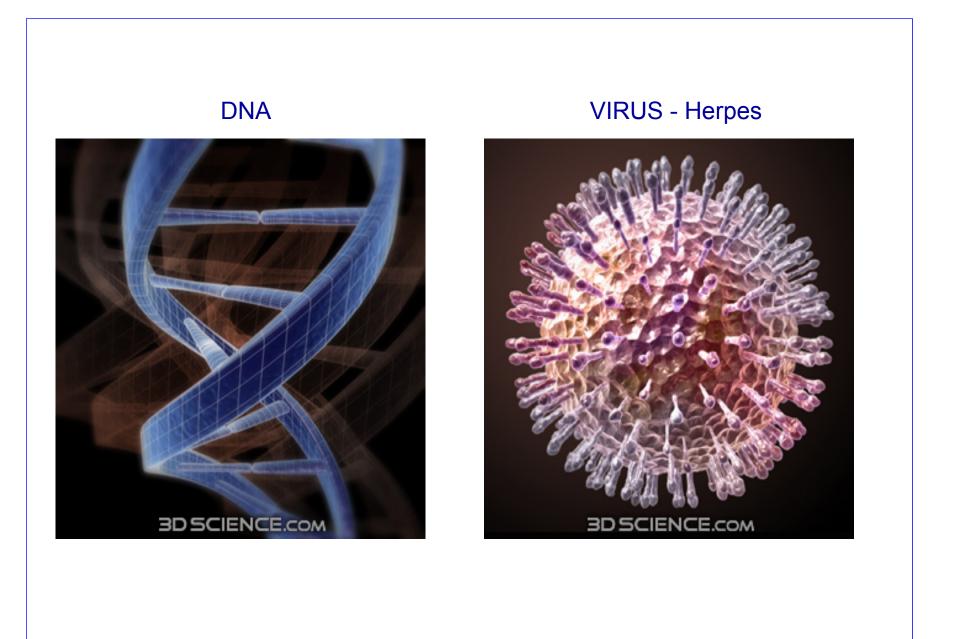
Computer graphics

- Algorithms allowing to generate *artificial* images and scenes
- Model-based
 - Scenes are created based on models
- Visualization often rests on 2D projections
- Hot topic: generate perceptually credible scenes
 - Image-based modeling & rendering

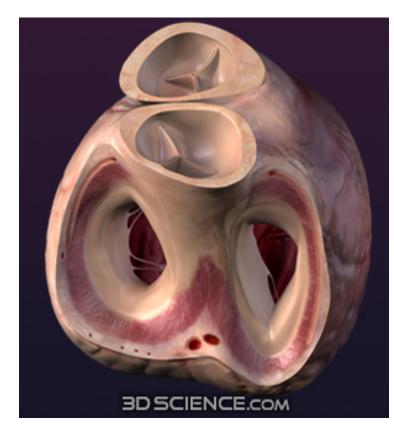




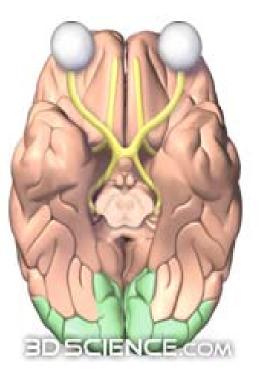




HEARTH (interior)



BRAIN (visual cortex)



Computer vision

- Methods for estimating the geometrical and dynamical properties of the imaged scene based on the acquired images
 - Scene description based on image features
- Complementary to computer graphics
 - Get information about the 3D real world based on its 2D projections in order to automatically perform predefined tasks

Pattern Recognition

- Image interpretation
- Identification of basic and/or complex structures
 - implies pre-processing to reduce the intrinsic redundancy in the input data
 - knowledge-based
 - use of a-priori knowledge on the real world
 - stochastic inference to compensate for partial data
- Key to clustering and classification
- Applications
 - medical image analysis
 - microarray analysis
 - multimedia applications

Pattern Recognition

- Clustering
 - data analysis aiming at constructing and characterizing clusters (sets)
 - analisi dei dati per trovare inter-relazioni e discriminarli in gruppi (senza conoscenza a priori)
- Feature extraction and selection
 - reduction of data dimensionality
- Classification
 - Structural (based on a predefined "syntax"):
 - each pattern is considered as a set of primitives
 - clustering in the form of parsing
 - Stochastic
 - Based on statistics (region-based descriptors)

Applications

- Efficiently manage different types of images
 - Satellite, radar, optical..
 - Medical (MRI, CT, US), microarrays
- Image representation and modeling
- Quality enhancement
 - Image restoration, denoising
- Image analysis
 - Feature extraction and exploitation
- Image reconstruction from projections
 - scene reconstruction, CT, MRI
- Compression and coding

Typical issues

Multimedia

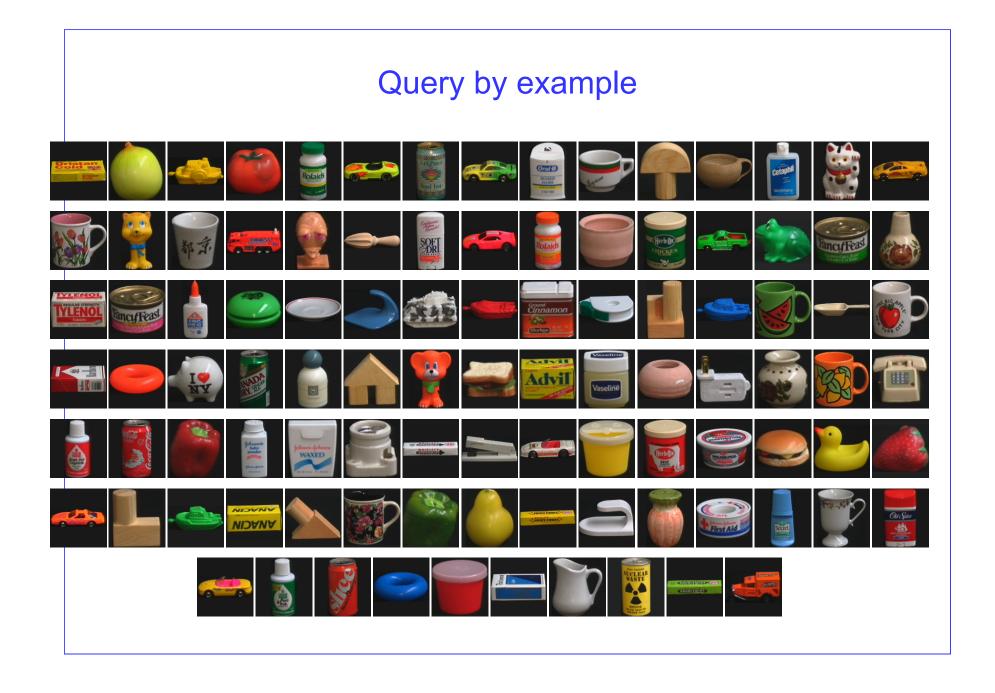
- Image resampling and interpolation
- Visualization and rendering
- Multispectral imaging
 - Satellite, color
- Motion detection, tracking
- Automatic quality assessment
- Data mining
 - query by example

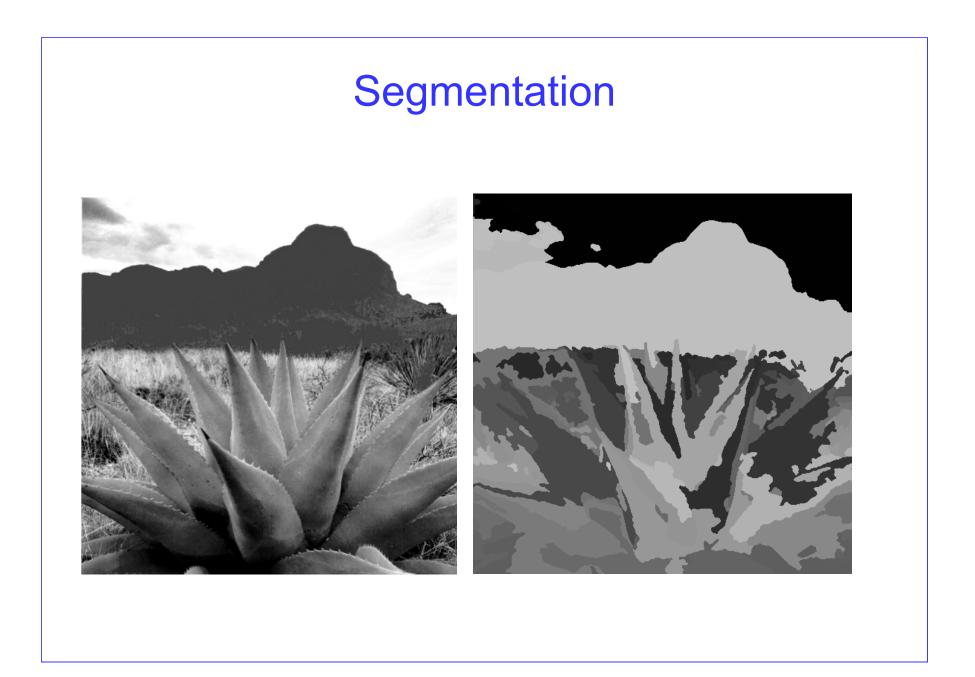
Medical imaging

- Image analysis
 - optical devices, MRI, CT, PET, US (2D to 4D)
- Image modeling
 - Analysis of hearth motion, models of tumor growth, computer assisted surgery
- Telemedicine
 - remote diagnosis, distributed systems, medical databases

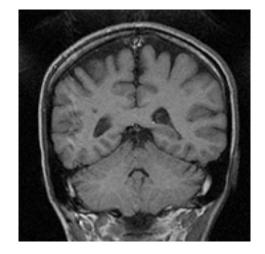
Other applications

- Quality control
- Reverse engineering
- Surveillance (monitoring and detection of potentially dangerous situations)
- Social computing (face and gesture recognition for biometrics and behavioural analysis)
- Robotics (machine vision)
- Virtual reality
- Telepresence

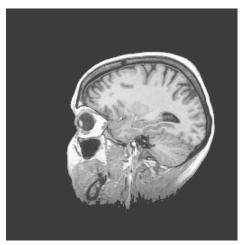




Medical Image Analysis

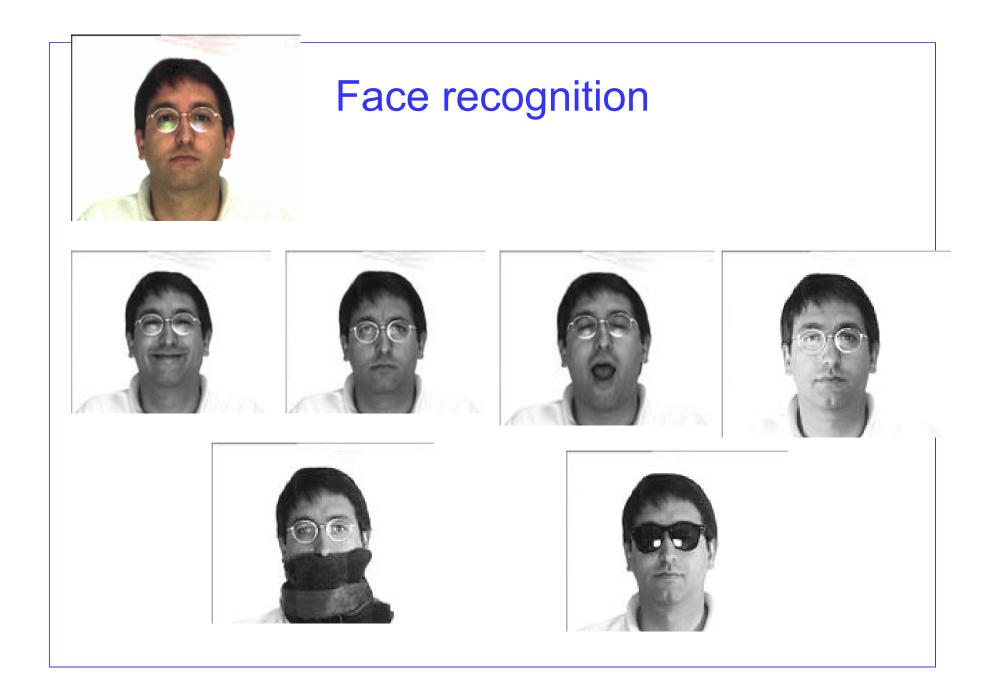




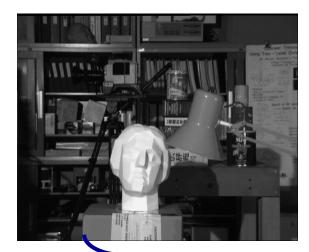


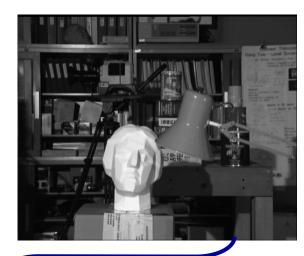
Sequence analysis





Stereo pairs





Coppia di immagini stereo (immagini ottiche)

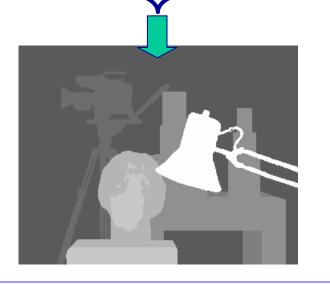
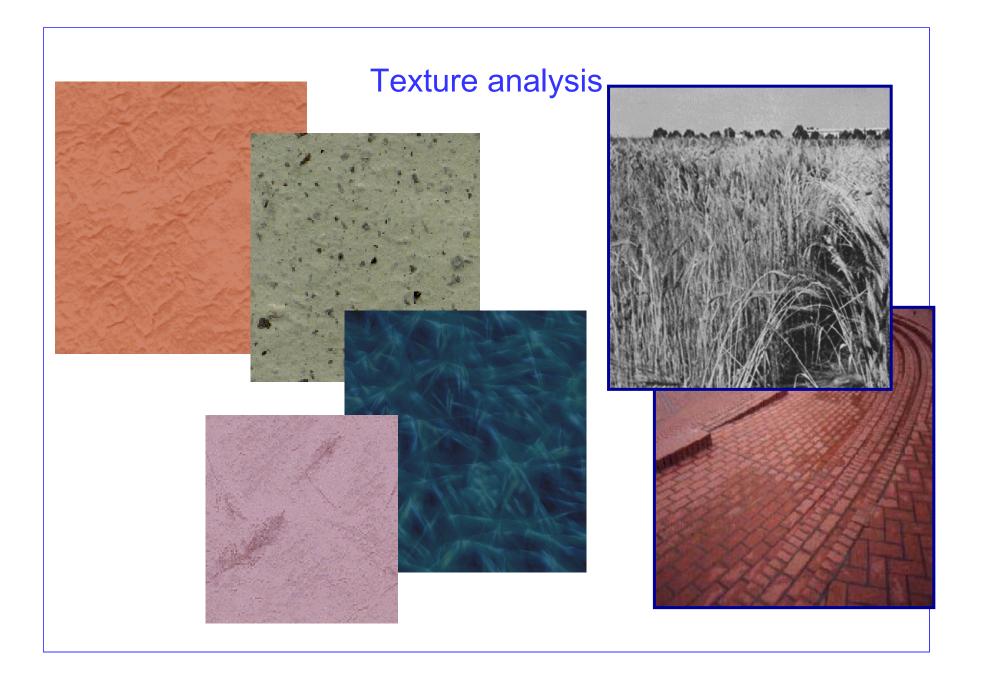


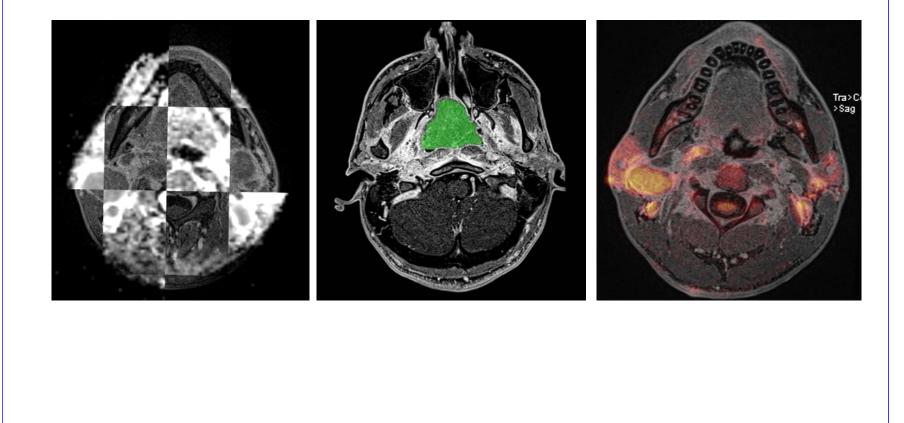
Immagine di disparità: i punti più chiari rappresentano oggetti più vicini all'osservatore





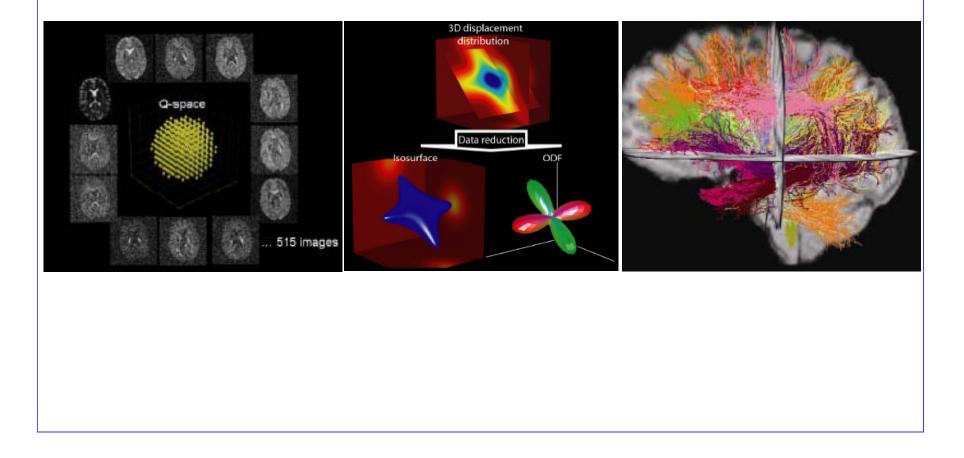
MI applications

• Tumor identitication and staging

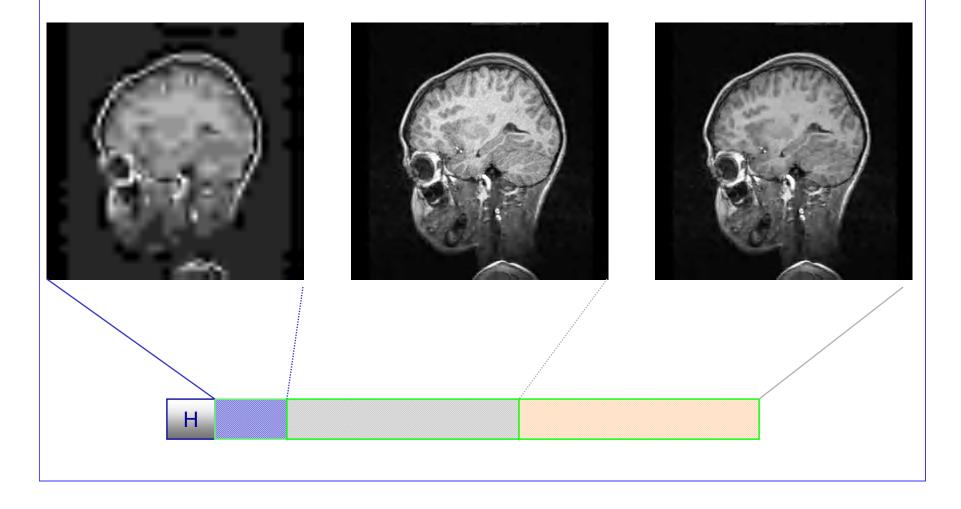


MI applications

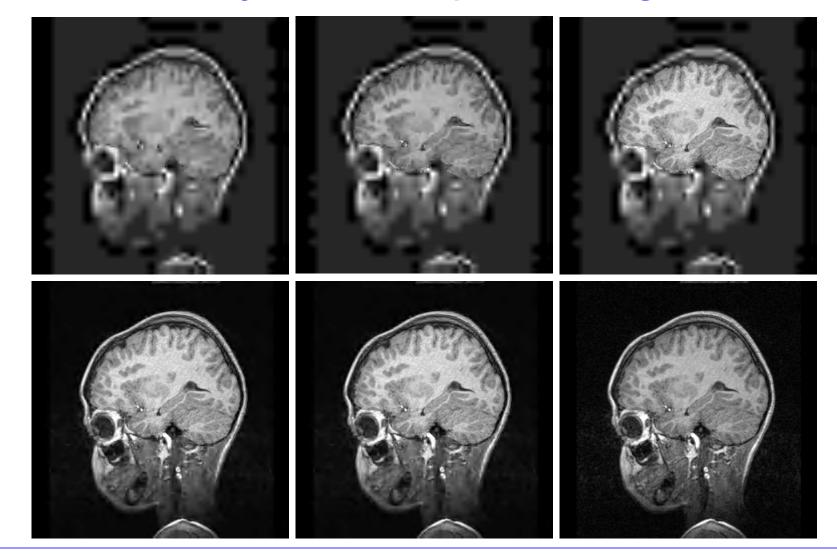
• Exploring brain anatomy by diffusion weighted MRI



Compression and coding



Object-based processing



Mosaicing



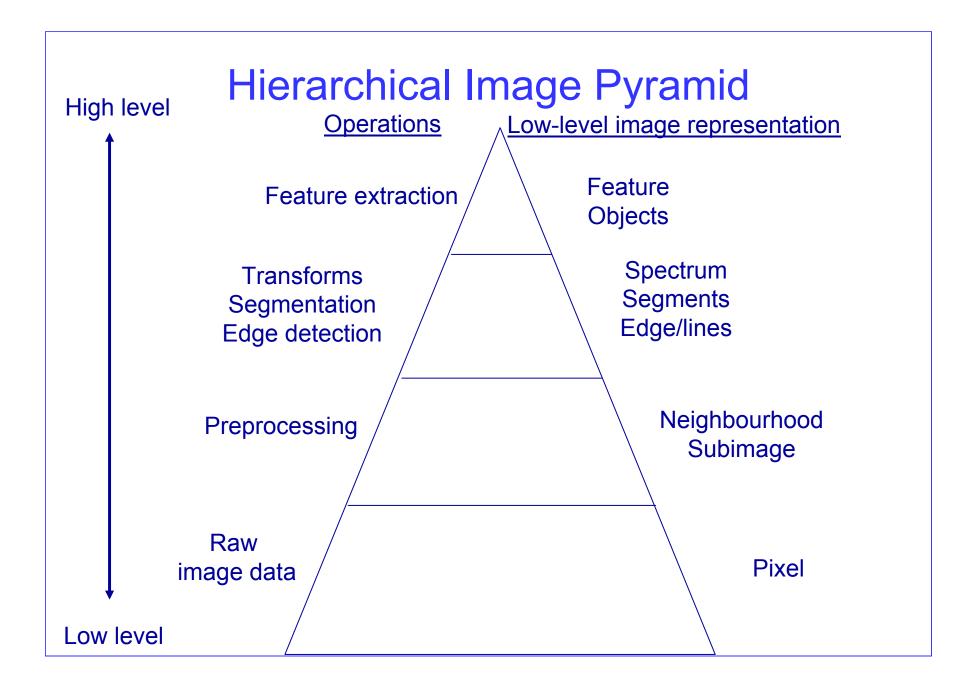
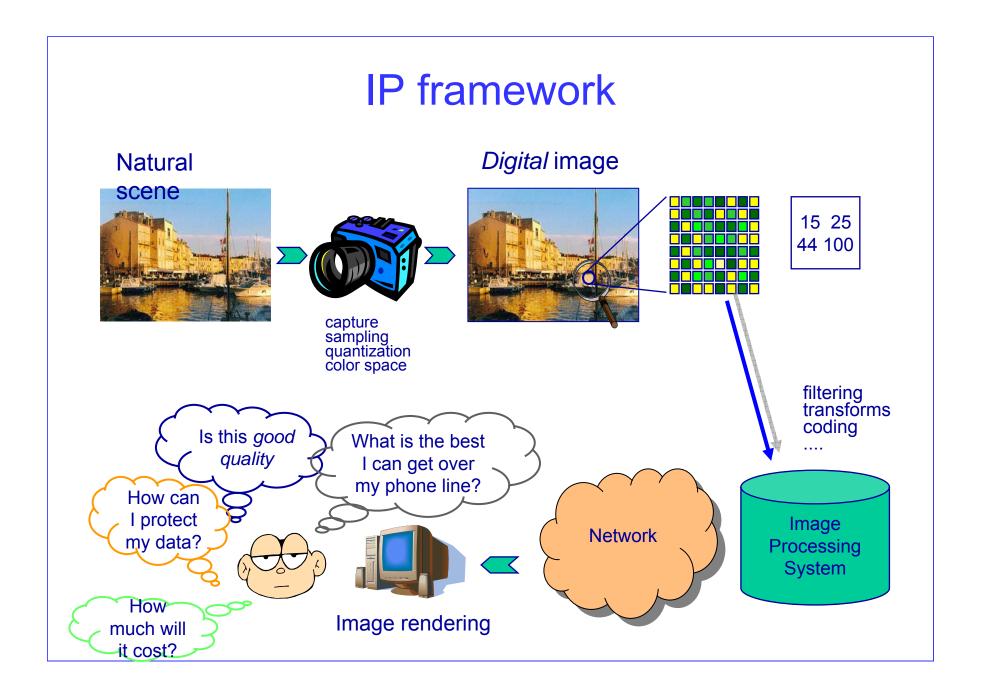
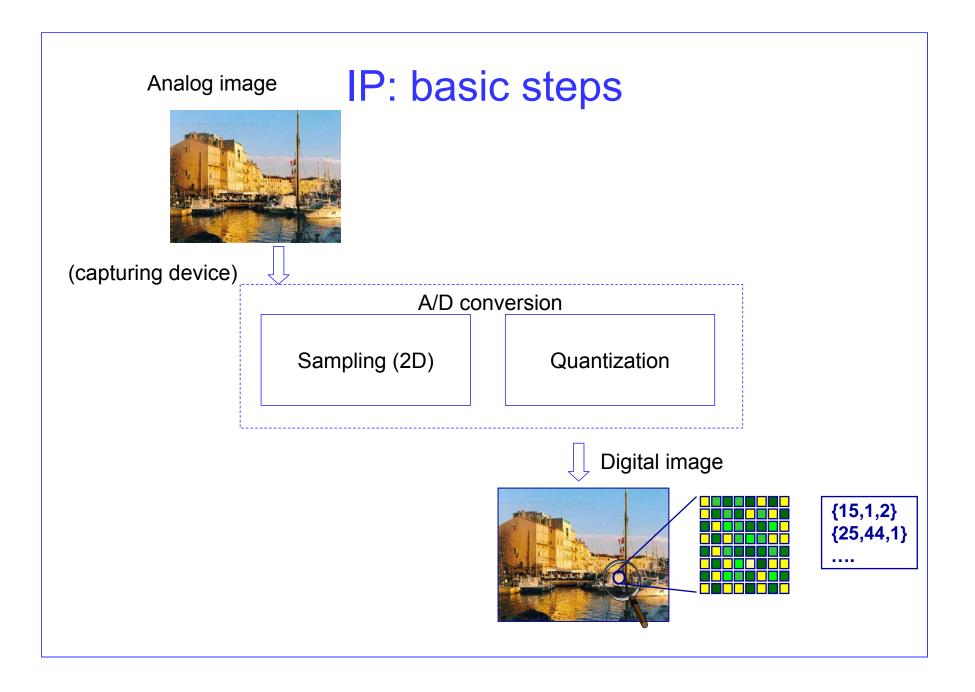


Image formation and fundamentals





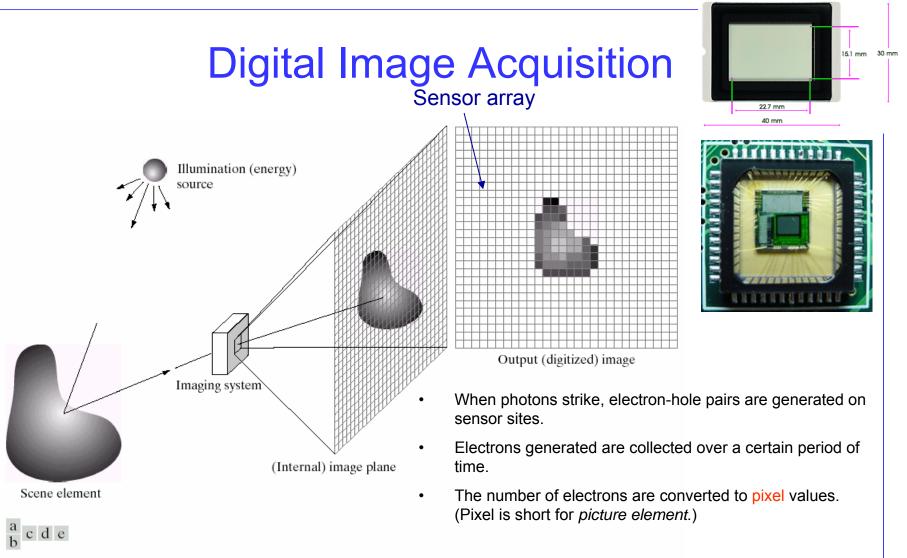
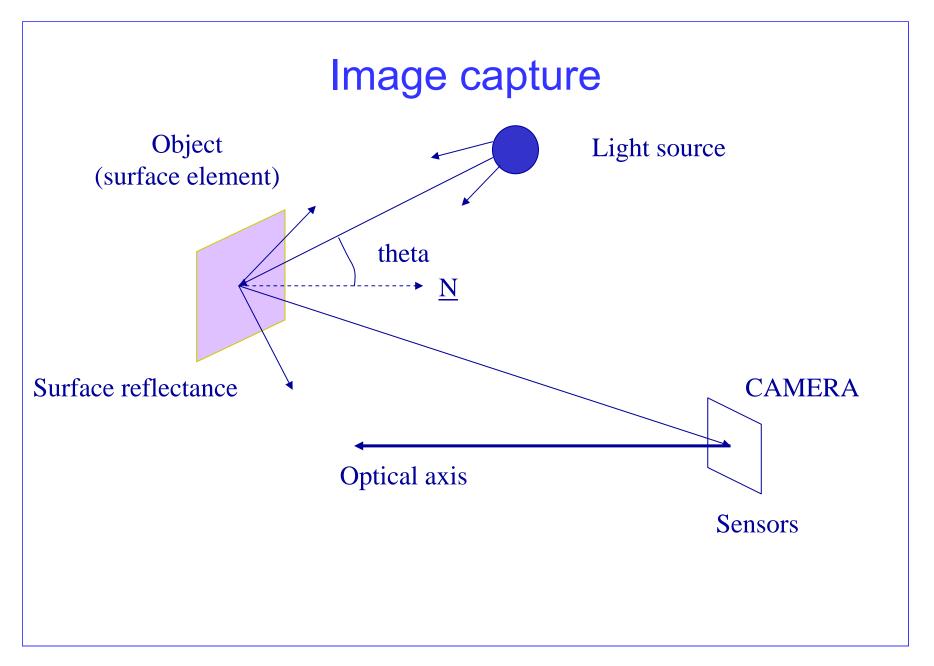


FIGURE 2.15 An example of the digital image acquisition process. (a) Energy ("illumination") source. (b) An element of a scene. (c) Imaging system. (d) Projection of the scene onto the image plane. (e) Digitized image.

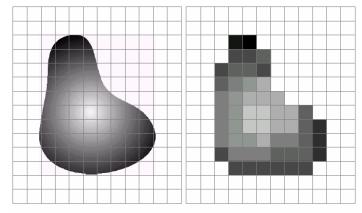
VM1



Slide	52				

- VM1 - radianza: energia che viene emessa dall'elemento di superficie
 - irradianza: energia che colpisce la camera e dipende da lo spettro della luce, la riflettanza della superficie (che cambia lo spettro) e la sensibilità spettrale del sensore swan; 14/01/2004

Digital Image Acquisition

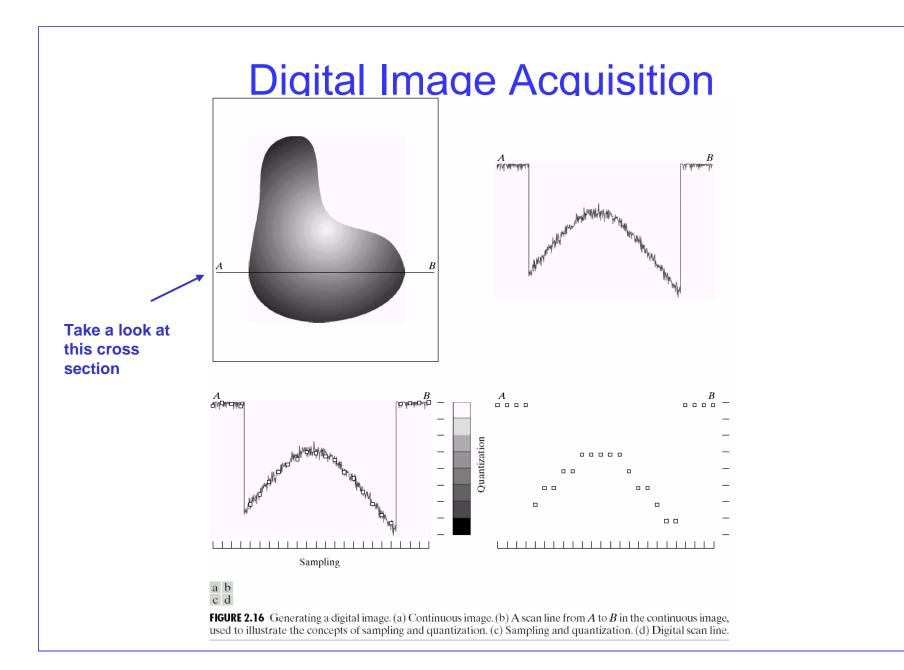


a b

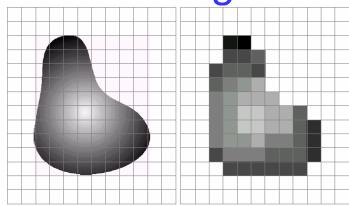
FIGURE 2.17 (a) Continuos image projected onto a sensor array. (b) Result of image sampling and quantization.

Two types of discretization:

- 1. There are finite number of pixels. (sampling \rightarrow Spatial resolution)
- The amplitude of pixel is 2. represented by a finite number of bits. (Quantization \rightarrow Gray-scale resolution)

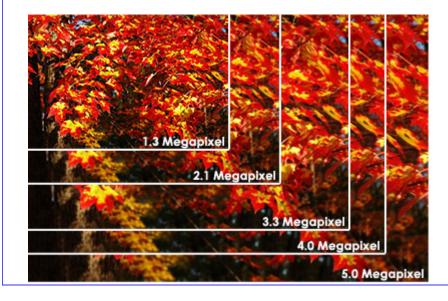


Digital Image Acquisition



a b

 $FIGURE \ 2.17$ (a) Continuos image projected onto a sensor array. (b) Result of image sampling and quantization.



- **256x256** Found on very cheap cameras, this resolution is so low that the picture quality is almost always unacceptable. This is 65,000 total pixels.
- 640x480 This is the low end on most "real" cameras. This resolution is ideal for e-mailing pictures or posting pictures on a Web site.
- **1216x912** This is a "megapixel" image size -- 1,109,000 total pixels -- good for printing pictures.
- **1600x1200** With almost 2 million total pixels, this is "high resolution." You can print a 4x5 inch print taken at this resolution with the same quality that you would get from a photo lab.
- 2240x1680 Found on 4 megapixel cameras -- the current standard -- this allows even larger printed photos, with good quality for prints up to 16x20 inches.
- 4064x2704 A top-of-the-line digital camera with 11.1 megapixels takes pictures at this resolution. At this setting, you can create 13.5x9 inch prints with no loss of picture quality.

Basics: greylevel images

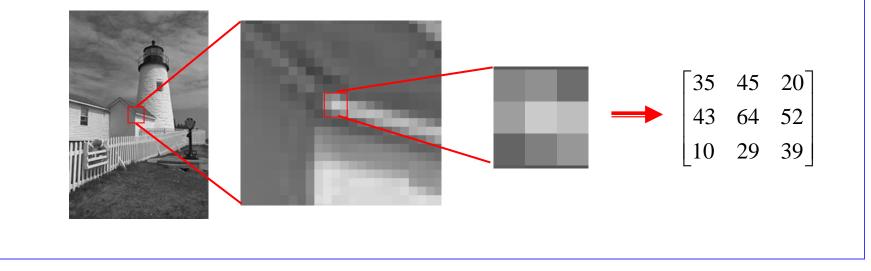
	100	100	200	90
	50	0	50	200
\/	100	200	100	50
	100	0	200	100

Images : Matrices of numbers Image processing : Operations among numbers bit depth : number of bits/pixel *N* bit/pixel : 2^{N-1} shades of gray (typically N=8)

Matrix Representation of Images

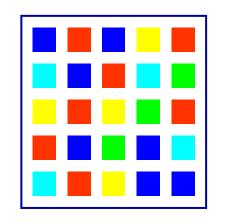
• A digital image can be written as a matrix

$$x[n_1, n_2] = \begin{bmatrix} x[0,0] & x[0,1] & \cdots & x[0,N-1] \\ x[1,0] & x[1,1] & \cdots & x[1,N-1] \\ \vdots & \vdots & \ddots & \vdots \\ x[M-1,0] & \cdots & \cdots & x[M-1,N-1] \end{bmatrix}_{MxN}$$



Digital images acquisition

- Analog camera+A/D converter
- Digital cameras
 - CCDs (Charge Coupled Devices)
 - CMOS technology
- In both cases: optics
 - lenses, diaphragms

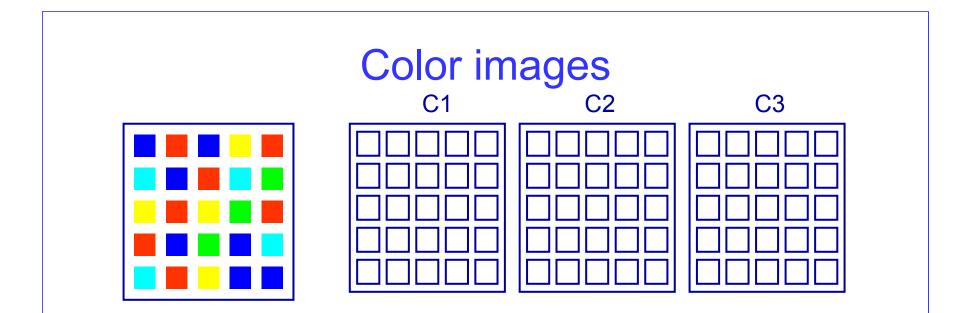


Matrices of photo sensors collecting photons of given wavelength



Features of the capture devices:

- Size and number of photo sites
- Noise
- Transfer function of the optical filter



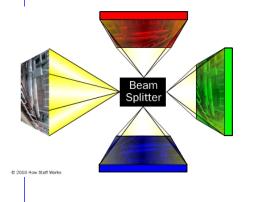
- Each colored pixel corresponds to a *vector* of three values {C1,C2,C3}
- The characteristics of the components depend on the chosen *colorspace* (RGB, YUV, CIELab,..)

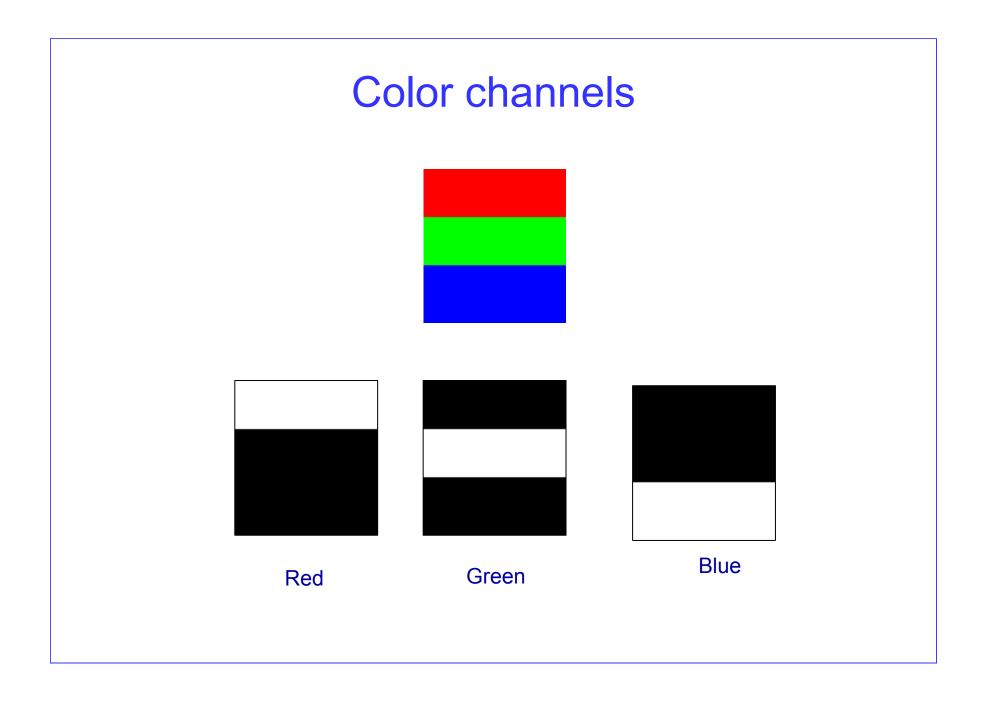
Digital Color Images

 $\cdot x_R[n_1, n_2]$ $x_G[n_1, n_2]$ $x_B[n_1, n_2]$











Red

Green

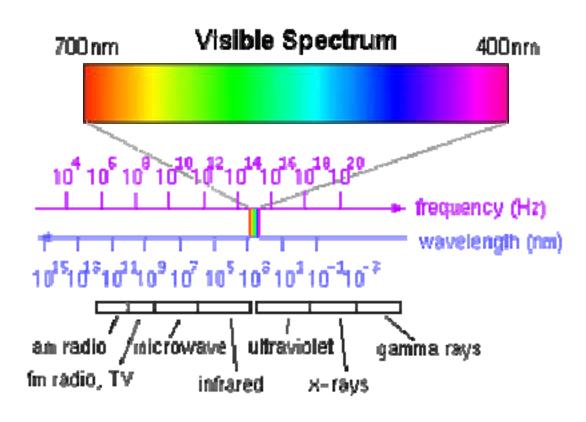
Blue





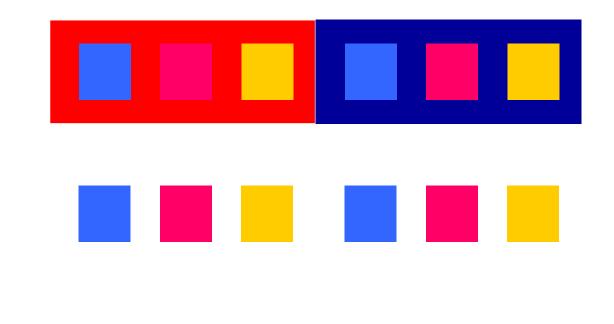


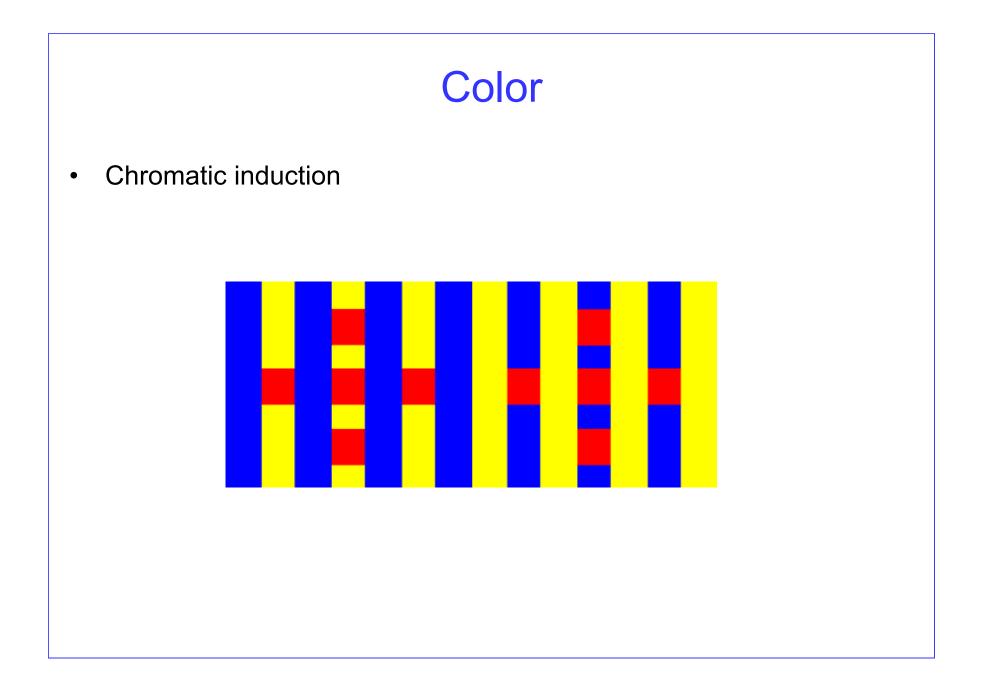
The physical perspective



The perceptual perspective

Simultaneous contrast





Color

- Human vision •
 - Color encoding (receptor level)
 - Color perception (post-receptoral level)
 - Color semantics (cognitive level)

MODELS

Color categorization and naming (understanding colors)

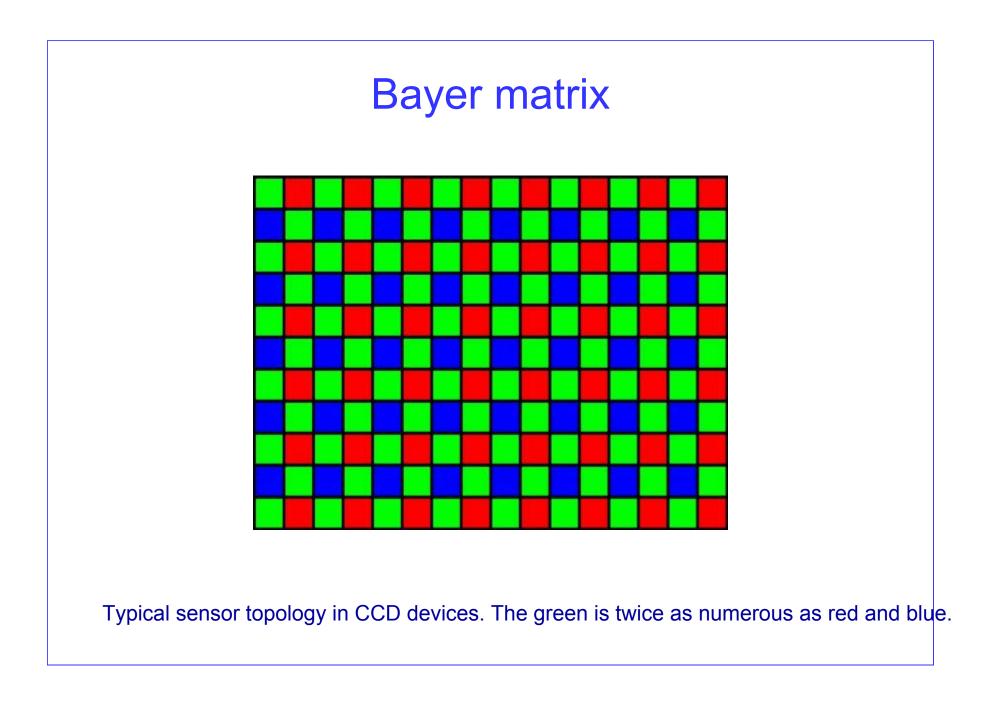
Colorimetry (Measuring colors)

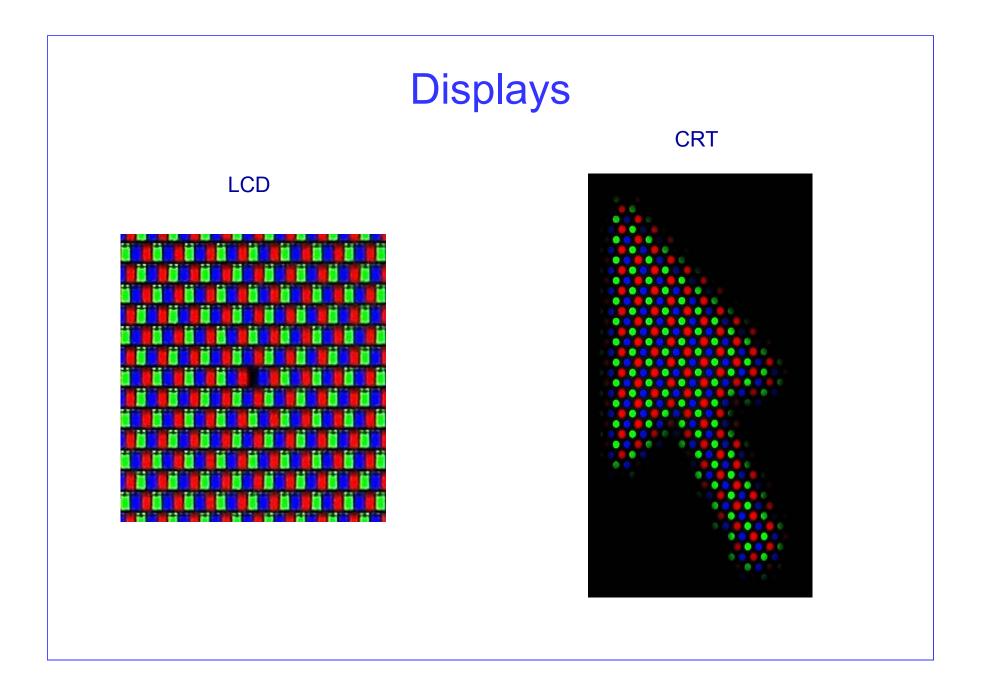
Colorimetry •

- Spectral properties of radiation
- Physical properties of materials

Color vision

(Seeing colors)





Color imaging

- Color reproduction
 - Printing, rendering
- Digital photography
 - High dynamic range images
 - Mosaicking
 - Compensation for differences in illuminant (CAT: chromatic adaptation transforms)
- Post-processing
 - Image enhancement
- Coding
 - Quantization based on color CFSs (contrast sensitivity function)
 - Downsampling of chromatic channels with respect to luminance

Some definitions

- Digital images
 - Sampling+quantization
- Sampling
 - Determines the graylevel value of each pixel
 - Pixel = picture element
- Quantization
 - Reduces the resolution in the graylevel value to that set by the machine precision
- Images are stored as matrices of unsigned chars

Resolution

- Sensor resolution (CCD): Dots Per Inch (DPI)
 - Number of individual dots that can be placed within the span of one linear inch (2.54 cm)
- Image resolution
 - Pixel resolution: NxM
 - Spatial resolution: Pixels Per Inch (PPI)
 - Spectral resolution: bandwidth of each spectral component of the image
 - Color images: 3 components (R,G,B channels)
 - Multispectral images: many components (ex. SAR images)
 - Radiometric resolution: Bits Per Pixel (bpp)
 - Greylevel images: 8, 12, 16 bpp
 - Color images: 24bpp (8 bpp/channel)
 - Temporal resolution: for movies, number of frames/sec
 - Typically 25 Hz (=25 frames/sec)

VM2

Slide 71

VM2 da book Shapiro swan; 10/04/2003

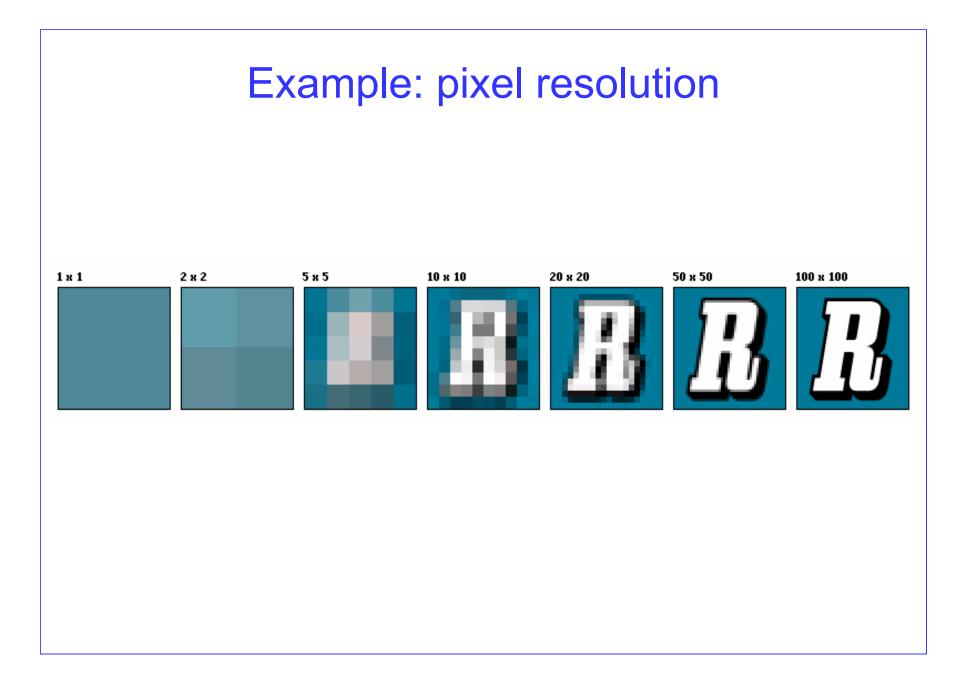
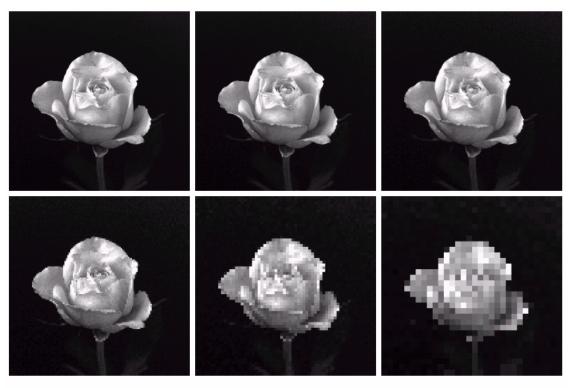


Image Resolution

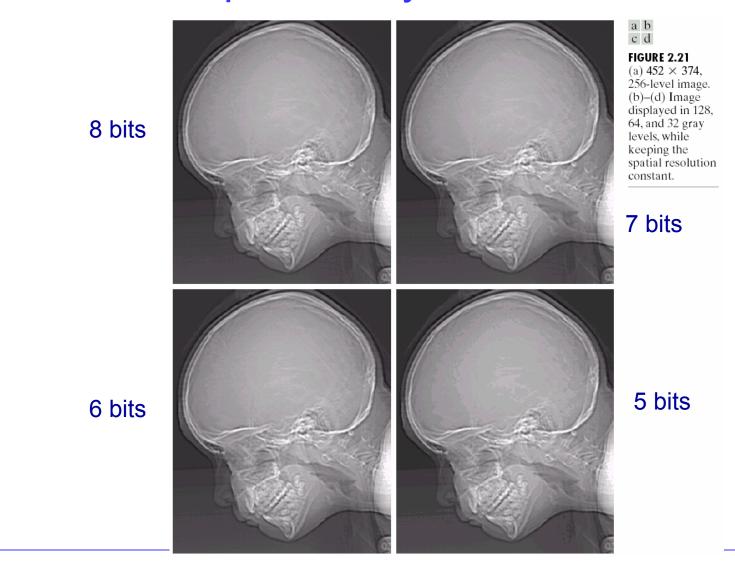
Don't confuse image size and resolution.



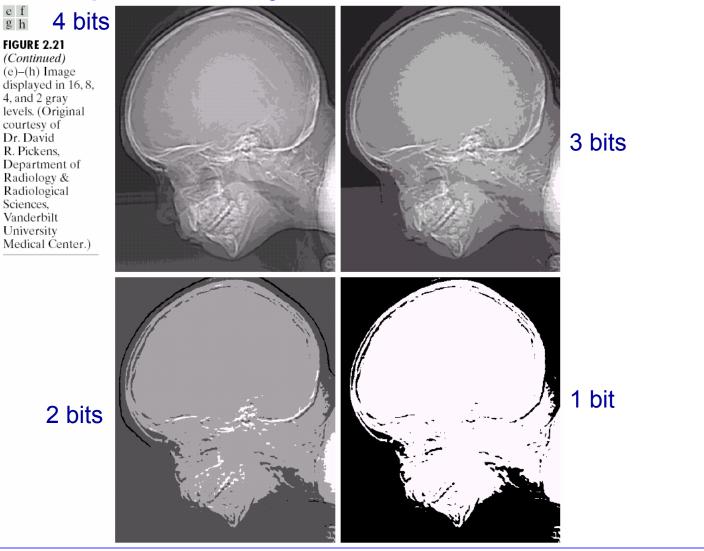
abc def

FIGURE 2.20 (a) 1024×1024 , 8-bit image. (b) 512×512 image resampled into 1024×1024 pixels by row and column duplication. (c) through (f) 256×256 , 128×128 , 64×64 , and 32×32 images resampled into 1024×1024 pixels.

Bit Depth – Grayscale Resolution



Bit Depth – Grayscale Resolution



File format

- Many image formats (about 44)
- BMP, lossless
- TIFF, lossless/lossy
- GIF (Graphics Interchange Format)
 - Lossless, 256 colors, copyright protected
- JPEG (Joint Photographic Expert Group)
 - Lossless and lossy compression
 - 8 bits per color (red, green, blue) for a 24-bit total
- PNG (Portable Network Graphics)
 - Freewere
 - supports truecolor (16 million colours)