

Second partial test in Optimization

Verona, 2nd February 2015

Solve obligatorily Exercise 3 and **one between** Exercises 1 and 2.

Exercise 1. For $i = 1, 2, 3$, consider the following problem: minimize the functional

$$J(x(\cdot)) := \int_0^1 (4t^2 x'(t) + 5x'(t)^2 + x(t)^2 x'(t) + 6x(t)^2) dt, \quad x(\cdot) \in \mathcal{C}_i,$$

where

$$\begin{aligned} \mathcal{C}_1 &:= C^2(]0, 1[) \cap C^0([0, 1]), \\ \mathcal{C}_2 &:= \{x(\cdot) \in \mathcal{C}_1 : x(0) = 0, x(1) = 1\}, \\ \mathcal{C}_3 &:= \left\{ x(\cdot) \in \mathcal{C}_2 : \int_0^1 x^2(t) dt = 1 \right\}. \end{aligned}$$

In each case establish whether the infimum is attained or not, and for \mathcal{C}_1 and \mathcal{C}_2 in the positive case find explicitly the point of minimum (not required for \mathcal{C}_3).

Exercise 2. Consider the following control system in \mathbb{R}^2 :

$$\begin{cases} \dot{x}_1(t) = 3x_1(t) - x_2(t); \\ \dot{x}_2(t) = u(t) + 2x_1(t) - x_2(t). \end{cases}$$

where $u(\cdot) \in \mathcal{U} := \{u : \mathbb{R} \rightarrow U := [-1, 1] \text{ measurable}\}$.

Consider the problem $\max_{u \in \mathcal{U}} x_1(T)$.

- (1) Write the adjoint system with terminal conditions and solve it explicitly.
- (2) Apply Pontryagin's Maximum Principle to isolate the candidates and establish if they are optimal.

Exercise 3.

- (1) Write down the statement of Pontryagin's Maximum Principle.
- (2) Formulate mathematically Dido's problem, and solve it analytically.
- (3) Write down the statement of the parametric contraction's principle.
- (4) Let Ω be an open bounded nonempty subset of \mathbb{R}^d with C^∞ boundary. Let $\nu(x)$ be the external unit normal to Ω at $x \in \partial\Omega$. Consider the control system $\dot{x}(t) = f(x(t), u(t))$ where $f \in C^{1,1}(\mathbb{R}^d \times \mathbb{R}^m)$ is bounded, an measurable admissible controls $u : [0, +\infty[\rightarrow U$, where U is a compact subset of \mathbb{R}^m . Prove that if there exists $\mu > 0$ such that $f(x, u) \cdot \nu(x) < -\mu$ for every $x \in \partial\Omega$, then for every $x_0 \in \Omega$ there exists trajectories starting from x_0 and remaining in Ω per ogni $t > 0$.
- (5) State and prove a result concerning the sum rule for the subdifferential of convex analysis.

Written test in Optimization

Verona, 2nd February 2015

Exercise 1. Let Ω be an open bounded subset of \mathbb{R}^2 . Consider the problem:

$$\inf_{u \in H_0^1(\Omega)} \int_{\Omega} \left(|\nabla u(x_1, x_2)|^2 + \partial_{x_2} u(x_1, x_2) \partial_{x_1} u(x_1, x_2) + (\cos(x_2) u(x_1, x_2) - 2)^2 \right) dx_1 dx_2.$$

- (1) Prove that the problem admits a unique solution.
- (2) Formulate the problem as $\mathcal{F}(u) = F(u) + G \circ \Lambda(u)$, where $F : X \rightarrow]-\infty, +\infty]$, $G : Y \rightarrow]-\infty, +\infty]$ and $\Lambda : X \rightarrow Y$, carefully precisising the function spaces X, Y and discussing the regularity of F, G, Λ .
- (3) Write the dual problem and the extremality relations. Establish if the dual problem admits a unique solution.
- (4) Use the above results to write a partial differential equation whose solution is the minimum.

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where $u(\cdot) \in \mathcal{U} := \{u : \mathbb{R} \rightarrow U := [-1, 1] \text{ measurable}\}$.

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